AlQT: Lecture 1 notes

Introduction

One of the most important quencing modes is the M/M/1 queue

(A+L)Pn = APn+ +LPn+1 Balance equations

Cut equation Ap = 4 pm+1 , n>0



$$\begin{pmatrix} J_1 \end{pmatrix} \int_{2}^{2}$$

simple Random walks in the guodrant with no transitions to the N, NE, E.

In Lecture I, we will delve into the class of simple Random walks in the quadrant with no transitions to the N, NE, E.

M/M/1 in a Random environment

The model

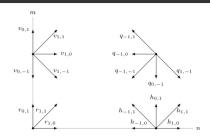


Figure 1: Transition rate diagram of the homogeneous simple random walk on the state space (n, m) with no transitions in the interior to the North, North-East, and East. Only the transitions at a few selected states are depicted as an indication.

The conditions

Conditions 1.1. Step size: Only transitions to neighboring states are allowed;

Forbidden steps: No transitions from interior states to the North, North-East, and East are allowed;

Homogeneity: In the interior, all transitions in the same direction occur according to the same rate.

Furthermore, in order to avoid the random walk exhibiting a trivial behavior, we consider the following assumptions

The stability

$$\begin{split} \boldsymbol{M} &= (M_x, M_y) = \Big(\sum_{n', m' \geq 0} (n'-n) p_{(n,m),(n',m')}, \sum_{n', m' \geq 0} (m'-m) p_{(n,m),(n',m')} \Big), \ n, m > 0; \\ \boldsymbol{M}' &= (M_x', M_y') = \Big(\sum_{n', m' \geq 0} (n'-n) p_{(n,0),(n',m')}, \sum_{n', m' \geq 0} (m'-m) p_{(n,0),(n',m')} \Big), \ n > 0; \\ \boldsymbol{M}'' &= (M_x'', M_y'') = \Big(\sum_{n', m' \geq 0} (n'-n) p_{(0,m),(n',m')}, \sum_{n', m' \geq 0} (m'-m) p_{(0,m),(n',m')} \Big), \ m > 0. \end{split}$$

Then, when, $M \neq 0$, the homogeneous nearest neighbor random walk is ergodic if and only if, one of the following three conditions holds:

i)
$$M_x < 0$$
, $M_y < 0$, $M_x M'_y - M_y M'_x < 0$, and $M_y M''_x - M_x M''_y < 0$;

ii)
$$M_x < 0$$
, $M_y \ge 0$, and $M_y M_x'' - M_x M_y'' < 0$;

iii)
$$M_x \ge 0$$
, $M_y < 0$, and $M_x M_y' - M_y M_x' < 0$.

The main

Theorem 1.1. [1, Theorem 2.33] Under the Conditions for meromorphicity 1.1 and Assumptions 1.1, and given the stability condition, there exists an $N \in \mathbb{Z}_+$, such that for n+m>N, the equilibrium distribution $\pi_{n,m}$ can be written

$$\pi_{n,m} = \sum_{(\alpha_0, \beta_0)} c(\alpha_0, \beta_0) x_{n,m}(\alpha_0, \beta_0),$$
(1)

where (α_0, β_0) runs through the set of at most four feasible pairs and $c(\alpha_0, \beta_0)$ is an appropriately chosen coefficient and

$$x_{n,m}(\alpha_0, \beta_0) = c_0 \alpha_0^n \beta_0^m + \sum_{k=1}^{\infty} c_k \alpha_k^n (\beta_{k-1}^m + f_k \beta_k^m), n, m > 0,$$
 (2)

$$x_{n,0}(\alpha_0, \beta_0) = \sum_{k=0}^{\infty} e_k \alpha_k^n, \quad n > 0,$$
 (3)

$$x_{0,m}(\alpha_0, \beta_0) = \sum_{k=0}^{\infty} d_k \beta_k^m, m > 0.$$
 (4)

The equilibrium distribution of the states close to the origin, e.g. $\pi_{0,0}$, can be obtained as a function of (2)-(4) by solving the corresponding system of balance equations.

The process

Step 1: $\pi_{n,m} = \alpha^n \beta^m$, m, n > 0, is a solution to the balance equations in the interior if and only if α and β satisfy the following kernel equation

$$\alpha\beta(q_{-1,1} + q_{1,-1} + q_{0,-1} + q_{-1,-1} + q_{-1,0}) =$$

$$\alpha^2q_{-1,1} + \beta^2q_{1,-1} + \alpha\beta^2q_{0,-1} + \alpha^2\beta^2q_{-1,-1} + \alpha^2\beta q_{-1,0}.$$
(5)

Step 2: Consider a product-form $c_0\alpha_0^n\beta_0^m$ that satisfies the kernel equation (5) and also satisfies the balance equations of the horizontal boundary. Without loss of generality, we can assume that $c_0 = 1$. If the product-form $c_0\alpha_0^n\beta_0^m$ also satisfies the balance equations of the vertical boundary then this constitutes the solution of the balance equations up to a multiplicative constant that can be obtained using the normalizing equation. Otherwise, consider a linear combination of two product-forms, say $c_0\alpha_0^n\beta_0^m + c_1\alpha^n\beta^m$, m, n > 0, such that this combination satisfies now the balance equations of the vertical boundary. For this to happen it must be that $\beta = \beta_0$ and then $\alpha = \alpha_1$ is obtained as the solution of the kernel equation (5) for $\beta = \beta_0$.

Step 3: Finally, as long as our expression of linear combinations of product-forms violates one of the two balance equations on the boundary, we continue by adding new product-form terms satisfying the kernel equation (5). This will eventually lead to Equations (2)-(4). Of course, one still needs to show that the series expression of Equations (2)-(4) converge for all $n, m \ge 0$.

This procedure leads to the statement of Theorem 1.1.

The numerical

Algorithm 1 Compensation approach algorithmic implementation

- 1: Inputs ρ , ε and precision ε' .
- 2: Set $\alpha_0 = \rho^2$, $d_0 = 1$ and $N_{\text{ca}} = 1$.
- 3: Compute β_0 from Equation (18).
- 4: Set $T_{\text{ca}} = \max\{\lceil \log(\varepsilon)/\log(\beta_0)\rceil, 3\}$.
- 5: Compute recursively α_i , β_i , for $i = 1, ..., N_{\text{ca}}$, from Equation (18).
- 6: Compute the coefficients c_i and d_i , $i = 0, 1, ..., N_{\text{ca}}$, recursively from the balance equations, starting with $d_0 = 1$, cf. Step 2.
 - 7: For all $|T_{ca}/2| < m, n \le T_{ca}$, compute $\pi_{m,n}^{(N_{ca})}$ from Equation (28).
 - 8: For all $0 \le m, n \le |T_{\rm ca}/2|$, solve the linear system of the balance equations (6)-(11) and compute $\pi_{m,n}^{N_{\rm ca}}$.
 - 9: Normalize $\pi_{m,n}^{(N_{ca})}$.
 - 10: Stop if Equation (29) is satisfied, else update $N_{\text{ca}} := N_{\text{ca}} + 1$ and go to Step 5.

Compensation approach example : the 2x2 switch

The general model

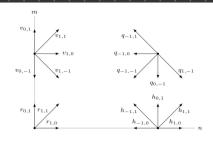
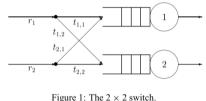


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The 2×2 switch



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transition diagram

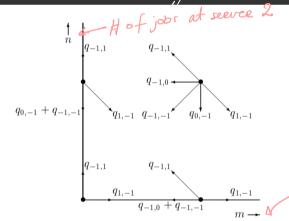


Figure 2: The one-step transition probabilities.

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$$\begin{array}{ll} q_{1,-1} = r_1 r_2 t_{1,1} t_{2,1}, & q_{0,0} = r_1 r_2 (t_{1,1} t_{2,2} + t_{1,2} t_{2,1}), \\ q_{0,-1} = r_1 (1 - r_2) t_{1,1} + r_2 (1 - r_1) t_{2,1}, & q_{-1,1} = r_1 r_2 t_{1,2} t_{2,2}, \\ q_{-1,0} = r_1 (1 - r_2) t_{1,2} + r_2 (1 - r_1) t_{2,2}, & q_{-1,-1} = (1 - r_1) (1 - r_2). \end{array}$$

Step size: Only transitions to neighboring states are allowed; Conditions 1.1.

Forbidden steps: No transitions from interior states to the North, North-East, and East are allowed;



conditions

The general stability

condition.

 $\boldsymbol{M} = (M_x, M_y) = \Big(\sum_{n', m' \geq 0} (n' - n) p_{(n,m),(n',m')}, \sum_{n', m' \geq 0} (m' - m) p_{(n,m),(n',m')} \Big), \ n, m > 0;$

 $\boldsymbol{M}' = (M'_x, M'_y) = \Big(\sum_{n', m' > 0} (n' - n) p_{(n,0),(n',m')}, \sum_{n', m' > 0} (m' - m) p_{(n,0),(n',m')} \Big), \ n > 0;$

 $\boldsymbol{M}'' = (M_x'', M_y'') = \Big(\sum_{n', m' \geq 0} (n' - n) p_{(0,m),(n',m')}, \sum_{n', m' \geq 0} (m' - m) p_{(0,m),(n',m')}\Big), \ m > 0.$

three conditions holds:

- $i) \ M_x < 0, \ M_y < 0, \ M_x M_y' M_y M_x' < 0, \ and \ M_y M_x'' M_x M_y'' < 0;$
- ii) $M_x < 0$, $M_y \ge 0$, and $M_y M_x'' M_x M_y'' < 0$;
- iii) $M_x \ge 0$, $M_y < 0$, and $M_x M'_y M_y M'_x < 0$.

$$M_{\times} = -2H$$
 $M_{\text{y}} = \lambda + 2H$

if
$$\lambda \in (1,2L)$$
 then from condition (iii) the system

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The general

Step 1: $\pi_{n,m} = \alpha^n \beta^m$, m, n > 0, is a solution to the balance equations in the interior if and only if α and β satisfy the following kernel equation

$$\alpha\beta(q_{-1,1} + q_{1,-1} + q_{0,-1} + q_{-1,-1} + q_{-1,0}) =$$

$$\alpha^2q_{-1,1} + \beta^2q_{1,-1} + \alpha\beta^2q_{0,-1} + \alpha^2\beta^2q_{-1,-1} + \alpha^2\beta q_{-1,0}.$$
(5)

Step 2: Consider a product-form $c_0\alpha_0^n\beta_0^m$ that satisfies the kernel equation (5) and also satisfies the balance equations of the horizontal boundary. Without loss of generality, we can assume that $c_0=1$. If the product-form $c_0\alpha_0^n\beta_0^m$ also satisfies the balance equations of the vertical boundary then this constitutes the solution of the balance equations up to a multiplicative constant that can be obtained using the normalizing equation. Otherwise, consider a linear combination of two product-forms, say $c_0\alpha_0^n\beta_0^m + c_1\alpha^n\beta^m$, m, n > 0, such that this combination satisfies now the balance equations of the vertical boundary. For this to happen it must be that $\beta = \beta_0$ and then $\alpha = \alpha_1$ is obtained as the solution of the kernel equation (5) for $\beta = \beta_0$.

Step 3: Finally, as long as our expression of linear combinations of product-forms violates one of the two balance equations on the boundary, we continue by adding new product-form terms satisfying the kernel equation (5). This will eventually lead to Equations (2)-(4). Of course, one still needs to show that the series expression of Equations (2)-(4) converge for all $n, m \ge 0$.

This procedure leads to the statement of Theorem 1.1.

The 2x2 switch

$$qp_{m,n} = q_{1,-1}p_{m-1,n+1} + q_{-1,1}p_{m+1,n-1} + q_{0,-1}p_{m,n+1} + q_{-1,0}p_{m+1,n} + q_{-1,-1}p_{m+1,n+1}, \quad m > 0, n > 0,$$
(2.2)

$$(q - q_{0,-1})p_{m,0} = q_{1,-1}p_{m-1,1} + q_{1,-1}p_{m-1,0} + q_{0,-1}p_{m,1}$$

$$+ (q_{-1,0} + q_{-1,-1})p_{m+1,0} + q_{-1,-1}p_{m+1,1}, \quad m > 0, n = 0,$$
 (2.3)

$$(q - q_{-1,0})p_{0,n} = q_{-1,1}p_{1,n-1} + q_{-1,1}p_{0,n-1} + q_{-1,0}p_{1,n}$$

$$+ (q_{0,-1} + q_{-1,-1})p_{0,n+1} + q_{-1,-1}p_{1,n+1}, \quad m = 0, n > 0, (2.4)$$

$$(q_{1,-1}+q_{-1,1})p_{0,0} = (q_{-1,0}+q_{-1,-1})p_{1,0} + (q_{0,-1}+q_{-1,-1})p_{0,1} + q_{-1,-1}p_{1,1}, \quad m = 0, n = 0,$$

$$(2.5)$$

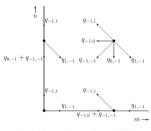
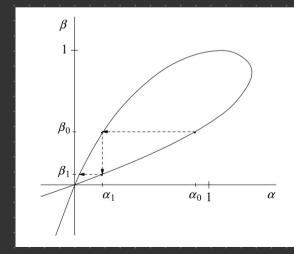


Figure 2: The one-step transition probabilities.

$$q\alpha\beta = q_{1,-1}\beta^2 + q_{-1,1}\alpha^2 + q_{0,-1}\alpha\beta^2 + q_{-1,0}\alpha^2\beta + q_{-1,-1}\alpha^2\beta^2.$$
 (2.7)



The starting term for the lorizontal:

$$(\alpha_0, \beta_0) = \left(\frac{q_{1,-1}}{q_{-1,1} + q_{-1,0} + q_{-1,-1}}, \frac{q_{-1,1}\alpha_0^2}{q_{1,-1} + q_{0,-1}\alpha_0 + q_{-1,-1}\alpha_0^2}\right). \tag{2.8}$$

the term $(\tilde{\alpha}_0, \tilde{\beta}_0)$ for the vertical boundary is symmetrical.

There is a starting term for the vertical: (20, Bo)

The initial solution

$$x_{m,n} = \underbrace{\overbrace{c_0 \alpha_0^m \beta_0^n}_{0} + \overbrace{d_1 \alpha_1^m \beta_0^n}_{V} + \underbrace{c_1 \alpha_1^m \beta_1^n}_{V} + \underbrace{d_2 \alpha_2^m \beta_1^n}_{V} + c_2 \alpha_2^m \beta_2^n}_{V} + \cdots$$
(2.11)

reduces to

$$x_{m,n} = \sum_{i=0}^{\infty} (1 - \beta_i) \beta_i^n [(1 - \alpha_i) \alpha_i^m - (1 - \alpha_{i+1}) \alpha_{i+1}^m].$$
 (2.12)

Accounting for the second solution xmin yields

$$p_{m,n} = x_{m,n} + \tilde{x}_{m,n}, \qquad m \ge 0, n \ge 0, m+n > 0.$$
 (2.13)

Clearly, from this result we can derive similar expressions for performance characteristics such

The numerical

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