



# Control of HVDC Transmission Systems: *1-2-Many Coordinated HVDC Links*

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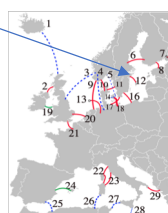
*Knut och Alice  
Wallenberg's  
Stiftelse*



2nd International Conference on Future Electric Power Systems and the Energy Transition, Feb 3-8, 2019, Champéry

## High Voltage Direct Current (HVDC) Transmission

- World's first commercial HVDC link in 1954
- Traditional HVDC tradeoffs
  - + Lower resistive losses for long transmissions
  - + Separating asynchronous AC systems
  - Expensive converters
- Emerging use of HVDC
  - Inter-area oscillation damping
  - Sharing frequency control reserves
  - Integration of renewables (offshore grids)



- **J. Björk**, K. H. Johansson, and L. Harnefors, Fundamental performance limitations utilizing HVDC to damp interarea modes. IEEE Transactions on Power Systems, 2019
- **J. Björk**, K. H. Johansson, L. Harnefors, and R. Eriksson, Analysis of coordinated HVDC control for power oscillation damping, IEEE Workshop on the Electronic Power Grid, 2018
- **M. Andreasson**, R. Wiget, D. V. Dimarogonas, K. H. Johansson, and G. Andersson, Distributed frequency control through MTDC transmission systems. IEEE Transactions on Power Systems, 2017

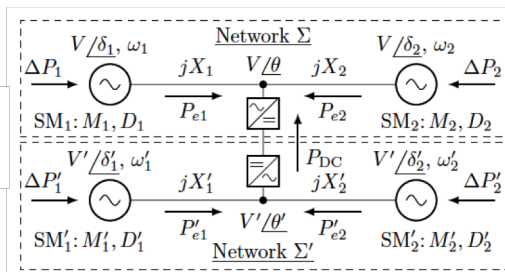
## Power Oscillation Damping using HVDC

AC networks represented by two two-machine models:

$$\begin{aligned} \dot{\delta}_i &= \omega_i \\ M_i \dot{\omega}_i &= \Delta P_i - \frac{P_{ei}}{X_i} \sin(\delta_i - \theta) - D_i \omega_i \end{aligned}$$

Interconnected by HVDC link

$$P_{DC} + \sum_{i=1}^2 \frac{V^2}{X_i} \sin(\delta_i - \theta) = 0$$



Linearization gives overall dynamics

$$\dot{z} \triangleq \begin{bmatrix} \dot{z} \\ \dot{z}' \end{bmatrix} = \begin{bmatrix} A_z & 0 \\ 0 & A'_z \end{bmatrix} z + \begin{bmatrix} B_z \\ B'_z \end{bmatrix} u \triangleq A_z z + B_z u$$

with states corresponding to relative angles and frequencies, and control  $u = P_{DC}$ .

Harnefors et al., 2017; Björk et al., 2018

## Fundamental Limitations in Single-line HVDC Power Oscillation Damping

Proximity in frequencies  $f_0$  and  $f'_0$  of poorly damped oscillatory modes in the AC networks limits the achievable power oscillation damping

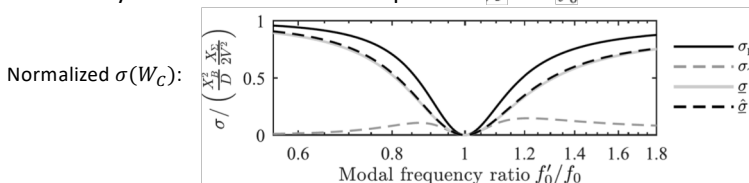
Follows from a controllability analysis with Gramian

$$W_C = \int_0^T e^{A_z t} B_z B_z^T e^{A_z^T t} dt.$$

representing the control effort required to transfer an initially disturbed system state to the origin

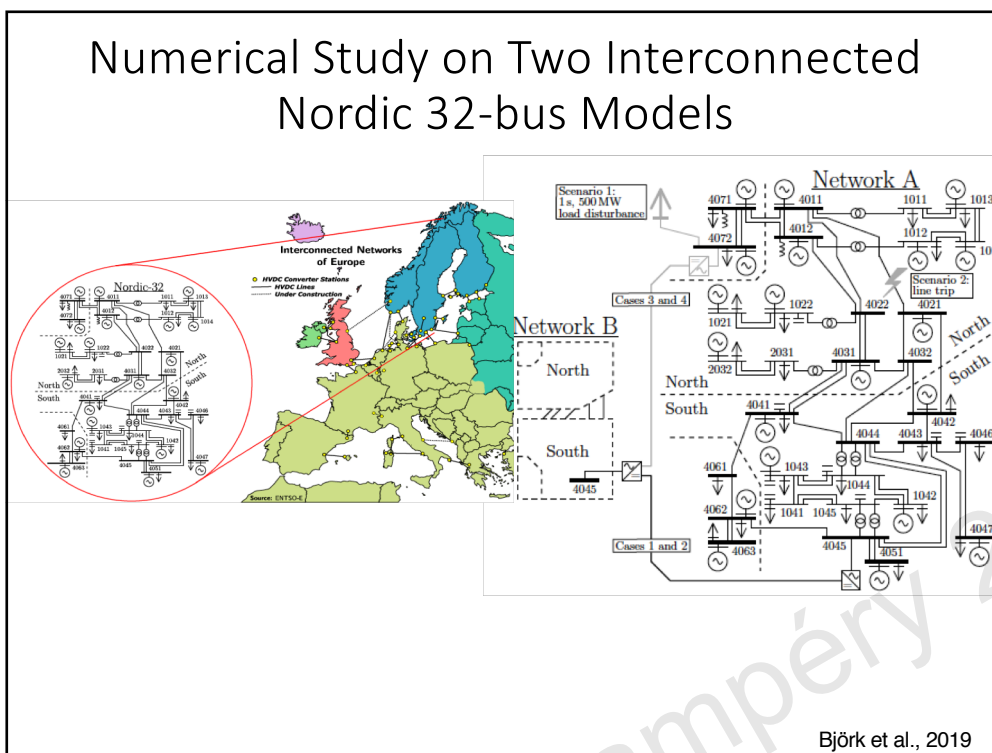
$$\|u\|_2^2 = z_0^T W_C^{-1} z_0$$

Controllability lost when the modal frequencies  $f_0$  and  $f'_0$  are close.



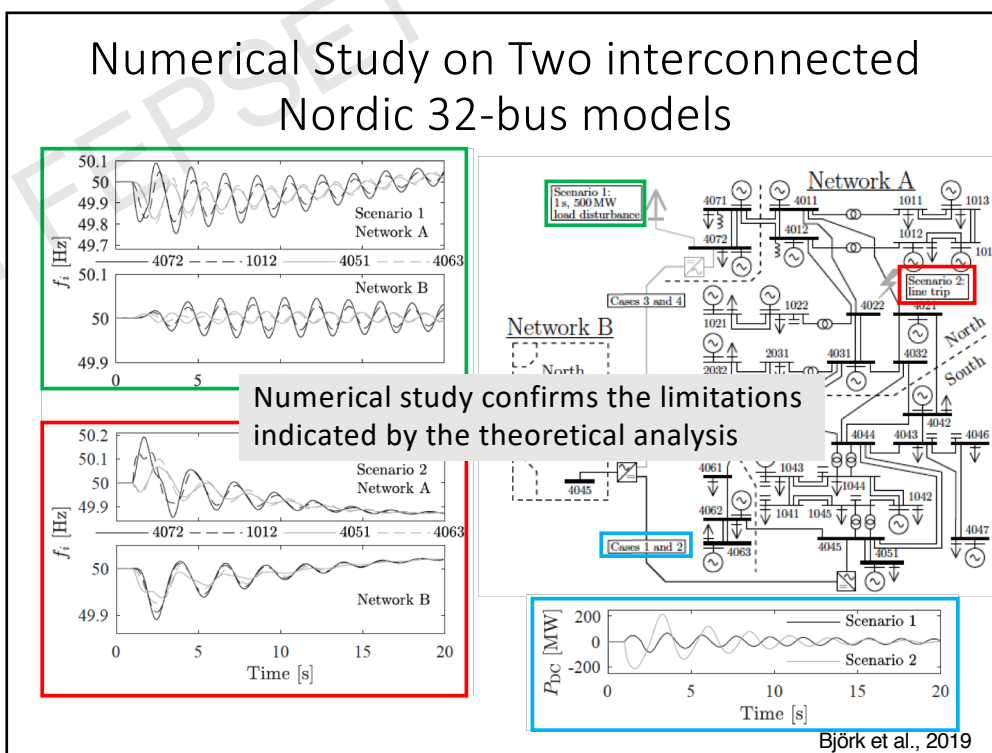
Björk et al., 2019

## Numerical Study on Two Interconnected Nordic 32-bus Models



Björk et al., 2019

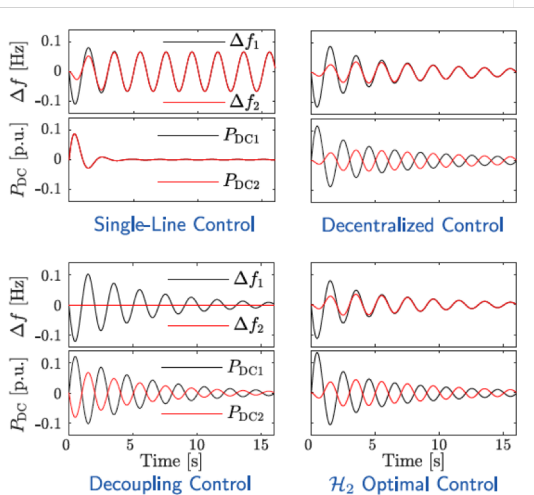
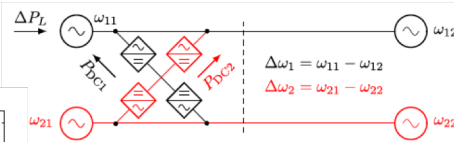
## Numerical Study on Two interconnected Nordic 32-bus models



Björk et al., 2019

## Two Coordinated HVDC Lines

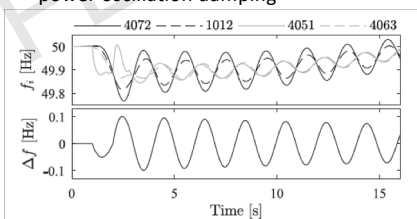
Two coordinated HVDC lines do not have the same limitations as single lines



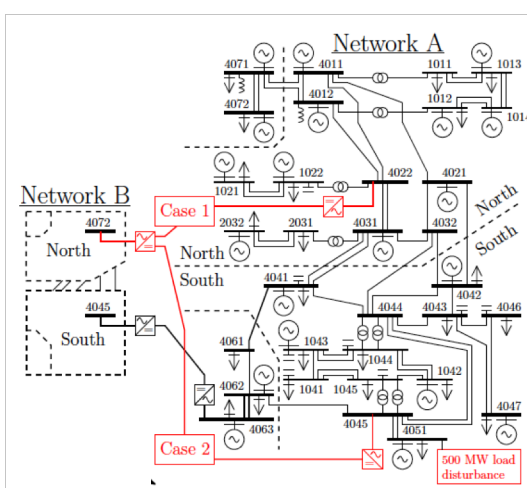
Björk et al., 2018

## Interconnected Nordic 32-bus Models Revisited

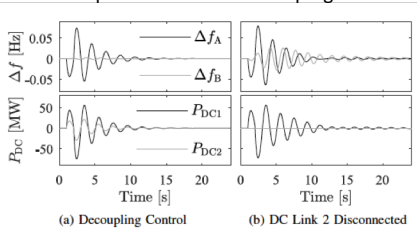
Disturbance response without HVDC power oscillation damping



Inter-area oscillatory mode frequencies  $f_0=0.5$  and  $f_0=0.6$  Hz for Networks A and B

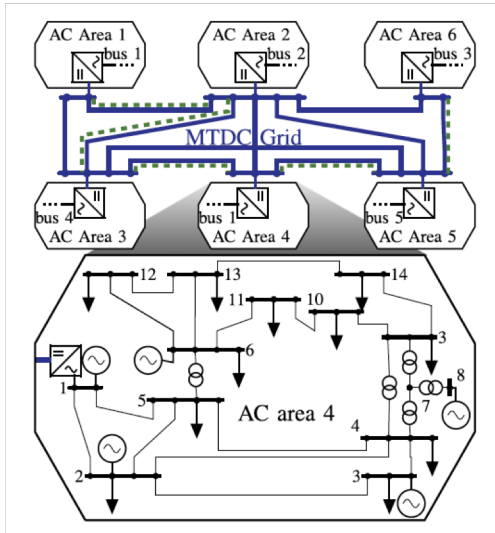


Disturbance and fault responses with HVDC power oscillation damping



Björk et al., 2018

## Distributed Frequency Control Through Multi-Terminal HVDC Transmission Systems



IEEE 14 bus AC grid  
Andreasson et al., 2017

How to share frequency control reserves between AC areas through a multi-terminal HVDC grid?

Converter dynamics

$$C_i \dot{V}_i = - \sum_{j \in \mathcal{N}_i} \frac{1}{R_{ij}} (V_i - V_j) + I_i^{inj}$$

AC system dynamics (single generator)

$$m_i \dot{\omega}_i = P_i^{gen} + P_i^m - P_i^{inj}$$

Objectives

$$\lim_{t \rightarrow \infty} \omega_i(t) - \omega^{ref} = 0 \quad i = 1, \dots, n,$$

$$\lim_{t \rightarrow \infty} P_i^{gen} = P_i^{gen*}, \forall i = 1, \dots, n, \text{ where}$$

$$[P_1^{gen*}, \dots, P_n^{gen*}] = \underset{P_1, \dots, P_n}{\operatorname{argmin}} \frac{1}{2} \sum_{i=1}^n f_i^P (P_i^{gen})^2$$

$$\lim_{t \rightarrow \infty} V_i = \tilde{V}_i^*$$

$$[V_1^*, \dots, V_n^*] = \underset{V_1, \dots, V_n}{\operatorname{argmin}} \frac{1}{2} \sum_{i=1}^n f_i^V (V_i - V_i^{ref})^2$$

## Stability of Distributed Frequency Control

Distributed generation controller of the AC systems

$$P_i^{gen} = -K_i^{droop} (\omega_i - \omega^{ref}) - \frac{K_i^V}{K_i^\omega} K_i^{droop, I} \eta_i$$

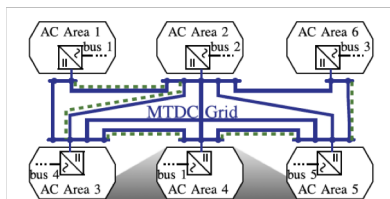
$$\dot{\eta}_i = K_i^{droop, I} (\omega_i - \omega^{ref}) - \sum_{j \in \mathcal{N}_i} c_{ij}^\eta (\eta_i - \eta_j),$$

Converter controller for the HVDC lines

$$P_i^{inj} = K_i^\omega (\omega_i - \omega^{ref}) + K_i^V (V_i^{ref} - V_i)$$

$$+ \sum_{j \in \mathcal{N}_i} c_{ij}^\phi (\phi_i - \phi_j)$$

$$\dot{\phi}_i = \frac{K_i^\omega}{K_i^V} \omega_i - \gamma \phi_i,$$



Theorem

Suppose the Laplacian matrices of the HVDC grid and its communication graph fulfills

$$\mathcal{L}_\phi = k_\phi \mathcal{L}_R,$$

and the converter control gain satisfies

$$\gamma > k_\phi / (4V^{nom}),$$

Then, the closed-loop dynamics

$$\dot{\hat{\omega}} = M \left( -(K^{droop} + K^\omega) \hat{\omega} + K^V \hat{V} \right. \\ \left. - K^V (K^\omega)^{-1} K^{droop, I} \hat{\eta} - \mathcal{L}_\phi S \hat{\phi}'' + P^m \right)$$

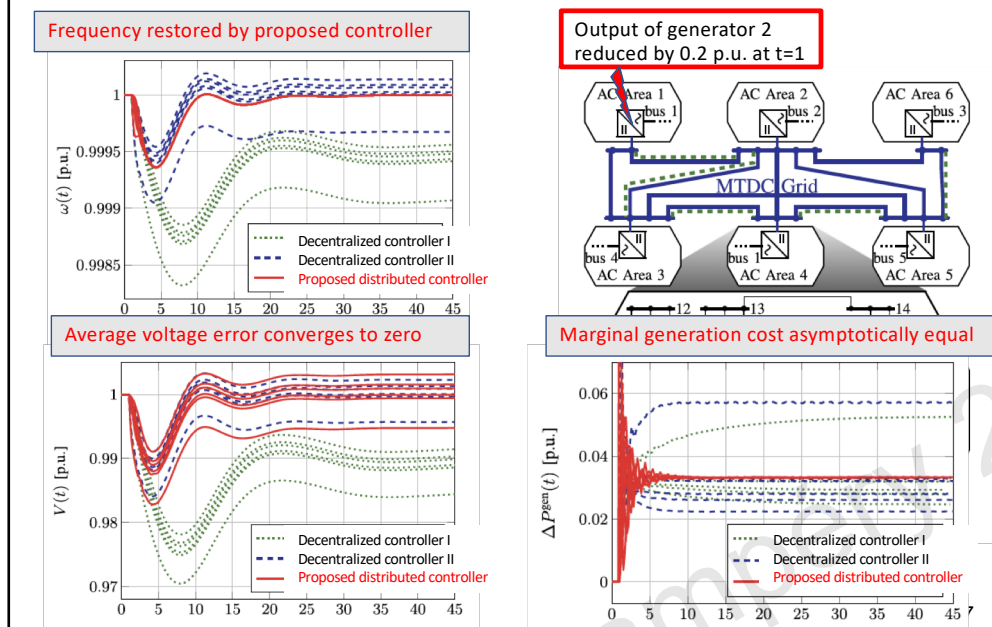
$$\dot{\hat{V}} = \frac{1}{V^{nom}} E K^\omega \hat{\omega} - E \left( \mathcal{L}_R + \frac{K^V}{V^{nom}} \right) \hat{V} + \frac{1}{V^{nom}} E \mathcal{L}_\phi S \hat{\phi}''$$

$$\dot{\hat{\eta}} = K^{droop, I} \hat{\omega} - \mathcal{L}_\eta \hat{\eta}$$

$$\dot{\hat{\phi}}'' = S^T (K^V)^{-1} K^\omega \hat{\omega} - \gamma \hat{\phi}''.$$

is globally asymptotically stable. The objectives are fulfilled for classes of control parameters.

## Simulation Evaluation of Proposed Controller

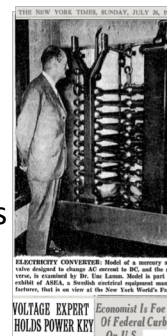


## Conclusions

- HVDC can be used to damp inter-area oscillations
- Damping by single HVDC line poses some limitations
- Can be overcome by coordinating multiple HVDC lines
- Multi-terminal HVDC for frequency reserve control

### Future work

- Detailed converter models in numerical studies
- Resilient coordinated HVDC control
- Realistic test scenarios in the Nordic grid



<https://people.kth.se/~kallej>