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## ABSTRACT

This work consists of two parts. One concerns the development of the University of Adelaide Computer Assisted Instruction System (UACAIS) and the other is an investigation into the problem of supervising trigonometric proofs in CAI.

UACAIS is a dedicated CAI system based on a Control Data 6400 computer and is designed to support a large number of student consoles. The associated author language ALFIE is cue-oriented. An experimental version of UACAIS has been successfully implemented.

Proof supervision refers to the dual task of checking and of assisting trigonometric proofs. The problems are confined to the single argument case. To simplify treatment, proofs are assumed to have the form $e_{0 \rightarrow e_{l} \rightarrow \ldots e_{n} \text { where the }}$ expressions $e_{0}$ and $e_{n}$ are directly related to the identity being proved and where each $e_{i} \rightarrow e_{i+1}$ is a step deriving $e_{i+l}$ fromei.

Proofs are checked step-by-step as they are entered. Each step must be both correct and small. The correctness of a step is a problem in expression equivalence. Step-size is however elusive, being largely dependent on subjective judgement.

The step-by-step checking of a proof can help the student considerably in his proofs by preventing them from going astray. More explicit types of assistance can take
the form of a set of relevant identities for substitution, a next-step to help him continue his proof, or information that no further trigonometric substitution is required. Much of such forms of assistance can be provided with the aid of an automatic proof generator.

Although proof supervision is essentially a symbolic problem, the main emphasis in the solutions proposed is on the use of numeric techniques. The numeric approach is advocated in the belief that it is superior to a purely symbolic one. several numeric techniques are discussed, including a simple test for deciding the correctness of a step. The most important of these is C-set determination which enables the supervisor to discover a minimum sufficient set of basic identities for proving a given problem identity. An identity requiring no substitution for its proof has an empty c-set. Some theoretical justification for the theory of C-sets is given, using algebraic geometry. Hilbert's Nullstellensatz plays an important role. The relevance of C-sets in proof-checking and in proof construction are discussed.

A scheme for defining models of small steps has been developed. Two models based on it have been selected for closer study. A survey of human opinions on step-size was conducted to provide data for gauging the adequacy of these models. Good agreement between both models and the human data was obtained.
The main ideas for proof-checking have been implemented in a program called super-2. The problem of implementing efficiently the various numeric techniques advocated has also been considered.

## DECLARATION

To the best of my knowledge and belief, this thesis contains no material which has been previously published or written by another person, except where due reference is made in the text. None of the material in this thesis has been accepted for the award of any other degree or diploma in any University.

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This work is concerned with the problem of supervising trigonometric proofs in computer assisted instruction (CAI). It also involves the development of a CAI system.

## Survey of CAI Literature

Since it first came into being some twenty-five years ago, the general purpose digital computer has come to play a very significant role in society. Computer technology has been developing so rapidly that it is now being applied to practically every major aspect of human activity, including education. Today the computer is finding increasing use in teaching and in educational administration.

In the last fifty years vigorous efforts have been made to produce better teaching methods. SoL. Pressey (see [41]) beginning in 1926 devised a series of simple devices for administering and scoring objective tests. He found that these devices could also be used to teach and saw in them the exciting possibility for automating and individualising instruction. However the work of Pressey and his students passed largely unnoticed.

It was not until the mid-1950's that the work of B.F. Skinner and his colleagues (see [65]) at Harvard University generated renewed interest in auto-instructional methods and teaching machines. This was soon to inspire the programmed instruction (PI) movement and its wider implications we now call educational technology.

Skinner argues that his extensive work on operant conditioning has direct relevance for the mechanisation of instruction. He developed teaching
programs for machine presentation that were characterised by linearity, small steps, constructed (i.e. overt) responses, low error rate, immediate knowledge of result, and the reinforcement of correct responses. Courses prepared in this way are referred to as linear or skinnerian programs.

Following the development of the linear program, other instructional paradigms have been devised. Crowder [14] introduced the intrinsic programming technique which features branching, larger steps, multiple-choice response and remedial sequences. Two other important instructional methods are the mathetics of Gilbert and structural communication of Bennet et al. (see [42]).

Early auto-instructional materials were presented by mechanical devices. These devices, called teaching machines, can display a segment of a course, and have provisions for accepting answers, usually of the multiple-choice type. Subsequent work has shown that instructional material can often be presented as effectively in the book medium as by teaching machines.

Schramm [62] sums up the essentials of PI as :-
(a) an ordered sequence of stimulus items
(b) to each of which the student responds in some specified way
(c) his responses being reinforced by immediate knowledge of results
(d) so that he moves by small steps
(e) thereby making few errors and practising mostly correct responses
(f) from what he knows, by a process of successively closer approximation towards what he is supposed to learn from the program.

Lumsdaine and Glaser [41] is a standard reference on the early works on teaching machines and programmed learning. The reader may also consult Unwin and Leedham [71], Dunn and Mulroyd [17] and Mann and Brunstrom [43] for more recent efforts in educational technology.

Although PI is potentially a very powerful approach to teaching, its effectiveness and flexibility have been seriously restricted by the traditional media of teaching machines and programmed texts. The digital computer, with its vast information processing and storage capability, and its ability to control multi-media learning stations, alone appears to be able to offer the full potential of programmed learning.

Silvern and Silvern [64] define CAI as a man-machine relationship in which the man is a learner and the machine is a computer system. A two-way communication exists between the human learner and the computer in which there is a stimulus-response-feedback interaction producing learning.

The reader is referred to Coulson [13] and Rath [59] for an account of early CAI development. For a recent review of the field, Hickey [33], Feldhusen and Szabo [22] and Engel [19] may be consulted.

CAI began in 1958 when Rath et al. [60] programmed an IBM 650 to teach binary arithmetic. In the next three years it was investigated at several centres which include Systems Development Corporation, Bolt, Beranek and Newman and the University of Illinois (see [59]). Since then the growth in the number of CAI projects, especially in the United States, has been remarkable. Recent CAI systems have become increasingly large and sophisticated.

Only a few prototype systems were reported by Rath [59] to exist over the 1968-61 period; each had no more than a few simple typewriter terminals. Today there appears to be more than a hundred institutions in the United States engaged in CAI activity. The New York City Board of Education's RCA Instructional 70 system [7] supported 192 terminals serving sixteen schools and there were plans to expand it. More recently, the University of Illinois was reported [18] to be planning for a system with more than 4000 stations using the "Digivue" display device.

Despite a decade of research and development ( $\mathrm{R} \& \mathrm{D}$ ), results obtained in CAI have been meagre [34]. Nevertheless the works of many centres including those of Hansen and Dick [31] at the Florida State University, and Suppes and his associates [67] at Stanford have clearly demonstrated the technical feasibility of CAI.

There is a small, but rapidly growing, number of studies on the comparative effectiveness of CAI. Their findings, although preliminary in nature, are encouraging and suggest that CAI is at least as effective as the other instructional methods under comparison. We cite a few such studies below.

One of the earliest studies, by Grubb and Selfridge [29] reported very marked superiority of CAI over conventional instruction. They taught six college students a half-semester course on statistics by CAI and another group by conventional lectures. The CAI group took an average of only 5.33 hours to complete the half-semester course and scored an average of $94.3 \%$
in an achievement test compared with an average of $58.4 \%$ for the conventional lecture group. The smallness of the CAI group must be borne in mind. Results from similar subsequent studies have been more modest.

Suppes and Jerman [68] at Stanford taught thirty students a computerbased course on elementary Russian. A control group received the same course in a conventional way. The CAI group was taught solely via teletype with Cyrillic keyboard and audio-tapes with earphones, fifty minutes daily, five days per week throughout the academic year. At the end of the year the CAI group was found to perform at a statistically higher level than the control group and to suffer a much lower dropout rate.

Love [40] presented a CAI course on Boolean algebra to groups of students; one group received the lessons individually whereas the other group did so in pairs. Both groups were later found on the average to perform equally well with respect to scores, time and error rate. This finding could mean a significant improvement in the cost-effectiveness of CAI.

Expressed student attitudes towards CAI have been very favourable. Thus Borman [5], Oldehoeft [52], Butler [7], Love [40] and Bell [2] are just a few investigators to report very positive reactions to CAI by their subjects.

With the technical feasibility of CAI well-established, $R \& D$ efforts have now been directed towards the wider problem of making CAI more effective and more widely applicable. Areas under investigation include instructional strategies, suitability of subject areas, hardware, software and economics. Needless to say, these problems are generally closely interrelated.

Most early CAI courses are essentially computerised versions of programmed instruction. Since CAI in a sense grew out of PI, this is hardly surprising. The student is presented the course frame-by-frame. Each frame is usually accompanied by one or more tests to ensure understanding. He responds to questions or problems by typing in his answers which are then analysed by the computer. If desired, responses can be recorded for subsequent investigation. Branching based on the student's most recent responses can be incorporated. Reinforcements in the form of encouraging remarks often accompany correct answers.

The drill and the tutorial are two important modes of instruction in CAI. Drills are usually test sequences on which students practise in order to reach a satisfactory level of mastery. The binary arithmitic course of Rath et al. [60] is issentially a drill. Among the best known examples of drill in regular instruction are the elementary school courses in mathematics and language skills developed by Suppes and Atkinson [67] for the Palo Alto schools.

Most courses in CAI are programmed in the tutorial mode. In this mode, actual teaching function is undertaken。 Learning objectives are carefully identified in terms of the student's entry and desired target behaviours. The latter is attained via a sequence of intermediate behaviours; at the course level these are effected by a carefully prepared program of steps which permit the stimulus-response-reinforcement interaction to occur.

The drill and the tutorial are, however, not the only modes of computerised instruction. Several other modes exist - each exploiting some
aspect of the computer's versatility, to facilitate a form of teaching for which it is best suited. Thus we have the inquiry/dialogue, simulation and gaming, information retrieval and the computational-aid modes of computerassisted teaching.

In the dialogue mode the student is encouraged to undertake greater initiative in the learning; to direct queries on points of difficulty or doubt, in general to engage the system in some form of restricted discussion. It is exemplified by the medical diagnosis exercise of Feurzeig [23] and the work of Taylor [69]. However the dialogue capability is still primitive.

The computer is a powerful medium for conducting gaming and simulation exercises. Unlike the drill, tutorial and dialogue modes, student interactions for these exercises are not programmed step-by-step. Rather, the rules of the game and the model underlying the simulation are incorporated into the program. This mode of CAI is useful in imparting decision-making skills in management sciences and military exercises. Examples of gaming and simulation programs can be found in [38] and [32].

Information retrieval is another way in which the computer can aid learning. With carefully organised data, students can use their own initiative to search for the information they require. One important work in this direction is that of Grubb [28] in his learner-controlled statistics course, which is organised as non-linear files of text and a series of maps with which the students can chart their own paths. An advantage of this approach is that detailed frame-by-frame programming becomes unnecessary.

Desk-calculator facilities are provided in PLANIT [21] and several other systems. A more sophisticated form of computational aid are the systems of Culler and Fried [15] and Oliver and Brooks 153]. These systems, though not designed specifically for CAI usage, can provide a useful on-line display and computation facility for teaching numerical analysis.

CAI systems employ two basic levels of software :-
(1) the operating system that drives the hardware
(2) the teaching programs.

The operating system usually includes programs for presenting instructional materials; accepting, analysing and recording student responses; and various peripheral equipment drivers. There are also softwares for course preparation and validation, on-line or off-1ine.

To facilitate and simplify the task of preparing courses for computer presentation, author languages have been developed. Zinn [73] is so far the most comprehensive document on languages for instructional programming. In it more than thirty languages have been studied, classified and assessed. He notes that despite their variety, many of their differences are superficial, leaving some user needs still unmet. He notes four classes of instructional languages according to their operational characteristics :-
(1) presentation by successive frames
(2) conversation within a limited context
(3) presentation of a curriculum file by a standard procedure, and
(4) data analysis and revision of materials.

Such a classification is useful but it should be noted that most languages do not fall neatly into a single category.

The majority of CAI languages belong to class 1. Examples are COURSEWRITER (various versions, IBM), PLANIT (SDC), COMPUTEST-II (U of Calif. Medical Centre, San Francisco), and INFORM (Philco-Ford). Of these COURSEWRITER is perhaps the most widely used. Class 1 languages generally have convenient facilities for the display of text, acceptance and analysis of student responses, recording of performance data, and branching based on the student's answers or his response history.

MENTOR (BEN) and ELIZA (MIT) are typical examples of class 2 languages. MENTOR has been used [23] to teach medical diagnosis via conversational interaction. ELIZA has been used [72] by its developer, Joseph Weizenbaum, to simulate a psychiatric interview, which conveys a surprisingly good impression of dialogue and understanding. This has been achieved by analysing input sentences on the basis of decomposition rules associated with keywords in the text. Selected decomposition rules are then used to assemble machine responses in the conversation. ELIZA has subsequently been used for developing teaching programs [69], which again permit the above kind of dialogue.

Two examples of languages for presenting curriculum files by a standard procedure, i.e. class 3 languages, are CATO of the PLATO project of Illinois University and CG-2 of Meadow et al. (see [73]). Such languages are characterised by the agidityone builtmin teaching strategies and the with weo... whem wor consequent ease in which courses can be prepared. Thus jn CATO, the author's task is little more than the insertion of slides for the corresponding slots for questions, hints, answer explanations, and keying in the correct answers
at a keyboard.

It is not clear if class 4 forms a useful classification since every language for CAI has some facility for data analysis and course revision and therefore belongs to the class. [ Chow 4 has becen reptased in a labe.
repert by Zimn]
Some class 2 languages like MENTOR and FOIL [32] have also been used for programming games and simulation. It is also worth noting that some author languages are extensions of existing standard algorithmic languages which by themselves would be very inconvenient, if not impossible, for writing courses. Thus MENTOR is an extension of LISP and CATO and FOIL are extensions of FORTRAN.

Several author languages permit students to use the computer for computation while taking a course. These include COURSEWRITER which has a service program called DESCAL, and PLANIT which incorporates a fully-integrated CALC mode that can be used interactively by authors during lesson building and by students during lessons. The CALC mode of PLANIT contains rather sophisticated computational routines for functions, matrices and statistical tables. Interactive computing is a basic feature of languages like APL and BASIC, but these are not CAI languages.

Every CAI language has an answer-processing capability which varies from the recognition of multiple-choice responses to the recognition of complex algebraic expressions. Some of the commoner CAI answer-matching routines are [25] :-

| Type of Match | Language |
| :--- | :--- |
| Exact string | all languages |
| keyword | all languages |
| selected string | CAL, COURSEWRITER |
| Percentage | COURSEWRITER, LYRIC |
| partial string | CAL, COURSEWRITER |
| phonetic | PLANIT, PLANIT |
| algebraic expression | LYRIC, PLANIT |
| numeric (within specified limits) | CATO, PLANIT |
| calculated numeric |  |

Cost has been a severe constraint on the implementation of CAI. Estimates for the cost per student console hour vary from as low as 20¢ (see [74]) to as high as over $\$ 80$ [9]. These differences in estimates are due to variations in assumptions regarding hardware, course development, operational and other costs. The reader is referred to Chapin [9], and Kopstein and seidel [36] for their treatments on the problems in estimating costs in CAI and on the economics of CAI generally.

It is widely agreed that CAI cannot at present be justified purely on the basis of cost. Indeed there are some who do not even regard it to be a partial replacement for traditional teaching; rather they see it as an experimental learning and teaching laboratory in which learning and instructional hypotheses can be tested under a fairly realistic, and yet controllable, learning environment. There are also those who see CAI as a
powerful means for testing and validating teaching materials, which can then be adapted for cheaper conventional presentation.

Several points have been cited in favour of CAI: it is auto-instructional, cheat-proof; it is said to be capable of providing independent, simultaneous, mass, multi-media instruction with great scope for individualisation both by pre-programming and by dynamic adaptation. It is also capable of recording student performance data, including responses to questions. Not all these advantages have been fully realised or convincingly demonstrated.

Several modes of computer assisted instruction have been mentioned earlier. No single mode can be regarded as being unqualifiedly superior to another, some are more suited than others, for certain teaching objectives. However there is still much scope for the development of new CAI modes.

One promising direction for investigating new instructional modes is that of intelligent CAI systems. By this term we mean a system which simulates some aspect of human intelligence. The vast information processing capability of modern computers seems to have been hardly tapped. In most CAI systems the computer is little more than an information storage and retrieval device, with very little data manipulation required.

Important work is being done in the area of artificial intelligence (see [47, 48]). Slagle [66] has written a LISP program for integrating elementary expressions symbolically. Later, Moses [49] developed a more powerful program which can solve a wide range of textbook integration problems with practically no wrong attempts at all. D.G. Bobrow [4] developed a
program for solving high school story algebra problems. These problems, posed in simple English, are converted into their equivalent equations and then solved. Raphael's [58] SIR program is a question-answering system which is able to accept (understand) simple English sentences expressing certain relationships between objects. It is also able to answer simple questions on relationships about objects, given enough information.

Successful automatic theorem proving programs for first-order predicate calculus have also been written (see Robinson [61]).

This author feels that the important results already obtained from research in artificial intelligence would be useful for the development of intelligent CAI systems. In particular, as John McCarthy [45] has pointed out, any program for generating proofs can be incorporated into a proof checker - and this has relevance for proof-supervision in CAI, of which more will be said later.

## Scope of this work:

The work to be described in this thesis involves initially the development of a CAI system - the University of Adelaide Computer Assisted Instruction System or UACAIS. The aims of this undertaking were :-
(a) to create a facilicy for investigating CAI;
(b) to enable the author to acquire practical experience in CAI and an appreciation of some of its problems;
(c) on the basis of experience in CAI gained in (b), to single out problems for further investigation.

This initial work led to the subsequent investigation into the problems associated with supervising proofs in elementary trigonometry.

## A Brief History of this Work:

While CAI systems were growing rapidly in number and sophistication overseas, none existed* in Australia in 1966. That year Ovenstone [54] outlined how a large CAI system might be implemented on the University of Adelaide's Control Data 6400 computer. The following year, P.G. Perry and K.C. Lee [55] undertook** to design and implement a CAI system based on the CDC 6400 as part of their graduate research program. This work was under the supervision of Professor J.A. Ovenstone. Terminal and interface hardware was developed by Dr. R.J. Potter [56] and became available at the end of 1968.

The first phase of UACAIS has been completed. It includes the development of the operating system and an author language called ALFIE (Adelaide Language for Instruction \& Education). These will be described in the next two chapters.

As the development of UACAIS progressed, a number of problems confronting CAI became obvious. One of these lies in the area of response processing and concerns the analysis of certain types of responses occurring in mathematical instruction.

* In 1967 a simple CAI capability was incorporated into a time-shared PDP-6 computer at the University of Western AustraZia.
** The development of UACAIS has been a joint, cooperative effort between Peter Perry and the author. It is not easy to attribute any major portion of this development completely to any one of us. Perry played the major role in the overall development and was largely responsible for the implementation of the CAI operation system, including the resident central progran, system monitor and interface driver. The author developed the language ALFIE and its associated compiler. He also programmed the resident disc driver and display programs as well as a number of routines in the operating system.

It has been noted by Glaser [27] that an essential component of the auto-instructional process is performance assessment. The system must continually determine whether the desired learning goals are being attained or not, and this requires response processing. However when we consider the teaching of mathematics, we find that existing capabilities are inadequate for assessing certain kinds of performance. Problem solving and proof construction are skills fundamental in mathematical training. To determine whether a student can solve a problem* or not, it is normally quite sufficient to check only his answer - usually a number, an expression or some similar entity. On the other hand there is no similar simple quantity which a student may type in to indicate that he can prove a proposition. What is required in this case is a supervisory sub-system for following through and validating a proof.

A similar supervisor for checking problem solutions would be both very useful and desirable - especially when incorrect answers are received. This is because in programmed instruction, the knowledge that a student's answer is wrong helps him discover where, why or how his solution has been incorrect. This is made possible by the smallness of a PI frame. However the solving of a problem is generally a large multi-step process and the knowledge of incorrectness of the answer often sheds very little light on the nature and location of the error. An answer can be wrong simply because of a trivial

[^0]error in a single solution step. By checking his solution as it is input into the system, a solution supervisor could reveal an error as it occurs, or help the student discover the nature of his error in some similar way.

We have argued briefly the need for a CAI sub-system for supervising matkmatical solutions and proofs. While work along this line does not appear to have been done before, the idea of a supervisory system for some formal system is not new. Computer programs for checking proofs have been proposed before, although in a different applicational context. In [45], McCarthy discusses some possible uses of proof-checking programs in mathematics and systems engineering. The solution supervision concept is also implicit in Uhr [70] and Feurzeig and Papert [24]. Actually CAI systems which have interpretive/interactive compilers for teaching programming languages already incorporate a supervisory capacity.

At present very little appears to be known about supervising mathematical proofs. As a modest initial attempt at gaining some understanding of this problem, we have chosen a simple topic, elementary trigonometry, for investigation. This has led to the design considerations for a trigonometric proof supervisor (TPS), capable of :-
(a) checking and validating proofs of trigonometric identities
(b) assisting the student to construct his proofs.

In the actual application of TPS, the following situation is envisaged. The student is asked to prove a problem identity at his console. He inputs his proof step by step via a suitable input device and TPS examines each step as it is input, for correctness and for acceptability of step size. The student may seek help when in difficulty and receive some assistance in the
form of a useful identity for substitution, a 'next step' to enable him to continue, suggestions about the method to employ in the proof or some other relevant information. When the student gives up, the system may either give him a proof or complete his proof from where he left off. When his proof is unduly long, the system may bring this to his attention. It should also be appreciated that the student is receiving very important aid from the fact that his steps are analysed immediately on input.

As an illustration, we offer the following hypothetical TPS-student interactions. The replies from TPS are assumed to be based on standard messages stored in the system.

TPS : Show that $\cot ^{4} \mathrm{~A}-\csc ^{4} \mathrm{~A}=1-2 * \csc ^{2} \mathrm{~A}$
STUD : $\cot ^{4} A-\csc ^{4} A$
$=\frac{\cos ^{4} A}{\sin ^{4} A}-\frac{1}{\sin ^{4} A}$
$=\frac{\cos ^{4} A-1}{\sin ^{4} A}$
$=\frac{\left(\cos ^{2} A-1\right)^{*}\left(\cos ^{2} A+1\right)}{\sin ^{4} \mathrm{~A}}$
$=\frac{\sin ^{2} A^{*}\left(\cos ^{2} A+1\right)}{\sin ^{4} A}$
TPS : Incorrect
STUD : (Oops! Forgot the minus sign - erase last expression)
$=\frac{-\sin ^{2} A^{*}\left(\cos ^{2} A+1\right)}{\sin ^{4} A}$
$=\frac{-\left(\cos ^{2} A+1\right)}{\sin ^{2} A}$
$=\frac{-\left(\cos ^{2} A+\sin ^{2} A-\sin ^{2} A+1\right)}{\sin ^{2} A}$
$=\frac{-\left(2-\sin ^{2} A\right)}{\sin ^{2} A}$
$=1-\frac{2}{\sin ^{2} A}$
$=1-2 * \csc ^{2} \mathrm{~A}$

QED
TPS : Correct. But look at the following proof:
$\cot ^{4} A-\csc ^{4} A$
$=\left(\csc ^{2} \mathrm{~A}-1\right)^{2}-\csc \mathrm{A}$
$=\csc ^{4} A-2 * \csc ^{2} \mathrm{~A}+1-\csc ^{4} \mathrm{~A}$
$=1-2 * \csc ^{2} A$ QED

TPS : Show that $\frac{1+\tan A-\sec A}{\sec A+\tan A-1} \equiv \frac{1+\sec A-\tan A}{\sec A+\tan A+1}$
STUD : $\frac{1+\tan A-\sec A}{\sec A+\tan A-1}$
$=\frac{1+\sin A / \cos A-1 / \cos A}{1 / \cos A+\sin A / \cos A-1}$
$=\frac{\frac{\cos A+\sin A-1}{\cos A}}{\frac{1+\sin A-\cos A}{\cos A}}$
$=\frac{\cos A+\sin A-1}{1+\sin A-\cos A}$
\# HELP
TPS : It is easier to prove this identity by showing that LS/RS $\equiv 1$.
STUD : \#HELP (requesting further help)
TPS : You need only use the identity: $\sec ^{2} A=\tan ^{2} A+1$
: ! !
IPS : Prove: $(1-\cot A) *(1-\tan A)=2-\sec A * \csc A$
STUD : $(1-\cot A) *(1-\tan A)$
$=2-\sec A * \csc A$

QED

TPS : This is not a proof at all!
STUD : (erasing the previous expression - to renew proof)
$=1-\cot A-\tan A+\cot A * \tan A$
\#HELP
TPS
STUD

TPS
STUD
: (exases last expression)
$=2-\cos A / \sin A-\sin A / \cos A$
\# HELP
TPS
STUD
: You will need $\cos ^{2} A+\sin ^{2} A \equiv 1$, csc $A \equiv 1 / \sin A, \sec A \equiv 1 / \cos A$

- (continuing)
$=2-\frac{\cos ^{2} A+\sin ^{2} A}{\sin A \cdot \cos A}$
$=2-\frac{1}{\sin A \cdot \cos A}$
$=2-\sec A \cdot \csc A$
QED
Good

TPS has only been partially implemented. A program called Super-2 for checking trigonometric proofs off-line has been written. It incorporates a model for small steps and uses a numeric technique for verifying the correctness of steps. The section of TPS for generating proofs and rendering problems associated with it have been considered in some detail and are described in the thesis. A novel method for determining reference identities 'relevant' to a proof has been developed.

This work on proof supervision constitutes the major part of this thesis and may be regarded as a contribution towards the development of intelligent CAI systems.

To recapitulate, this thesis comprises essentially two parts :-
(i) the development of UACAIS, including ALFIE
(ii) an investigation into the problem of supervising trigonometric proofs. Although they appear unrelated, it was the pursuance of (i) which led to the problem (ii).

## CHAPTER II

This chapter is essentially a revised and expanded version of the paper [55] by Perry and Lee. It describes the August 1969 version of the University of Adelaide Computer-Assisted Instruction System (UACAIS). The main emphasis is on external rather than internal features and only a general outline of the internal organisation will be given.

UACAIS is implemented on a Control Data 6400 computer [ll]. The aims of the system are to provide :-
(a) a flexible medium for the presentation of teaching programs;
(b) authors and instructional researchers with useful statistics on the effectiveness of their teaching programs;
(c) a general experimental tool for the investigation of teaching and learning processes.

## Basic System Features

UACAIS is based on existing equipment and its available software togethex with locally-developed interface and terminal hardware and its supporting software.

In the initial stages of the implementation, the CDC 6400 installed at the University had the minimum 32 K of 60 -bit central memory, a central processor (CP), and ten peripheral and control processors (PP), each of which is an autonomous computer with its own store of 4096 12-bit words and an unlimited access to the central memory by the use of read and write instructions. The 6400 also had twelve bi-directional l2-bit data channels, common to all

PPs and connected to the various peripheral equipment.

The main peripheral I/O devices were :-
(a) a dual-screen CRT display console with manual keyboard. Display modes are dot and character; characters comprising 26 alphabetics, 10 numerics and 11 specials, in three sizes;
(b) a mass storage discfile providing nominal storage of 500 million bits;
(c) six magnetic tape units, with three recording densities on half-inch tapes of up to 2400 feet;
(d) one card reader with a maximum speed of 1200 cpm ;
(e) one card punch;
(f) two 800-lpm line-printers;
(g) one 10-inch CALCOMP incremental plotter.

The CDC 6400 has since been upgraded by the addition of :-
(a) 32 K of 60 -bit central memory.
(b) three remote terminals each with a CRT display console, a card reader and a line-printer.
(c) four removable disc-pack units.
(d) a 30-inch CALCOMP plotter.

Some of the peripheral I/O devices were not required in the CAI system, although the card reader and the line-printers were used for certain off-line CAI applications such as course preparation. The remote CRT terminals and the disc-packs were acquired too late to be incorporated into the system, but should prove extremely important for future versions of UACAIS. The CRTS would be a useful replacement for the noisier and slower typewriters now in
use. The use of removable disc-packs would enable a virtually unlimited number of courses to be available on-line very conveniently and rapidly. At present, required courses have first to be loaded onto the discfile from tapes.

The major peripheral device in UACAIS is the discfile which serves as a random access, high-speed transfer, mass storage unit. It is used in the CAI system in three main ways:-
(a) The complete operating system is copied onto the discfile from tape as it is loaded. This allows the system to be recovered without a complete reload in the event of a hang-up. It also facilitates rapid access to PP subprograms when they are needed.
(b) All teaching programs are stored on the discfile when needed. A system of directories gives access to any course segment by name.
(c) The disc is used as a backing store for student operating information. Each console is allocated the required amount of space by the system. The implementation of the CAI system represents considerable programming effort.* The entire software has been developed by P.G. Perry and the author, and has been coded completely in the central and the peripheral assembly languages [12] of the CDC 6400. The size of the system precludes a detailed description of the programs in the system; only an outline of the more important ones will be given.

[^1]The system includes the monitor, the display and the disc driver programs, each residing in a separate PP. The remaining seven PPs form a pool on which the monitor can draw, for the execution of any of a suite of utility subprograms, including equipment drivers and general routines for performing jobs which cannot be carried out conveniently by the CP. The main programs in the system are outlined below.

MTR MTR is the monitor program and resides in PP-O. It controls the assignment and release of pool PPs, data channels, disc space and peripheral equipment, and coordinates their activities. It also maintains a realtime clock and services $C P$ and $P P$ requests for the loading and execution of utility programs.

RDD This is the disc driver program. It resides in PP-9 and communicates with the discfile via channel-00. RDD queues and processes all access to the discfile. $P P$ requests to $R D D$ are for data to be read from the disc, for data to be written on the disc, for the loading of PP overlays and for the release of disc tracks. $C P$ requests concern mainly the loading of course segments on central memory, and the transfer to and from the disc, of student record information. RDD maintains a request stack, 1 for $P P$ and $u p$ to 8 for $C P$, servicing them on the basis of their required disc access times, rather than on the first-come-first-served principle. Thus for two competing requests, the one entailing less track select and disc group-head switching time, will be serviced first. The reason for adopting such a priority system is to ensure optimum throughput between the disc and central memory.

Resident in PP-1, DSP is the system display program, driving the 6400 CRT scope via channel-10. It monitors system status and activity and permits operator control of the system from the keyboard. Among the operations it can handle are the activation and deactivation of channels, the assignment and the switching on and off of equipment, the modification of central memory and the despatching of equipment function codes. These control functions of DSP had proved invaluable in the debugging of the CAI system - during the various phases of its implementation. The display console has also been used to simulate the student terminals before they became operational.

RCP is the major resident central memory program. It contains various monitor and student communication tables as well as student working areas. Figure 2.1 is an outline of the central memory in $R C P$ and gives an insight into the internal structure of the program.

RCP is also responsible for the presentation of courses. The system was designed to have eight student areas to be time-shared by up to 512 students through swapping. Course segments not immediately required in core are rolled out to the disc, while segments that require processing are loaded from the disc. Since we do not expect to have more than a few dozen consoles for some considerable time, this version of UACAIS has been modified to have arbitrarily, forty student areas. This means that for up to a maximum of forty consoles, no swapping of student working records will be necessary. RCP accepts and processes, using an interpreter subroutine, the instructions of the teaching program. It
analyses student answers, performs the appropriate branching, records on tape student responses and performance data when so directed, and also handles the sign-on and sign-off protocol. RCP also maintains a desk calculator facility for servicing simple computational needs. The student uses this facility through the \#COMPUTE command; the syntax for the expressions to be evaluated resembles the one for the register expression in ALFIE. (See Appendix A)

The system software also contains many other programs. These include those for driving the login tape, the logout tape and the student responseperformance tape. Also included are the remote console/interface driverscheduler and the course and system loaders.

|  | Monitor Tables |
| :---: | :---: |
|  | Student Communication Tables |
|  | Resident Central <br> Program |
|  | Central Program Student Working Area <br> (n $\times 1000$ words) |
|  | Free Storage |
| 177777 |  |

Figure 2.la Central Memory Utilisation



## The CAI Consoles

The CAI consoles and their interface with the computer have been designed and built within the University [56]. The interface is designed to have up to 64 external links, two of which have now been implemented. Each link is capable of controlling 8 consoles, giving a maximum of 512 consoles.

A console is a unit which can contain up to seven pieces of equipment, only one of which can be operating at a time. The consoles available at present have only a typewriter (for input and output) but it is hoped that future consoles will incorporate a slide projector, a computer-controlled tape-recorder, for the playback of pre-recorded messages only, and a CRT display in lieu of the typewriter.

The consoles work on a basic seven bit code, with an eighth bit for Indicating control functions, such as status response and unit select, and three bits for the console address. The seven bit format allows for an implicit case bit in the typewriter code (see Appendix A).

All consoles are run by a single driver subprogram which schedules the console to be processed on each link at each cycle and performs certain automatic functions such as deactivating faulty consoles and links.

Although only four consoles have been built, the system is theoretically capable of processing the full complement of 512 consoles.

Input messages are terminated by a carriage return (c/r) and are not recognised by the system until this is received. The student can delete single characters by backspacing, and erase a whole message by using a character characters, it is automatically terminated and a $c / r$ sent back.

When messages from the student are being interpreted, the first test is for the first character being "\#" indicating a command word. If not the system next checks if an answer to a question is expected. Failing this the message is rejected.

## Operating Features

The general layout of the configuration of UACAIS is given in Figure 2.2.

Although a powerful computer could be expected to time-share CAI with normal job processing, as is being done elsewhere, this system has been designed as a dedicated system. The modifications needed in the standard operating system of the CDC 6400, SCOPE, would have taken at least as long to make as the preparation of an independent system from the start. Also a more compelling reason is that there would not have been enough core space left in the then minimum 6400 configuration, to run background jobs as well. F'urthermore, such a design would have been even more sensitive to revisions in the operating system than to those in the independent system; it should be appreciated that SCOPE was undergoing numerous revisions at the time.

In the event of a software hang-up, the system cannot at present be recovered, as it is an experimental rather than a production version. However, the loader saves a copy of the system on the discfile at load time and the major tables can be replaced from central memory. Even if the tables in memory were lost the portion of the disc which is used as a backing store would contain the positions of all students from only a few seconds before;


Figure 2.2 UACAIS Configuration
only a list of the active consoles would be needed to effect a recovery. Student Working Record Format

Some further insight into the internal arrangement of the system can be gained from the format of the information used to process an individual student. (See figure 2.ld.) This is best described in three separate phases:
(a) At Sign-on Time

When the student types in his registration code, a record with that code name is searched for on the login tape. This record should contain the student's name, his mode (whether he is a student, author or a proctor), the contents of various counters and a list of all the courses for which he is enrolled. Each item in this list includes the course, chapter and page names, the total time spent on the course so far, and the content of counters for the course.
(b) During Operation

The student working record during operation can be divided into two main parts:

1. Header, containing the student's name, various counters and flags, the course name and the position in the course. This section is derived initially from the information found in (a) above, and is altered as the student progresses.
2. Body, which is a copy of the current segment of the course. By keeping this copy with the information concerning the particular student, it is not necessary to search for it each time the student is processed.

With a total record length of 512 60-bit words and the header taking up 48 words, a maximum segment length of 464 words is left. A full segment containing only textual data and the necessary data transmission commands could contain up to 2000 characters, and these would take about $2 \frac{1}{2}$ minutes to present. During the swapping to and from the disc of the student working record, the full record need be written on the disc only once; subsequent transfers to the disc, for a given page of the course, need involve only the first one or more disc segments ( 64 words each) of the course required to cover the header. This is because only the header portion is variable during operation, and once a copy is on the disc, only the header segments need be altered. (Disc transfers are carried out in segments.) Since in a fully implemented 5l2-console system a great deal of disc swapping operation can be expected, valuable time would be saved by not retransferring the non-varying segments of the record to the disc.
(c) After Sign-off

When the student signs-off the record header information is dumped on another tape, the logout tape, in its final form. The information it now contains is the student's code, time spent during the session, the new counter values, the name of the course and the new position in it. This information is used to produce an updated master record (or login) tape so that when the student next signs on, the new course position is known. However this updating is made only after the CAI
system has finished running; by using disc packs instead of two magnetic tapes in future, immediate updating of the student master record can be made.

The Author and the Student's Views of the System
To the author, the system is essentially a means of presenting a course. This he can achieve through the author language ALFIE. At present courses are prepared off-line on cards and assembled by the ALFIE course compiler onto tape.

A student signs-on at the console by typing in his registration code. He then selects from among the courses for which he is enrolled the one he wishes to pursue. This course is presented to him according to the author's instructions: he may be offered informative material explaining a concept, then presented with questions to probe his grasp of the concept and additional, remedial, material if necessary.

The student has some control over the presentation by use of command words, such as LOGOUT, STOP, GO, LOCATE, COMPUTE and HELP. These may be abbreviated to any extent by dropping the end characters. For instance, HELP could be shortened to HEL, HE or simply $H$; the requirement that the abbreviation should uniquely identify the command is obvious - failure to do this will cause the use of the first command word in the table which could satisfy the message.

The student uses LOGOUT to sign off from the session. The STOP suspends the presentation of the course, until a GO is received. The GO also overrides any system/course interrupts, causing the lesson to continue. The

COMPUTE is used for simple calculations; the student supplies the expressions to be evaluated. HELP causes the system to present any cueing material that may be associated with the question presented. LOCATE enables the student to jump to any course segment by specifying its chapter and page names as necessary.

The student may also be directed to a proctor at another console and they can converse through the medium of the typewriter. This feature has not been fully implemented in the current version.

## Recovery of Statistics:

The CAI system has a wealth of statistics available to it and many of these may be recorded quite simply. The selection of statistics will be largely the responsibility of the authors, but typical data would include the time to reach a certain position in the course, the latency time for a response, the number of attempts at a question, and unanticipated answers.

The data is recorded in raw form on tape for off-line processing where it can be summarised in various forms, both from the point of view of the course and the individual students.

The current version of the system is operating with the four typewriter consoles so far installed. Several course segments have been developed to debug the system and to test out various language features. Most of the system features that have been described have been implemented and they are now working correctly.

Our experience with the present version indicates that the system can be expanded to support additional consoles without difficulty. Only a slight
expansion to certain hardware driver routines would be required. Also additional commands can be added in a modular fashion without adversely affecting the overall system.

Although the CAI system described cannot claim to compete with overseas systems in terms of size and complexity, for systems are now being built with several thousand consoles, we feel that apart from being the first experiment with large scale CAI in Australia it does have some novel features.

The course preparation language, ALFIE, is naturally enough unique While this is not necessarily desirable in terms of standardisation, some of its features, especially the control which the author has over the presentation of cueing materials are, we believe, new.

Apart from the provision of more consoles, and of more sophisticated design, some of the hardware additions to the computer which would most facilitate CAI operation are:
(a) Extended Core Storage: This is a fast access core backing store, addressable by block transfers of any length. This could be used to reduce the memory space used by programs and tables, allowing the use of more extensive programming features than would otherwise be possible. The use of E.C.S. as a backing store would also reduce the load on the discfile and significantly cut down disc swapping time.
(b) Disc Packs: These are fast random access, replaceable storage devices which could be used for storing CAI courses, thereby eliminating the need for copying them from tape to the discfile prior to use. Faster sign-on would also be possible with the student master records stored on disc packs and an updated record could be produced immediately on

## sign-off.

The development of the preliminary version of UACAIS has also led to ideas for useful additions to the software. This includes expansion and improvements to the author language, the development of an on-line course compilation, testing and revision capability. The set of keyboard commands should be expanded. Application packages for extracting student performance statistics should be developed; preferably these should be accessible from the keyboard. Also basic statistics like time spent in the current session, performance level and so on, should be immediately available to the student when he signs-off.

This chapter describes and discusses the main features of ALFIE, the author language for the Adelaide CAI system. A detailed specification of the language is given in Appendix A.

At present courses may be prepared only on cards. They are compiled onto magnetic tape for subsequent use under UACAIS. During CAI operation, required courses are loaded from tape onto the discfile ready for use. Courses are presented to the students at the remote consoles on their typewriters. The students communicate with the CAI system via the typewriter keyboard. They progress independently of one another, each proceeding at his own pace. Different students may be doing different courses, or different segments of a common course simultaneously. This independent presentation of courses is done automatically by the operating system. The author, in preparing a course, may imagine that he is teaching only one student, even though in reality, a single course may be used by more than one student during a CAI session.

While making ALFIE as flexible and powerful as we can, we have also attempted to make it easy to learn and convenient to use. This we believe we have achieved to a large extent, judging from the speed with which beginners have learnt to program courses in the language.

## Compiling ALFIE Programs

A course on cards is actually compiled in two stages. The first stage is performed by LKC, a preprocessor program for translating the course in the card format into a common intermediate code called CONCODE. The actual
compiler (or assembler) ALF, then converts the course in CONCODE into the object codes. It can be seen that we have in this way, made provisions for the implementation of other course-preparation media. All that is required for a new medium is a corresponding preprocessor for converting a course in that medium into CONCODE. Figure A. 3 (Appendix A) illustrates the approach just discussed.

In the compilation, two listings are also produced:-
(1) the source card listing produced by LKC (see Figure A.1); and
(2) the assembly listing produced by ALF (see Figure A.2).

The preprocessor LKC distinguishes between five kinds of course cards by examining their first columns. They are:-
(1) Listing Control Card (LCC): This has a 2-8 ( $\overline{\mathrm{D}}$ on IBM 029) punch on column l. It is used for producing and suppressing source card listing.
(2) Comment Card (CC): A CC is characterised by an '*' on column 1. The characters on the remaining 79 columns are treated as comments, and appear on the source card and assembly listings.
(3) Edit Card (EC): Carries $a^{\prime}=$ ' on column 1 and 'EDIT' on the next four columns. The EC is used as an aid for line truncation and text justification.
(4) Keyword Card (KWC): A KWC has a '\$' or ${ }^{\prime} \rightarrow$ ' ( $\bar{w}$ on IBM 029) on column 1 , or a 'c' if it is a continuation KWC. KWCs are for carrying instructions, each of which is identified by a keyword.
(5) Textbody Card (TBC): A TBC is normally one with column 1 blank; however any card which is not an LCC, CC, EC or KWC is a TBC. TBCs are used for coding typewriter texts streams. A text stream is a string of
typewriter codes to be output on the typewriter, and consists of a set of successive TBCs bonded by two KWCs.

The characters available on the console typewriters are the usual:-
(1) Alphabetic: A B C... X Y Z a b c ou. x y z
(2) Numeric: $\quad 123 \ldots 7890$
(3) Special: $+\cdots$ / ( ) $\$=$ blank , $[$ ] \# : ' o
\& _" \% @ ? ? ;

Available control functions are: carriage return, index*, tab, backspace and the black and red ribbon select.

Textual material must be composed from this set of characters and functions only. Since many of these are not available on a standard card punch, a card code for representing them is required. Table A.l gives the list of all available typewriter characters and functions, their card codes based on the IBM 029 punch, as well as other codes.

A course in ALFIE is essentially a sequence of directives or instructions and texts. The directives are KWCs while texts are made up of TBCS; CCs, ECs and LCCs may be included as comments and to control source and listing and text editing.

A course is organised into an arbitrary number of named chapters, each of which may have up to sixtyfour named pages. Figure A. 4 in Appendix A shows schematically the organisation of a typical course into chapters and pages. The arrows indicate the various kinds of branching permitted in ALFIE.

[^2]Each course directive is associated with a keyword and belongs to one of the three categories:
(1) listing control
(2) course organisational
(3) command.

The listing control directives are the LIST and NOLIST instructions. These are respectively directives to the assembler to produce and to suppress assembly listing. By placing the LIST and NOLIST cards appropriately in the deck, a selective listing of a course is obtained.

The organisational instructions are the COURSE, CHAPTER, PAGE and END cards. They direct the assembler in the organisation of a course into chapters and pages. Every course begins with a COURSE card, which initiates and names it. Each chapter is started and named by a CHAPTER card, which also terminates the previous page and chapter if any. Each page begins with a PAGE card which names it, and terminates the previous page if any. The END card terminates the current page, chapter and course.

The command directives enable an author to present texts, ask questions, accept and analyse student answers, take the appropriate action on the basis of such analyses, make either conditional or unconditional branches to almost any point in a course, perform register arithmetic ( $q . \mathrm{v}_{\mathrm{o}}$ ), sequence and control the presentation of a course and record student responses.

Command directives may be labelled. A label is any alphanumeric string not exceeding six characters, followed by a colon as in '\$L2:CUE.'. A label may occur by itself, as in '\$LX3:' and serves to define a page location.

The $' \rightarrow$ ' used instead of the ' $\$$ ' on column 1 of a KWC defines an implicit label ( $q, v_{*}$ ). All non-implicit labels in a page must be unique.

A command directs the course interpreter to perform certain operations. Commands are normally executed one by one down the page, continuing on the next page. This strictly sequential execution is interrupted by branch instructions. Certain critical (q.v.) commands like the CUE, also have special meaning which will be explained later.

When a command is executed, the next one will be executed immediately unless the command contains a delay - whether explicit or implicit. A delay is a period that must elapse before the next command is executed, but it can be overriden by an interrupt from the student, typing in an answer or a '\#GO'.

The various commands in ALFIE will now be briefly described. The reader may refer to Appendix A for further details.

The rexT command instructs the system to present the immediately accompanying text stream. A TEXT without an accompanying text stream is ignored. However a text stream need not be preceded by a TEXT card, in which case a '\$TEXT.' card is assumed. A delay of up to 999 seconds can be specified via the $T$-parameter. If not specified, as in '\$TEXT.', a l second delay is assumed, while $\mathrm{T}=$ * implies an infinite delay.

The SIGNOFF command signs off the student, who cannot then resume his course until he signs on again. The student can also sign himself off by typing in '\#LOGOUT'.

The COMPLETED command directs the system to sign-off the student, and informs it that he has finished his course. There may be more than one COMPLETED and SIGNOFF in a course.

The CUE, ANSWER, ENDANS, WAITCUE and GIVECUE commands may be used only in a problem environment, a rather loose concept which will be explained later.

The CUE is the command which directs the system to accept and analyse an answer from the student. The answer should be entered within the permitted delay; otherwise the system will execute the next command. The delay can be optionally specified by the $T$-parameter; if this parameter is absent as in '\$CUE.' , then an infinite delay is assumed. A repetition factor is also allowed in a CUE, e.g. '\$CUE, $4(T=10)$ ' is equivalent to four successive '\$CUE $(T=10)$ ' cards. The actual interpreter action on the CUE will be explained in the section on the problem block.

The ANSWER and ENDANS commands enable the author to specify one or more answers against which the student's responses are to be compared. The M-parameter specifies the answer recognition mode, the default mode being $\mathrm{M}=3$. At present only the modes $0,1,2, \ldots 14$ are implemented. These cover the following kinds of matches: catch-all (in which any answer matches), exact string match without prior editing of student answer, after removal of blanks or some specifiable class of characters, truncated string match, unordered list match, numeric match with specifiable numeric limits and algebraic expression match.

For each problem block, the author supplies a sequence of answers, the last of which must be an ENDANS. Thus if there is only one answer specified,
it must be an ENDANS. Only the ENDANS can have $M=O$, the catch-all mode.

An answer command also carries a C-parameter which can take any of the values $0,1,2, \ldots 63$, the default value is 0 . The $C$-parameter will be included in a recording of a response match with the answer. It is useful as a means of categorising answers in the course - for expediting subsequent analysis of recordings of student performance data.

Although the answer recognition capabilities available are adequate in meeting a wide range of needs, there are many answer processing needs that have still to be catered for. The modes so far implemented have been chosen to meet the immediate needs of the current phase of the CAI project. Three examples of the answer command are:-
(1) \$ANSWER ( $\mathrm{M}=2, \mathrm{C}=3)$ *PERMUTATION*
(2) \$ANSWER $(\mathrm{C}=4)=$ WARM=FRIENDLY=GENIAL=
(3) \$EN $\stackrel{\text { D }}{\text { D }}$. *NS *UBIQUITOUS*

The WAITCUE and GIVECUE commands carry no parameters. The WAITCUE instructs the system to re-execute the last-executed cue in the problem block. The GIVECUE differs from WAITCUE in that it instructs the system to execute the command immediately following the last-executed cue; this is usually some cueing text.

The TIME instruction, e.g. "\$TIME, $2 X X$. . instructs the system to record the current time, at which the present course position, specified by the name in the instruction, is reached. This is useful in investigating the time taken by different students to reach various course positions. The DELAY command instructs the system to pause for a specified period.
'Ihus '\$DELAY $(I=100)$ ' is a request to wait for 100 seconds to elapse before resuming course execution, unless there is a student-initiated interrupt.

The WAIT command instructs the system to output in red the character overprint "W" on the typewriter as a signal to the student to press the carriage return key when he is ready to resume. The WAIT may not be imbedded in a problem block.

The PROBLEM card carries two parameters - a problem block name and a recording or R -parameter, enabling the author to name a problem block, and to specify the recording mode. Student responses and other performance data will be recorded according to the associated PROBLEM card.

There are three kinds of unconditional branching :-
(1) Intra-page e.g. \$GOTO,L2.
(2) Inter-page but intra chapter e.g. \$GOTO,PAGE (TX2)
(3) Intra-chapter e.g. GOTO, CHAPTER(P2),PAGE (U26).

The intra-page branch enables the author to specify a transfer to anywhere in a page by specifying the label of the destination. The special case ' $\$ G O T O, \rightarrow$ ' is a branch to the next implicit label, i.e. ' $\rightarrow$ ', below in the page. The other branch instructions permit transfer to any named page in the same chapter, or the first or any named page of any other named chapter. Register Arithmetic

The author is provided with fifteen registers (or counters), A,B,C,... M,N,O. Each register is used to hold a 60-bit real number. By means of register statements (see Appendix A), the author can set register values and perform floating-point arithmetic on numeric constants and register values.

All registers are zeroed at the beginning of a course. Registers may be used to keep track of individual student progress. An example of the register statement is: $\$ A=B-4 * F / G$.

Conditional branching based on register values are allowed. The general form of the conditional branch is:- IF (relational expression) Br where ' Br ' stands for any unconditional branch statement. The relational expression, which can be true or false, is a statement about relative register values. 'The 'Br' is taken only if the relational expression is true. Examples of conditional branching are:-
(1) $\$$ IF (B.LE.G) GOTO ,K44.
(2) $\$$ IF (C. GT. 12) GOTO , PAGE (JA3) .

We should also mention here that some keywords have equivalent alternatives. Thus all the following keywords in a parenthetical group are equivalent: (CUE, EXPLAIN,EXP); (PROBLEM,BLOCK,PRB,BLK); (ANSWER,ANS); (ENDANS,ENS).

We have now covered briefly all the commands in ALFIE. The important concept of the problem block will now be described and this is quite vital in the understanding of the language.

## The Problem Block

The cue, answer, WAITCUE and GIVECUE commands are critical instructions in that they may be used only in the context of a problem environment, and not arbitrarily. Here, 'cue' refers to CUE,EXPLAIN or EXP; 'answer' to any of ANSWER,ANS, ENDANS and ENS.

A cue sequence is a set of one or more cues, possibly interspersed with
text and non-critical commands. It has the form:

e.g. \$CUE, 2 ( $\mathrm{T}=10$ )

It begins with a 'C'
\$CUE (T=15)
\$TIME, AG2.
Try again.
\$EXP
The answer is 'crisis'.

An answer sequence is either an ENDANS or a set of answers (not ENDANS)
terminated by an ENDANS. The sequence may be interspersed with text and
other instructions, but excluding cues and the WAIT.
c. Y. \$ANS (M=2) *COMMON*

Nearly correct. Try again.
\$WAITCUE.
\$ENS (M=2) *ORDINARY*
Correct.

A cue sequence followed by an answer sequence constitutes a problem
block. The cue sequence and the answer sequence have no independent standing; every cue sequence must be accompanied by an answer sequence.

Any answer sequence not immediately preceded by an unconditional branch, will have a "GOTO, $\rightarrow$ " automatically inserted there. Thus
:
\$CUE---
SANS---
:
is equivalent to


The problem block is a paradigm for posing a question to the student
and for accepting and analysing his responses against the author answers. The first cue of a problem block is normally preceded immediately by the text of a question or problem that is to be answered.

When a cue is encountered, the system outputs on the typewriter, on a new line, a red question mark '?'. This indicates to the student that an answer is expected. The system also sets a pointer to the associated answer sequence; to the first answer in fact. The student's answer must be received before the delay in the cue expires; otherwise the student forfeits his chance to answer, the pointer is cleared, and the next command below the cue is executed. If no $T$-parameter is set in the cue, the student may take as much time as he likes to enter his answer.

On receiving an answer, the system next executes the command indicated by the pointer; in this case it is the first answer command of the problem block. The answer is checked against the author answer in this command. If the answers match, then execution of the course resumes from immediately after this answer command; any subsequent answer command executed will be treated as matching (see later). If the answers do not match, then the pointex is reset to the next answer command, if any, and answer comparison is again made. The action taken by the system on the outcome of this comparison described above is repeated. Thus each answer in the problem block is executed in turn until either a successful match has been made or all answer commands have been exhausted. In this latter case the student's answer does not match any of the author answers, and the system clears the pointer, types out "Incorrect" and continues the course from immediately after the cue.

What usually follows the cue is some prompting or explanatory text - hence the keyword CUE and its equivalent EXPLAIN.

When an answer command is executed, the student's answer is compared with the author's answer(s), under the specified mode. The outcome of this comparison is either a (successful) match or a mismatch. If there is no student answer to be compared, e.g. when his answer has already been matched with a preceding answer in the same answer sequence, then a match with the answer (s) is assumed. If there is a mismatch, then the answer pointer is reset to the next answer command; this next answer is then executed. If no next answer exists, then the course resumes from the cue which has led to the execution of this answer command. If there is a match, then the course continues from immediately after the answer command just executed.

A problem block may not be split over two or more pages. When an author-defined page exceeds the page limit, the assembler will attempt to spread it over two or more pages without splitting any problem block.

## Specimen Course and Interaction:

Figure 3.la is the source listing of a course which has only one chapter and one page. The course is named 'SPECIMEN', the chapter 'ONE' and the page 'RR4'. The 'non-standard' characters in the texts are mainly codes for indicating upper and lower cases in alphabetics and for terminating text cards. (See Table A.1.) They appear in a more natural form in Figure 3.lb which is an assembly listing of the page. The assembly listing of text simulates as far as the line printer permits, its appearance on the typewriter; thus while spacing, backspace, tab etc. are reflected exactly, this listing

> 3.1a Source Listing
cannot show the effects of case changes in alphabetics, and of ribbon changes.

Note the three comment cards with an '*' on column 1. The page location into which each instruction is compiled is also shown in the assembly listing. At the bottom of this listing, the number of unused words in the page is printed.

Page RR4 is essentially a problem block and the following are three student interactions with it. Every student response is terminated with a carriage return, but this is not shown. Student type-ins are given here in italics.
(a) Which element has the atomic symbol 'Pt'?
?PLATINUM
Good. Platinum is correct.
ABCD....
(b) Which element has the atomic symbol 'Pt'?
?TOTASUIUM
Incorrect.
Pl_...Try again.
? (ivudent fails to respond within 20 seconds)
pt is a metal, often used as an industrial catalyst.
?PLATINUM
Good. Platinum is correct.
ABCD....
(c) Which element has the atomic symbol 'Pt'?
?PHOSMHORUS
Phosphorous is 'P'.
Pl__. Try again.
?PLUTONIUM
plutonium is 'Pu'.
Pt is a metal, mainly used as an industrial catalyst.
?PLATTINUM
Incorrect
The answer is: PLATINUM.

## Cueing Feature of ALFIE

Unlike most CAI languages, ALFIE is a cue-oriented language, especially
suited to the presentation of hints or cues. It is an easy matter to program a problem which allows the student say three attempts at it, with a hint to follow each of the first two unsuccessful attempts. It is of course also possible to do the same thing in other CAI languages, but usually with less convenience.

One potentially useful application of the cueing feature of ALFIE is in the investigation of guided discovery learning. Suppose it is desired to teach a concept, which is small in some sense. A common approach in PI is to present a unit $U$ of information, usually a paragraph or two, to describe or explain the concept. An evaluative question $Q$ is then presented to assess the student's understanding. The student may be allowed several attempts, with or without hints. If the student fails to answer correctly, he will be given the correct answer. This conventional approach to instruction may be referred to as the IFTL or inform-first-test-later paradigm.

An interesting variation of the IFTL approach is the TFIL or test-first-inform-later paradigm. In this approach, 2 is presented first and the unit of information $U$ presented later only when necessary, i.e. when the student shows he does not already know the concept by failing to answer $Q$ correctly.
'The two approaches can be shown diagrammatically in Figure 3.2.
rrFIL in effect does not present to the student what he already knows, lhot
but gives only those information he needs. It is therefore an adaptive instructional technique in which good students could save much valuable time by not having to go over familiar material. At the same time students not familiar with a given concept is not penalised - but has the chance of learning


## Figure 3.2 Two Instructional Paradigms

it. Since it is both difficult and costly to develop good branching programs, TFIL might prove to be a cheap, simple and effective way of developing adaptive teaching material.

It is not suggested here that TFIL is widely applicable and can be used to achieve all teaching objectives. Rather it might prove to be especially appropriate and advantageous in some areas of application. As an example, TFIL might be very suitable for course revision, since students could be expected to be fairly familiar with the course, but need to review it and be refreshed in some areas. One can also envisage a TFIL course that can be
used for teaching as well as for revision, using the same material, since only those materials that have not been properly learnt or remembered will be re-presented.

TFIL also enables the student to learn by discovery, since in being tested on a concept even before it is introduced and explained, the student is required to 'discover' the answer. Materials learnt by discovery are often better retained, although there is no general agreement on this [16].

Between the two extremes of IFTL and TFIL there is a rich spectrum of allied instructional paradigms. In fact it is often possible to break U into subunits of information, $U_{I}, U_{2}, \ldots U_{k}$, not necessarily of equal substance. The student can then be taught a concept, by being presented with the evaluative question $Q$, and then $U_{1}, U_{2}, \ldots U_{k}$ in that order for each successive incorrect attempt. If $U_{l}$ is more substantial than the other subunits $U_{2}, \ldots U_{k}$, then by presenting firstly $U_{1}$, and then $Q$, and if necessary, successively $U_{2}, U_{3}, \ldots U_{k}$ we have a cue-oriented approach to instruction. One could think of various alternatives to these - all having the feature of teaching by guided discovery.

There is still considerable confusion over whether discovery learning refers to a method of teaching, a method of learning or something one learns. De Cecco [16] defines it as pertaining to those teaching situations in which the student achieves the instructional objectives with limited or no guidance from the teacher. It is characterised by the amount of guidance the teacher provides.
(a) increases intellectual potency
(b) increases intrinsic motivation
(c) teaches discovery techniques, and
(d) improves retention.

These various aspects of discovery learning can be investigated through the TFIL and other related cue-oriented techniques for teaching that have just been discussed. In particular the effect of varying degrees of guidance on the effectiveness of learning can be studied very conveniently in ALFIE. Useful changes that could be made to ALFIE include :-
(1) On-line facility: The development of an on-line keyboard-entry course preparation facility would be very useful. No special complicated card code for typewriter characters and functions would be needed. More importantly, in conjunction with immediate testing of course segments as they are built, the course can be quickly debugged and revision effected immediately.
(2) Answer processing: Present facilities are still rather primitive and sufficient to meet only immediate needs. However, these will have to be expanded. This expansion should not be done by simply adding more answer recognition modes. Rather what is required is a concerted examination of the answer processing problem so that simple and consistent methods for specifying acceptable answers, and the corresponding processors for recognising matching answers, can be developed.
(3) Course Structure: It would be far more convenient to the author if the organisation of a course into chapters and pages were left to the compiler. The author can then regard a course as a continuous sequence
of text and instructions.
(4) Imbedding Problems: At present problem blocks may not be nested. The removal of this restriction will enable a richer variety of programming techniques to be implemented.
(5) Edit Feature: The edit card has proved to be very useful, but does not provide enough features. It should therefore be expanded to include two-sided justification (at present all lines start on column 1) and richer options for text editing.
(6) Keywords: Some of the keywords can be simplified, e.g. \$GTC (ONE,TWO) instead of the current \$GOTO, CHAPTER(ONE), PAGE (TWO), and \$GTP(P22) instead of \$GOTO,PAGE (P22).
(7) Performance Data: At present student responses can be recorded. But there are no packages for extracting useful information from the recorded data and performing other useful analyses. Such packages should therefore be developed, with special emphasis on ease of use by interested parties. Simple performance summaries should also be available from the keyboard.

## EXPRESSION EQUIVALENCE AND CONSISTENCY SETS

Our aim in this and the next three chapters is to investigate some of the main problems in developing a trigonometric proof supervisor (TPS) and to suggest possible solutions. As indicated previously we envisage students inputting proofs from remote CAI terminals. The function of TPS is to check the incoming proofs step by step and to assist and guide the students as required.

For TPS to be of practical value in CAI, students should be serviced without unbearable delay. Therefore we should seek solutions which are practical and efficient enough to meet this real-time requirement.

Problem Scope
We confine our investigation to the class of mono-argument problems. This means that all the trigonometric functions will be of a single argument $\theta$. Our class $R$ of all allowable trigonometric expressions will be as given by the BNF definition below. <digit> $\quad:=0|1| 2|\ldots| 7|8| 9$
<unsigned int> $::=$ <digit>|<unsigned int><digit>
$<\operatorname{trig} \mathrm{fn}>\quad::=\sin \theta|\cos \theta| \tan \theta|\csc \theta| \sec \theta \mid \cot \theta$
<AOP> $::=+1-$
<MOP> $::=* \mid /$
<primary> $::=$ <trig fn>|<unsigned int>|(<trig exp>)
<factor> : := <primary>|<primary> $\langle$ <unsigned int>
<term> ::= <factor>|<term><MOP><factor>
<trig exp> $::=$ <term>|<trig exp><AOP><term>|<AOP><term>

Q corresponds to the syntactic class <trig exp>. However we exclude from $Q$ expressions like $\sin \theta /(\tan \theta-\sin \theta / \cos \theta)$ which are mathematically ill-defined. The symbol ' $\uparrow$ ' denotes exponentiation. We have excluded variables from our expressions, but this is merely to simplify the presentation of our theory of consistency sets. e.g. $(\sin \theta+2 * \cos \theta) \uparrow 2$ and $(\csc \theta+1) /(1-\sec \theta \uparrow 2+\cot \theta)$, but not $\sin (A+B)-\tan C$ and $B * \sin \theta+C / \cos \theta$, are valid expressions in $Q$.

In the subsequent we may use the more usual and convenient notations $a b$ and $a \cdot b$ for $a * b, a^{2}$ for $a \uparrow 2$ and so on. Also when brevity is desired we may write $\sin \theta, \cos \theta, \ldots$ as $\sin , \cos , \ldots$ without the $\theta$.

Table 4.1 lists the basic identities I1, I2, ... I8 and the supplementary identities J1, J2, J3, J4 in their standard form. These are the identities which we permit the student to assume in his proofs. Except for the supplementary ones, this choice of reference identities is fairly standard in textbooks. We allow these identities to be used (in substitution) in their various simple variants. Thus Il may be used in the form $\csc \theta-1 / \sin \theta \equiv 0$ and $\csc \theta \sin \theta \equiv 1$ while 16 may be used in such forms as $\sin ^{2} \theta \equiv 1-\cos ^{2} \theta$ and $\left(\cos ^{2} \theta-1\right) / \sin ^{2} \theta \equiv-1$. Note that the reference identities are by no means independent since, given Il, I2, I3, I4 and I6, we can derive the remaining identities in the table. Non-Pythagorean

| $\csc \theta \equiv 1 / \sin \theta$. | ... Il | $\sec ^{2} \theta \equiv \tan ^{2} \theta+1$ | . I7 |
| :---: | :---: | :---: | :---: |
| $\boldsymbol{s e c} \theta \equiv 1 / \cos \theta$ | ... I2 | $\csc ^{2} \theta \equiv \cot ^{2} \theta+1$ | - I8 |
| $\cot \theta \equiv 1 / \tan \theta$ | . I3 | Supplementary |  |
| $\tan \theta \equiv \sin \theta / \cos \theta$ | .. I4 | $\tan \theta \equiv \sin \theta \cdot \mathbf{s e c} \theta$ | 。Jl |
| $\cot \Theta \equiv \cos \theta / \mathrm{sin} \theta$ | . I5 | $\tan \theta \equiv \sec \theta / \csc \theta$ | . J2 |
| Pythagorean |  | $\cot \theta \equiv \cos \theta \cdot \mathrm{csc} \theta$ | . J3 |
| $\sin ^{2} \theta+\cos ^{2} \theta \equiv 1$ | .. I6 | $\cot \theta \equiv \csc \theta / \mathrm{sec} \theta$ | ... J4 |

## Difficulty in Proof-Checking

Let $e_{\ell}=e_{r}\left(e_{\ell}, e_{r} \varepsilon()\right.$ be a problem identity: The aim of $a$ proof is to show the equivalence of $e_{\ell}$ and $e_{r}$. There are various waysof doing this, the most direct being to derive $e_{r}$ from $e_{\ell}$. Other approaches include deriving 0 from $e_{\ell}-e_{r}$ and deriving $I$ from $e_{\ell} / e_{r}$. However this is a question of proof strategy which we will ignore 2 . Without loss of generality we will assume a proof to be a chain of steps which derives a target expression from an initial expression using only algebraic manipulation and trigonometric substitution. Each step derives one expression from another.

The task of proof-checking is then essentially to verify the correctness and acceptability of each step in a proof. The difficulty is that in our algebraic system, the various basic rules and axioms, especially of commutativity, associativity and distributivity, give rise to a proliferation of informal rules. These informal rules have become standard in algebraic reasoning because of their longstanding usage. Thus the step $\sin ^{2} \theta-\cos ^{2} \theta \rightarrow(\sin \theta-\cos \theta) *(\cos \theta+\sin \theta)$ uses an informal rule which may be regarded as a combination of the factorisation rule ' $A^{2}-B^{2}=(A+B) *(A-B)$ ' and the commutativity of '+' and '*'. The factorisation rule is itself based on the axiom of distributivity, the definition of indices and so on. Because there are so many of these informal rules it would be impractical, if not futile, to check their explicit use in a step.

Some formal systems, like the predicate calculus, do not have so many informal rules because of the nature of their axioms and inference rules. It may therefore be a reasonable approach in such systems, to
check a proof by verifying explicitly that only valid inference rules have been used and valid premises assumed.

It is suggested that a direct approach for checking trigonometric proofs would not be very promising. In particular this means that a purely symbolic approach should be avoided. In this thesis we have opted for an approach which is largely numeric. Preliminary Notions and Definitions

By the rational operations of algebra we shall mean those operations that conform to the laws of equality of expressions which are consequences of the basic laws of equality, the field axioms* and the definitions of subtraction, division and indices. This means that trigonometric substitutions are excluded. We list below some examples of rational algebraic operation. $a, b, c$ and $d$ stand for expressions, terms, or factors as appropriate and $m$ and $n$ are integers.

- $\mathrm{ax}(-\mathrm{b})=-\mathrm{axb}$
- $(-a)+(-b)=-(a+b)$
- $(-a) x(-b)=a x b$
- $\mathrm{axO}=0$
- $\left(a^{m}\right)^{n}=a^{m n}$
- $a^{0}=1$
- $-(a-b)=-(b-a)$
- $-0=0$
- $(a x b)^{m}=a^{m n} x b^{m}$
- $a^{m} x^{n}=a^{m+n}$

Let us now define a few terms. All expressions are from $\mathbb{Q}$. Defn: Two expressions $f$ and $g$ are equivalent, denoted $f \equiv g$, if one is derivable from the other solely by rational algebraic operations and substitution of reference identities.

[^3]e.g. (1) $(1-\sin \theta / \cos \theta) * \sec ^{2} \theta \equiv(1-\tan \theta) *\left(1+\tan ^{2} \theta\right)$
$\left(1-\sin ^{2} \theta\right) \equiv(1-\sin \theta) *(1+\sin \theta)$
(3) $\left(1-\sin ^{2} \theta\right) \neq t \tan \theta-\cot \theta$

Defn. $f$ and $g$ are algebraically equivalent or A-equivalent, denoted $f \stackrel{A}{=} g$, if one is derivable from the other solely by rational algebraic operations.
e.g. (1) $\left(1-\sin ^{2} \theta\right) \stackrel{A}{=}(1-\sin \theta) *(1+\sin \theta)$
(2)

$$
(1-\sin \theta / \cos \theta) * \sec \theta \nexists(1-\tan \theta) *\left(1+\tan ^{2} \theta\right)
$$

Defn: f and $g$ are trigonometrically equivalent or $T$-equivalent: denoted $f \stackrel{T}{=} g$, if they are equivalent but not $A$-equivalent. This means that substitution is required to derive a T-equivalent expression.
e.g. (1-sin$\theta / \cos \theta) * \sec ^{2} \theta \stackrel{T}{=}(1-\tan \theta) *\left(1+\tan ^{2} \theta\right)$

Defn: A step is an ordered pair of expressions ( $f, g$ ), and is denoted by $f \rightarrow g$. The step is said to be correct if $f \rightarrow g$. It is an $A-s t e p$ or a $\underline{T}$-step according as $f^{A}=g$ or $f^{T}=$.

Notn: Let $e_{0} \rightarrow e_{1} \rightarrow e_{2} \rightarrow \ldots \rightarrow e_{n}$, abbreviated to $e_{0} \rightarrow e_{n}$, represent the sequence of steps $e_{0} \rightarrow e_{1}, e_{1} \rightarrow e_{2}, \ldots e_{n-1} \rightarrow e_{n}$.

Defn: A proof is a chain of steps $e_{0}^{\text {t }} e_{n}$ which derives a target expression $e_{n}$ from an initial expression $e_{0}$. (It is: assumed that $e_{0}$ and $e_{n}$ are appropriate for the problem identity.)

Under our formulation a proof $\mathrm{e}_{0} \stackrel{*}{+} \mathrm{e}_{\mathrm{n}}$ is valid if and only if
(1) each step $e_{i} \rightarrow e_{i+1} \quad(i=0,1, \ldots n-1)$ is correct and
(2) each step $e_{i}^{\rightarrow} e_{i+1} \quad(i=0,1, \ldots n-1)$ is small.

Our primary task in checking a proof is accordingly one of verifying the correctness and smallness of each step in the proof.

Step correctness is a question of expression equivalence. The main difficulty in deciding equivalence is that a given expression can appear in any of an infinite number of equivalent ways. A purely symbolic approach to this problem would suffer not only from inefficiency, but the more serious problem of undecidability as well. Expression equivalence will be discussed in the next section.

A step is said to be small if its correctness is readily verifiable. But what is readily verifiable is rather subjective. The step "l-cot $\theta^{\rightarrow} 1-\cos \theta / \sin \theta^{\prime}$ would probably be regarded as small whereas " $\cot \theta+\tan \theta \rightarrow \csc \theta^{*} \sec \theta^{\prime \prime}$ would probably be considered large (i.e. not small). However it is not obvious whether "l-tan $\theta-\cot \theta+\tan \theta \cot \theta \rightarrow$ $2-1 /(\cos \theta \sin \theta) "$ should be regarded as large or small. Chapter $V$ is devoted to this step-size problem.

## Expression Equivalence

Quite apart from its application in proof-checking, expression equivalence is an important problem in the following.
(1) Answer Recognition: In CAI-based mathematics where a required answer happens to be an algebraic expression, it is clearly impossible for the author to anticipate all possible correct answers. The answer processor should be able to recognise expression equivalence.
(2) Object Code Optimisation:* To produce efficient object codes

[^4]> efficiently some compilers perform common subexpression detection, e.g. in array subscripts, so that the generation of duplicative machine codes can be minimized, avoided or speeded up. For this optimisation to be worthwhile, we may need a very cheap method for deciding equivalence, e.g. a numeric one.
(3) Formula Manipulation: Expressions generated by formula manipulation systems (see [10]) are often very long and unwieldy. Different systems generate different, but equivalent, formulae for the same problem. There is often a need to establish the equivalence of two different formulae.

The expression equivalence (decision) problem has been approached in various ways. Simplification techniques in formula manipulation languages [10] provide an indirect algebraic method. However these have enjoyed only partial success because simplification is an ill-defined concept. As an alternative to simplification B.F. Caviness [8] proposed the well-defined concepts of normal and canonical forms for expressions. We shall now examine briefly Caviness's work.

## The Work of Caviness

Let $\varepsilon$ be a well-defined class of expressions in which the members are formed from a finite set of atomic symbols, a subset of which are variables. The expressions are to be regarded as functions over some domain $D$.

Two expressions $E_{1}$ and $E_{2}$ are identical, written $E_{1} \equiv \mathrm{E}_{2}$ (note ' $\bar{\prime}$ ' not used for equivalence here), if they are the same string of atomic symbols. They are said to be equivalent if for all assignments of values in $D$ to their variables, for which they are defined, they
are equal. We write $E_{1}=E_{2}$ if $E_{1}$ and $E_{2}$ are equivalent.

A computable function $f$ is a normal form for $\mathcal{E}$ if it is a mapping from $\mathfrak{E}$ to $E$ satisfying:(1) $f(E)=E \quad E \varepsilon E$ and (2) $f(E) \equiv 0$ if $\mathrm{E}=0$. If further: (3) $\mathrm{f}\left(\mathrm{E}_{1}\right) \equiv \mathrm{f}\left(\mathrm{E}_{2}\right)$ whenever $\mathrm{E}_{1}=\mathrm{E}_{2}$ then it is an f-canonical form for $\varepsilon$. An expression $E$ is in $f$-canonical form if $f(E) \equiv E$. The normal form, unlike the canonical, is too general to be useful for deciding equivalence. Its requirements (1) and (2) can be trivially satisfied by the mapping: $f(E) \equiv E$, but with $f(E) \equiv 0$ whenever $\mathrm{E}=0$.

In a class for which a canonical form exists, Caviness has shown that expressions can be reduced to the standard normal from $P / Q$ in which $P$ and $Q$ are canonical. This provides an indirect method for deciding equivalence. But this method is not suitable for our problem because our class $Q$ has no canonical form. Even if $R$ has a canonical form, the derivation of the standard form is by no means an easy task.

Richardson (cited by Caviness) has shown that for the class $\mathbb{R}_{2}$, generated by :
(1) the rationals, $\pi$ and $\log _{e} 2$
(2) the variable $x$
(3) the operations + , * and composition
(4) the sine, exponential and absolute functions. the predicate " $E=0$ " for $E$ in $R_{2}$ is recursively undecidable. Caviness has also shown that $R_{2}$ has no canonical form. Note that our $Q$ is a richer class than $\mathbb{R}_{2}$.

A major objection to using a symbolic approach to the equivalence problem is that it would be very inefficient. An expression can appear in far too many distinct forms. A more serious objection however is Richardson's undecidability result which shows that expression equivalence cannot always be resolved symbolically.

While purely algebraic and symbolic techniques are unsuitable, a numeric one can be a very elegant and practical alternative. Numeric methods for deciding equivalence have already been adopted by oldehoeft [52], Martin [44] and others.

One class of expressions considered by Oldehoeft is the $T_{1}-c l a s s$. The expressions are constructed from variables, constants and the following operators and functions: $+,-, *, /$, composition, $\uparrow$ (to an integer power), sin, cos, tan, csc, sec, cot, exp, $r^{x}(r>0), \sinh$, cosh, tanh, csch, sech and coth. Oldehoeft has shown that to test for the equivalence of two $T_{1}$-expressions, it is sufficient to compare their values computed at one random point. The expressions are equivalent if and only if their values are equal. The probability of an incorrect decision in this random evaluation method is zero. The numeric approach can be seen as a direct consequence of the alternative definition for equivalence: two expressions are equivalent over some domain if they are equal at every point of the domain where they are defined.

Oldehoeft's method is applicable to our problem since his class $T_{1}$ includes our class $Q$. However we have developed a more general numeric technique which enables us not only to decide equivalence but also to determine a minimum sufficient set of basic identities for proving an identiy. This set is the consistency set of the identity.

Our technique enables us to distinguish between A-equivalence and T-equivalence. Note that Caviness's technique applies only to A-equivalence.

The Theory of Consistency Sets
We have $Q$ our set of expressions. Let $\mathbb{R}^{\circ}$ be the field of rational functions* in $\underset{\sim}{X}$ with rational number coefficients. ${\underset{\sim}{x}}^{X}$ is the row vector $\left(x_{1}, x_{2}, \ldots 0 . x_{n}\right) * *$. Members of $\mathcal{R}$ will be called $\theta$-expressions and will be said to be in the $\theta$-form. Similarly members of $\mathbb{R}^{\circ}$ will be called $X$-expressions and are in the $x$-form.

Consider the mapping $J$ of $R$ into $\mathbb{R}^{\circ}$ which transforms $\theta$-expressions into $x$-expressions by substituting $x_{1}, x_{2}, \ldots x_{6}$ for any occurrence of $\sin \theta, \cos \theta, \ldots \cot \theta$ respectively. We can denote this mapping by $f(\theta) \xrightarrow{\mathfrak{J}} f^{\circ}(X)$. We shall denote the $X$-form of $f$ under $J$ by $f^{0}$ and the 0 -form of $g^{\circ}$ by $g$, provided $g^{\circ}$ is known.

| e.g. f: $\theta$-form | $\mathrm{f}^{\circ}$ : X -form |
| :---: | :---: |
| 5* $\sec \theta-2 * \sin \theta / \cos \theta$ | $5 \mathrm{x}_{5}-2 \mathrm{x}_{1} / \mathrm{x}_{2}$ |
| 124 | 124 |
| $2-\sec \theta * \csc \theta \uparrow 2$ | $2-x_{5} x_{4}^{2}$ |

The X -form of the basic identities are NOT identities but the rational equations $R-1, R-2, \ldots R-8$ below。 Let $r_{1}^{0}, r_{2}^{0}, \ldots 0$ represent the reference rationals $\left(x_{4} x_{1}-1\right) / x_{1},\left(x_{5} x_{2}-1\right) / x_{2}, \ldots .$. In keeping with our notation $r_{1}$ is $(\csc \theta \sin \theta-1) / \sin \theta$ and so on.

[^5]$r_{1}(\mathrm{X}) \equiv\left(\mathrm{x}_{4} \mathrm{x}_{1}-1\right) / \mathrm{x}_{1}=0 \quad \ldots \mathrm{R}-1 \quad r_{5}^{g}(\underset{\sim}{x}) \equiv\left(\mathrm{x}_{6} \mathrm{x}_{1}-\mathrm{x}_{2}\right) / \mathrm{x}_{1}=0 \quad \ldots \quad \mathrm{R}-5$
$r_{2}(\underset{\sim}{x}) \equiv\left(x_{5} x_{2}-1\right) / x_{2}=0 \quad \ldots R-2(X) \equiv x_{1}^{2}+x_{2}^{2}-1=0 \quad \ldots R-6$
$r_{3}(\underset{\sim}{x}) \equiv\left(x_{6} x_{3}-1\right) / x_{3}=0 \quad \ldots R-3 \quad r_{7}^{0}(\underset{\sim}{x}) \equiv x_{5}^{2}-x_{3}^{2}-1=0 \quad \ldots R-7$
$r_{4}^{0}(\underset{\sim}{x}) \equiv\left(x_{3} x_{2}-x_{1}\right) \cdot x_{2}=0 \ldots R-4(\underset{\sim}{x}) \equiv x_{4}^{2}-x_{6}^{2}-1=0 \quad . \quad R-8$
Consider the corresponding polynomial equations $\mathrm{P}-1, \mathrm{P}-2, \ldots \mathrm{P}-8$. Here the reference polynomials are represented by $p_{1}^{0}, p_{2}^{0}, \ldots p \&$.

| $\mathrm{pi}(\underset{\sim}{x}) \equiv \mathrm{x}_{1+} \mathrm{x}_{1}-1=0$ | . P-1 | $\mathrm{p}_{5}^{0}(\underset{\sim}{\mathrm{x}}) \equiv \mathrm{x}_{1} \mathrm{x}_{2}-\mathrm{x}_{2}=0$ | P-5 |
| :---: | :---: | :---: | :---: |
| $\mathrm{p}_{2}^{\circ}(\underset{\sim}{X}) \equiv \mathrm{x}_{5} \mathrm{x}_{2}-1=0$ | . . P-2 | $\mathrm{p}_{6}^{0}(\underset{\sim}{\mathrm{X}}) \equiv \mathrm{x}_{1}^{2}+\mathrm{x}_{2}^{2}-1=0$ | P-6 |
| $\mathrm{p}_{3}^{\circ}(\underset{\sim}{\mathrm{x}}) \geq \mathrm{x}_{6} \mathrm{x}_{3}-1=0$ | . P-3 | $\mathrm{p}_{7}(\underset{\sim}{x}) \equiv \mathrm{x}_{5}^{2}-\mathrm{x}_{3}^{2}-1=0$ | P-7 |
| $\mathrm{p}_{4}^{0}(\underset{\sim}{x})=\mathrm{x}_{3} \mathrm{x}_{2}-\mathrm{x}_{1}=0$ | . P-4 | $\mathrm{p} 8(\underset{\sim}{\mathrm{x}}) \equiv \mathrm{x}_{4}^{2}-\mathrm{x}_{6}^{2}-1=0$ | . . P-8 |

The reference rationals and polynomials may be taken as functions which map $\mathbb{C}^{n}$ into $\mathbb{C} . *$ For practical purposes we shall take the mapping to be from $\mathbb{R}^{n}$ into $\mathbb{R}$.

Define: $M\left(f^{\circ}\right)=\left\{\underset{\sim}{X} \in \mathbb{C}^{n} \mid f^{\circ}(\underset{\sim}{X})=0\right\}$
$M\left(f^{\circ}\right)$ denotes the solution set of the equation $f^{\circ}(\underset{\sim}{x})=0$ in $\mathbb{C}^{n}$.
Let: $N^{*}=\{1,2,3,4,5,6,7,8\}$

$$
\begin{aligned}
& B i=M\left(r_{i}^{o}\right) \quad i \in N^{*} \\
& A i=M\left(p_{i}^{o}\right) \quad i \varepsilon N^{*} \\
& \left(B=\left\{\bigcap_{i \in N^{\prime}} B i \mid N \subset N^{*}\right\}\right. \\
& A=\left\{\bigcap_{i \in N^{\prime}} A i \mid N \subset N^{*}\right\}
\end{aligned}
$$

$* \mathbb{R}$ and $\mathbb{C}$ denote the fields of complex and real numbers respectively.

Members of $\mathcal{A}$, e.g. Al, AlnA6, A2nA3nA6, will be called sampling sets or S-sets while members of $\mathbb{B}$, e.g. $\mathbb{C}^{n}$, B2nB8, will be called R-sets. The s-sets are algebraic manifolds.* The largest S-set, $\mathbb{C}^{\text {n }}$, corresponds to the empty system of equations while AlnA2n.onA8 is the smallest S -set. This latter set is non-empty since the equations $\mathrm{P}-1, \mathrm{P}-2, \ldots \mathrm{P}-8$ are consistent.

If $S_{1}$ and $S_{2}$ are $S$-sets and $S_{1} c S_{2}$ then we say that $S_{1}$ is an S-subset of $S_{2}$ and that $S_{2}$ is an S-superset of $S_{1}$.A1nA2n...nA8 is an S-subset of every S-set while $\mathbb{C}^{n}$ is an $S$-superset of every S -set. Let $9 *=\{I 1, I 2, \ldots . .18\}$ and $C=\{9 \mid 9 \subset\{*\}$ the set of all subsets of $9 *$. Theoretically there are $2^{8}=256$ subsets. However in $e_{\text {we shall }}$ not distinguish between any two elements $\mathscr{S}_{1}=\left\{I i \mid i \varepsilon N_{1}\right\}$ and $\mathcal{S}_{2}=\left\{I i \mid i \in N_{2}\right\}, N_{1}, N_{2} \subset N^{*}$, if $\bigcap_{i \in N_{1}} B i=\bigcap_{i \in N_{2}} B i$. The elements of $\ell$ will be called consistency sets or C-sets. We represent a C-set by the largest set of basic identities if it is not unique.
e.g. The sets $\{I 3, I 4\},\{I 3, I 5\},\{I 4, I 5\}$ and $\{I 3, I 4, I 5\}$ are not distinguished since $B 3 \cap B 4=B 3 \cap B 5=B 4 \cap B 5=B 3 \cap B 4 \cap B 5$, and are represented by the C-set $\{I 3,14, I 5\}$.

Because our eight basic identities are not independent, there are only 98 distinct C-sets. These are given in Table 4.2 where they are sequenced $0,1,2, \ldots 97$ representing the C -sets $\mathrm{C} 0, \mathrm{Cl}, \mathrm{C} 2, \ldots \mathrm{C} 97$; e.g. Cl8, the C-set $\{I 1, I 2, I 4\}$ is shown as $[1,2,4]$ in the table. Note the empty C-set C 0 which is a C-subset of every C-set, and C97 the

[^6]| 0 | [ ] (EMPTY SET) |
| :---: | :---: |
| 1 | [1] |
| 2 | (2) |
| 3 | [3] |
| 4 | [4] |
| 5 | [5] |
| 6 | [6] |
| 7 | [7] |
| 8 | [8] |
| 9 | [1,2] |
| 10 | [1,3] |
| 11 | [1,4] |
| 12 | [1,5] |
| 13 | [2,3] |
| 14 | [2,4] |
| 15 | [2,5] |
| 16 | [3,4,5] |
| 17 | [1,2,3] |
| 18 | [1,2,4] |
| 19 | [1,2,5] |
| 20 | [1,3,4,5] |
| 21 | [ $2,3,4,5$ ] |
| 22 | $[1,2,3,4,5]$ |
| 23 | $[6,7]$ |
| 24 | [ 6,8 ] |
| 25 | [7,8] |
| 26 | $[6,7,8]$ |
| 27 | [1,6] |
| 28 | [2,6) |
| 29 | [ 3,6 ] |
| 30 | [ 4,6 ] |
| 31 | [ 5,6$]$ |
| 32 | [1,7] |
| 33 | [ 2,7$]$ |
| 34 | [3,7] |
| 35 | [4,7] |
| 36 | [5,7] |
| 37 | [1,8] |
| 38 | [208] |
| 39 | [ 3.8 ] |
| 40 | [ 4,8 ] |
| 41 | [ 5,8 ] |
| 42 | [ $1,6,7]$ |
| 43 | [ $3,6,7)$ |
| 44 | $[5,6,7]$ |
| 45 | $[2,6,8]$ |
| 46 | [ $3,6,8$ ] |
| 47 | $[4,6,8]$ |
| 48 | [1,7,8] |


| 49 | $[2,7,8]$ |
| :---: | :---: |
| 50 | [ $3.7,8$ ] |
| 51 | $[4,7,8]$ |
| 52 | [5,7,8] |
| 53 | $[1,2,6]$ |
| 54 | [ $1,3,6$ ] |
| 55 | [1,4,6] |
| 56 | $(2,3,6]$ |
| 57 | [ $2,5,6$ ] |
| 58 | [1,2,7] |
| 59 | [1,3,7] |
| 60 | [1,4,7] |
| 61 | [1,5,7] |
| 62 | (2,3,7] |
| 63 | [ $2,5,7$ ] |
| 64 | [ $1,2,8]$ |
| 65 | [ $1,3,8$ ] |
| 66 | [1,4,8) |
| 67 | $[2,3,8]$ |
| 68 | [2,4,8] |
| 69 | [ $2,5,8$ ] |
| 70 | [ $3,4,5,6]$ |
| 71 | [ $1,2,3,6$ ] |
| 72 | $[3,4,5,7]$ |
| 73 | [1,2,3,7] |
| 74 | [1,2,5,7] |
| 75 | [3,4,5,8] |
| 76 | [1,2,3,8] |
| 77 | [1.2,4,8) |
| 78 | [1,2,4,6,7] |
| 79 | $[1,3,6,7]$ |
| 80 | [ $1,5,6,7,8$ ] |
| 81 | [ $2,3,4,5,6,7]$ |
| 82 | [2,4,6,7] |
| 83 | [1,2,5,6,8] |
| 84 | [ $1,3,4,5,6,8]$ |
| 85 | [1,5,6,8] |
| 86 | $[2,3,6,8]$ |
| 87 | [2,4,6,7,8] |
| 88 | [1,2,7,8] |
| 89 | [1,3,7,8] |
| 90 | [1,4,7,8] |
| 91 | $[2,3,7,8]$ |
| 92 | [2,5,7,8] |
| 93 | $[3,6,7,8]$ |
| 94 | [1,3,4,5,7] |
| 95 | [ $2,3,4,5,8$ ] |
| 96 | [3,4,5,7,8] |
| 97 | [1,2,3,4,5,6,7,8\} |

C-SET TABLE
Figure 4.2
largest C-set which is a C-superset of every C-set.
We define $C(S)$, the $C$-set of the $S$-set $S$ by $C(S)=\left\{I i \mid \bigcap_{i} A i=S\right\}$, e.g. $C(A 3 \cap A 4)=C(A 3 \cap A 4 \cap A 5)=\{I 3, I 4, I 5\}$. If $S_{1}$ and $S_{2}$ are $S$-sets and $S_{l} C S_{2}$, then $C\left(S_{1}\right) \supset\left(S_{2}\right)$; smaller $S$-sets correspond to larger C-sets and vice versa. The smallest $S-$ set has the largest C-set C97.

A step $f(\theta) \nrightarrow g(\theta)$ is said to hold over a set $W$ if $f^{\circ}(\underset{\sim}{X})=g^{\circ}(\underset{\sim}{X})$ for every $\underset{\sim}{X} \in W, W \subset \mathbb{C}^{n}$, provided both $f^{\circ}$ and $g^{\circ}$ are well defined at $\underset{\sim}{X}$.* If $f(0) \nrightarrow g(\theta)$ holds over $W$, then $f(\theta) \equiv g(\theta)$ will be said to hold over W. If $W$ is also an $S$-set, then the step $f \rightarrow g$ (as well as $f \equiv g$ ) is said to hold on the C-set $C(W)$.

Remark: If $f \rightarrow g$ holds over $S=\bigcap_{i \in N} A i$, then $f^{\circ}(\underset{\sim}{X})=g^{\circ}(\underset{\sim}{X})$ (pwd) is true where $r_{1}^{o}(\underset{\sim}{X})=0(i \varepsilon N)$ is true. In effect this means that $C(S)$ makes $f^{\circ}=g^{\circ}$ (pwd) "consistent" - hence the name consistency set.

## On Appendix B

In Appendix $B$ we derive the three theorems below.
Thm 1: Let $w(\underset{\sim}{X}) \equiv u(\underset{\sim}{X}) / v(\underset{\sim}{X})$ where $u$ and $v$ are relatively prime polynomialsu If a polynomial vanishes on $M(w)$ then it vanishes on $M(u)$. Thm 2: Let $w_{1}, w_{2}, \ldots, w_{k}$ be rational expressions in which $w_{i}=u_{i} / v_{i}$ $(i=1,2, \ldots k), u_{i}$ and $v_{j}(l \leqslant i, j \leqslant k)$ being relatively prime polynomials. Then any polynomial vanishing on $\bigcap_{i=1}^{k} M\left(w_{i}\right)$ also vanishes on $\bigcap_{i=1}^{k} M\left(u_{i}\right)$. Thm 3: Let $w_{1}, w_{2}, \ldots w_{k}$ be rational expressions in which $w_{i}=u_{i} / v_{i}$ ( $i=1,2, \ldots k), u_{i}$ and $v_{j}(1 \leqslant i, j \leqslant k)$ being relatively prime polynomials. If $r$ is any rational expression which vanishes ( $p w d$ ) on $\cap_{i=1}^{M\left(w_{i}\right)}$ then

[^7]$r^{m}=\sum_{i}^{k} s_{i} \cdot W_{i}$ where $m$ is a positive integer and each $s_{i}$ is a $i=1$
rational expression which is not ill-defined all over $M\left(w_{i}\right)$.
Appendix $B$ begins with a brief summary of relevant definitions and basic results in algebraic geometry. The summary includes definitions of rings, ideals and manifolds as well as Hilbert's Nullstellensatz (zero theorem) which states: if a polynomial p vanishes where the polynomials $\bar{u}_{1}, \bar{u}_{2}, \ldots \bar{u}_{k}$ jointly vanish, then $p^{m}=\sum_{i=1}^{k} \dot{v}_{i} \cdot \dot{u}_{i}$ where $m$ is a positive integer and $\dot{v}_{i}(i=1,2, \ldots k)$ are polynomials. All polynomials are in $\underset{\sim}{x}$ and over the complex field $\mathbb{C}$. To prove the three theorems, Appendix B establishes two lemmas first. Lemma 1 states that if $A, B_{1}, B_{2}, \ldots B_{k}$ are irreducible manifolds (see Defn. B•7 in Appendix B) and $C$ is a manifold which covers $A-\left(B_{1} U B_{2} U \ldots B_{k}\right)$ then $C$ covers $A$. This lemma says in effect that, under the given conditions, there is no manifold smaller than $A$ that covers $A-\left(B_{1} u B_{2} \cup \ldots \cdot B_{k}\right)$. Lemma 2 extends this result to the case where $A$ is replaced by a collection of irreducible manifolds which are distinct from $B_{1}, B_{2}, \ldots B_{k}$. The significance of Lemma 2 is that an arbitrary polynomial which vanishes where a rational function $u / v$ vanishes, $u$ and $v$ being relatively prime polynomials, must also vanish where $u$ itself does. This is in fact what Thm 1 is about. Note that $M(u / v)=M(u)-M(v)$ and $M(u)$ and $M(v)$ are expressible as the union of irreducible manifolds (see Res-ll, Appendix B), the irreducible manifolds of $M(u)$ and $M(v)$ being distinct. The conditions of Lemma 2 are therefore satisfied.

Thm 2 is an extension of Thm l. It shows that if a polynomial vanishes on a R-set $\bigcap_{i \in N} M\left(r_{i}^{\circ}\right)$ (i.e. ( $_{i \in N} B i$ ) then it actually vanishes on
the corresponding s-set $\bigcap_{i \in N} M\left(p_{i}^{\circ}\right)$. Consequently there is no need to distinguish between an $R$-set and its corresponding $s$-set when $a$ rational expression vanishes on the $R$-set.

Thm 3 is based on Hilbert's Nullstellensatz and Thm 2. It connects a rational to a set of rationals on whose common zeroes it vanishes by expressing it as a "linear combination" of the rationals in the set. In this relation, viz. $r^{m}=\sum_{i=1}^{k} s_{i} \cdot w_{i}$, we shall say that $r$ is $L$-expressed in terms of $\mathrm{w}_{1}, \mathrm{w}_{2} \ldots \mathrm{~W}_{\mathrm{k}}$. This relationship is non-trivial. A word of explanation is in order.

The rational expressions in $\underset{\sim}{X}$ over a ring form a field and as such every non-zero rational has an inverse. A consequence of this is that given an arbitrary set of rational expressions $R_{1}, R_{1}, R_{2}, \ldots R_{k}$, which are non-zero, we can L-express $R$ in terms of $R_{1}, R_{2}, \ldots R_{k}$, viz. as $R=\underset{i}{\stackrel{k}{=}}{ }_{l} T_{i} \cdot R_{i}$ where $T_{i}=R / k R_{i}$. But this L-expression is trivial since each coefficient $T_{i}$ is ill-defined everywhere on $M\left(R_{i}\right)$. In Thm 3, the coefficient $\mathbf{s}_{i}$ may be ill-defined on $M\left(w_{i}\right)$, but not all over it.

The relevance of Thm 1, Thm 2 and Thm 3 will become clear shortly. Trigonometric Substitution

Suppose $f(\theta) \rightarrow g(\theta)$ is a T-step involving the substitution of say, Il. Let $h$ denote $f-g$. The substitution can be made in any of the permitted variants* of $I 1: \csc \theta \rightarrow 1 / \sin \theta, \csc \theta-1 / \sin \theta \rightarrow 0$, cscesin $\theta-1 \rightarrow 0$ and so on. In general for $\underset{\sim}{X}$ from $\mathbb{C}^{n}, f^{\circ}(\underset{\sim}{X})$ and $g^{\circ}(\underset{\sim}{X})$

[^8]are unequal, i.e. $h^{\circ}(X) \neq 0 .^{*}$ If the substitution is made in the standard form csce $\rightarrow 1 /$ sin $\theta$ as in $\sin ^{2} \theta+\csc \theta \tan \theta \rightarrow \sin ^{2} \theta+\tan \theta / \sin \theta$, then $f^{\circ}(\underset{\sim}{X})=g^{\circ}(\underset{\sim}{X})$ provided $x_{4}=1 / x_{1}$, i.e. $h^{\circ}(\underset{\sim}{X})=0$ on the R-set Bl. By Thm 1 , this means $h^{\circ}(\underset{\sim}{X})=0$ on the $s-$ set $A l$. If the substitution is made in another variant, then $h^{\circ}$ vanishes on the set of zeroes of $\left(x_{1} x_{1}-1\right) / q^{\circ}(\underset{\sim}{x}), * *$ i.e. $p q(\underset{\sim}{X}) / q^{\circ}(\underset{\sim}{X})$, where $q^{\circ}$ is some polynomial relatively prime to $p_{1}^{\circ}$. By Thm $1, h^{\circ}$ also vanishes on the S-set Al. If the substitution is made in several places, employing $k$ distinct forms, then $h^{\circ}$ vanishes on the common zeroes of the corresponding set of $k$ rational expressions $p_{1}^{0} / t_{1}^{0}, p_{1}^{0} / t_{2}^{0}, \ldots p_{1}^{0} / t^{\circ}{ }_{k}$, the $t_{i}^{\circ}(i=1,2, \ldots k)$ being polynomials relatively prime to $p_{1}^{0}$. By Thm 2, $h^{\circ}$ vanishes on the common zeroes of $p_{1}^{0}, p_{1}^{0} \ldots p_{1}^{0}$, which is the $S$-set Al.

In general if $f(\theta) \rightarrow g(\theta)$ is a $T$-step involving the substitution of the identities $I i\left(i \varepsilon N, N \in N^{*}\right)$, in whatever permitted variants, then i.t can be shown by Thm 2, that $h^{\circ}$ vanishes on the $S$-set $\bigcap_{i \in N} A i$. We remind the reader here that when we say $h^{\circ}$ vanishes on the $S-s e t$, it is its numerator polynomial which does and in fact $h^{\circ}$ is illdefined where its denominator polynomial vanishes.

It follows that the $h^{\circ}$ of every correct step vanishes on some Swset. An A-step vanishes on the $S$-set $\mathbb{C}^{n}$. If a step involves the

[^9]substitution of $\mathrm{Ii}(\mathrm{i} \in \mathrm{N})$ then its $h^{\circ}$ vanishes on the $\mathrm{S}-\operatorname{set} \bigcap_{i \in N} \mathrm{Ai}$. However in general the $h^{\circ}$ of an incorrect step does not vanish on any s-set. It may be regarded as an arbitrary rational expression unrelated to any s-set.

The above result relates a step to the $S$-set of the identities it uses for substitution. Thm 3 provides a converse result as we shall see.

As before let $f \rightarrow g$ be a step with $h$ denoting $f-g$. Suppose $h^{\circ}$ vanishes where the rationals $r_{i}^{o}(i \varepsilon N)$ jointly vanish, i.e. $h^{\circ}$ vanishes on $\left(_{i \in N} B i\right.$ (and therefore on $\bigcap_{i \in N} A i$, by Thm I). By Thm $3\left(h^{\circ}\right)^{m} \equiv$ ${ }_{i \in N} s_{i}^{\circ} \cdot r_{i}^{o}$ where $m$ is a positive integer and $s_{i}^{o}$ is a rational expression which is not everywhere ill-defined on Bi. Converting this relation into the $\theta$-form we obtain $h(\theta)^{m} \equiv \sum_{i \in N} s_{i}(\theta) \cdot r_{i}(\theta)$. It follows that if $r_{i}(\theta) \equiv O(i \in N)$, then $h(\theta) \equiv 0$, i.e. $f(\theta) \equiv g(\theta)$. This shows that if we use the relations $r_{i}(\theta) \equiv O(i \in N)$, then the step $f \rightarrow g$ is correct. But $f_{i}(\theta)=O(i \in N)$ are reference identities. What we have in fact shown is therefore that the C-set $C\left(\bigcap_{i \in N} A i\right)$ are sufficient for proving the problem identity $f(\theta) \equiv g(\theta)$.

To recapitulate we have dexived the two results:-
(1) Let $f(\theta)-r g(\theta)$ be a correct step involving substitution for the basic identities $\{I i \mid i \varepsilon N\}, N N^{*}$, then $h^{\circ}$ (where $h$ is $f-g$ )
vanishes on the s-set $\bigcap_{i \in N} A i$.
(2) If $f^{o}-g^{0}$ vanishes on the $S$-set $S$ then the identities of the C-set $C(S)$ are sufficient for proving the identity $f(\theta) \equiv g(\theta)$.
(1) Step: $\sec \Theta \csc \theta \rightarrow \frac{1}{\cos \theta \sin \theta}$

Then $h^{\circ} \equiv \mathrm{x}_{5} \mathrm{x}_{4}-\frac{1}{\mathrm{x}_{2} \mathrm{x}_{1}}$, which vanishes ( pwd ) on B1 $\cap \mathrm{B} 2$, can be expressed as $\frac{1}{x_{1}}\left(x_{5}-\frac{1}{x_{2}}\right)+x_{5}\left(x_{4}-\frac{1}{x_{1}}\right)$, i.e. $\frac{1}{x_{1}} r \&+x_{5} r_{1}$. Thus $\sec \theta \csc \theta-\frac{1}{\cos \theta \sin \theta} \equiv \frac{1}{\sin \theta}\left(\sec \theta-\frac{1}{\cos \theta}\right)+\sec \theta\left(\csc \theta-\frac{1}{\sin \theta}\right)$. This shows that the basic identities $\sec \theta \equiv 1 / \cos \theta$ and $\csc \theta \equiv$ $1 / \sin \theta$ are sufficient for proving that $\sec \theta \csc \theta \equiv \frac{1}{\cos \theta \sin \theta}$.
(2) Step: $(1-\cot \theta)(1-\tan \theta) \rightarrow\left(1-\frac{\cos \theta}{\sin \theta}\right)\left(1-\frac{\sin \theta}{\cos \theta}\right)$.
$h^{0} \equiv\left(1-x_{6}\right)\left(1-x_{3}\right)-\left(1-x_{2} / x_{1}\right)\left(1-x_{1} / x_{2}\right)$ vanishes (pwd) on $B 4 \cap B 5$ and is expressible as $\left(\frac{x_{2}-x_{1}}{x_{1}}\right) r_{4}^{\circ}+\left(x_{3}-1\right) r_{5}^{\circ} . h$ is expressible as $\left(\frac{\cos \theta-\sin \theta}{\sin \theta}\right)\left(\tan \theta \frac{\sin \theta}{\cos \theta}\right)+(\tan \theta-1)\left(\cot \theta-\frac{\cos \theta}{\sin \theta}\right)$. The problem
identity $f \equiv g$ can therefore be proved by using I4 and I5 only.
(3) The identity I7 is derivable from the three identities I2, I4 and I6. In fact $r_{7}^{0}$ which is $x_{5}^{2}-x_{3}^{2}-1$ vanishes on $B 2 \cap B 4 \cap B 6$ and $x_{5}^{2}-x_{3}^{2}-1 \equiv x_{2}\left(x_{3}^{2}+1\right)\left(x_{2} x_{5}+1\right)\left(x_{5}-\frac{1}{x_{2}}\right)+x_{2} x_{5}^{2}\left(x_{3} x_{2}+x_{1}\right)\left(x_{3}-\frac{x_{1}}{x_{2}}\right)+x_{5}^{2}\left(x_{1}^{2}+x_{2}^{2}-1\right)$. i.e. $r_{i}^{9} \equiv x_{2}\left(x_{3}^{2}+1\right)\left(x_{2} x_{5}+1\right) r_{2}^{\circ}-x_{2} x_{5}^{2}\left(x_{3} x_{2}+1\right) r q_{4}+x_{5}^{2} x_{6}^{8}$. This shows the relationship between I7 and I2, I4 and I6.

## C-set of a Step

If $h^{\circ}$ vanishes (pwd) on an S-set then it also does on every of its S-subsets. Correspondingly a step which holds on a C-set also holds on every of its C-supersets. Since there are only 98 s-sets, then for the $h^{\circ}$ of a correct step, there must be a maximal one, $s$ say, on which $h^{\circ}$ vanishes ( pwd ) and such that there is no S -superset of $S$ on which it does. $C(S)$ is then the corresponding minimal C-set on which the step $f \rightarrow g$ holds.

Defn: Let $f \rightarrow g$ hold on a $C$-set $C$, but not on any $C$-subset of $C$. Then C is called a C-set of the step $f \rightarrow g$ (or of $f \equiv g$ ).

A C-set of an identity is a minimum sufficient set of basic identities for proving it. It is minimum in the sense that we cannot prove it by using a proper C-subset of this c-set. An incorrect step does not have a c-set. The C-set of an A-step is the empty C -set Co.

We have used "a" rather than "the" C-set of a step because it is not always unique. Some steps have more than one c-set. An example is $\left(1+\tan ^{2} \theta\right) /\left(1+\cot ^{2} \theta\right) \rightarrow \sin ^{2} \theta / \cos ^{2} \theta$ which has two $C$-sets, viz. $\{I 3, I 4, I 5\}$ and $\{I I, I 2, I 7, I 8\}$. In practice an overwhelming majority of the correct steps have only one c-set. For this reason, we sometimes, if only loosely, talk of "the C-set of a step". The Representative Point Technique

Let $\mathrm{p}^{\circ}(\underset{\sim}{x})$ be an arbitrary polynomial, one that occurs "at random". Then since $p^{\circ}$ is in general not related to any reference polynomial, it is a reasonable assumption that there is a O-probability that $M\left(p^{\circ}\right)$ covers any component (a component is an irreducible manifold) of an $S$-set. Now if a manifold $M_{1}$ does not cover a component $M_{2}$, then their intersection is "negligible" compared to $M_{2}$. In fact the dimension of the components of $M_{1} \cap M_{2}$ is lower than the dimension of $M_{2}$. Given the above assumption, there is an O-probability that $\mathrm{p}^{\circ}(\underset{\sim}{\mathrm{X}} 0)=0$ for $\underset{\sim}{X_{0}}$ sampled randomly from an S -set. This yields the random evaluation criterion: A polynomial vanishes at a random point from an $s$-set $S$ if and only if it vanishes all over $S$. There is an O-probability of the conclusion of this test being wrong.

This test can be extended to a rational expression $r^{\circ}$ since this is expressible as $p^{\circ} / q^{\circ}$ where $p^{\circ}$ and $q^{\circ}$ are relatively prime polynomials. The criterion now reads: $r^{\circ}(\underset{\sim}{x})=0$ for random point $X_{0}$ from $S$-set $S$ if and only if $r^{\circ}$ vanishes on $S$, whenever it is not ill-defined. There is a zero probability of this test being incorrect and an O-probability that the test breaks down due to $\mathrm{r}^{\circ}(\underset{\sim}{\mathrm{X}} 0)$ being ill-defined. This follows if we assume $q^{\circ}$ to be arbitrary. This random evaluation criterion is similar to that of Oldehoeft's, except that his $S-$ set is only $\mathbb{C}^{n}$. We do not adopt this random evaluation test because of two objections: (1) it is not practical to randomly sample a point from an $S$-set and (2) sampling is a timeconsuming process.

As a simple alternative to the above test, we "permanently preselect a random point" $X(S)$ for each $S-$ set $S$ : $\underset{\sim}{X}(S)$ is called the representative point $(R P)$ of $S$. $X(S)$ is selected to satisfy:
(1) $\underset{\sim}{x}(S) \in S$
and
(2) $\underset{\sim}{X}(S) \not A^{\prime} S^{\prime}$ if $S^{\prime}$ is a proper $S$-subset of $S$. Our representative point technique ( $\mathrm{RP} T$ ) then adopts the following criterion: A rational expression $r^{\circ}$ vanishes (pwd) on an $S$-set $S$ if and only if $r^{\circ}(\underset{\sim}{X}(S))=0$. In practice we choose our RPs to be real numbers. To reduce the chance of a breakdown in the test as well as an erroneous conclusion, we give these numbers several decimal figures. This takes advantage of the fact that in practice our expressions have simple integer coefficients. The RPs we have actually used in our experiments are described in Chapter VII.

The RPT gives us a very simple numeric technique for finding
the C-set of a step. In particular the step $f(\theta) \rightarrow g(\theta)$ holds over the sampling set $S$ if and only if $f^{\circ}(\underset{\sim}{X}(S))=g^{\circ}(\underset{\sim}{X}(S))$.

## Simple Illustrations

We show below how we may determine "the" c-set of a step by the RPT. This is however not our adopted approach for $C$-set determination (see Chapter VII). Our aim here is to show the principles involved. Only the essential numeric tests are shown. The RPs are assigned simple values to simplify manual calculations. The underlined numbers in an $R P$ must satisfy the relevant equations. As an example the $R P$ for $A 2 \cap A 7$, viz. $\{2, \underline{1 / \sqrt{2}}, \underline{1}, 5, \underline{\sqrt{2}}, 3\}$ satisfies the equations $x_{5}=1 / x_{2}$ and $x_{5}^{2}=x_{3}^{2}+1$.

| C-set | $\underline{\text { S-set }}$ | Representative Point |
| :---: | :---: | :---: |
| $\emptyset$ | $¢^{\square}$ | $\underset{\sim}{X}{ }_{1}:\{1,2,3,4,5,6\}$ |
| \{13\} | A3 | ${\underset{\sim}{x}}_{2}:\{1,2,3,4,5,1 / 3\}$ |
| $\{I 2, I 4\}$ | A2へ A4 | $\underset{\sim}{x} 3:\{\underline{1}, \underline{2}, \underline{1 / 2}, 4, \underline{1 / 2}, 6\}$ |
| \{ $12, \mathrm{I} 6\}$ | A2ก A6 | ${\underset{\sim}{4}}_{4}:\{3 / 5, \underline{4 / 5}, 1,2,5 / 4,6\}$ |
| $\{12,17\}$ | A2 ${ }^{\text {A } 7}$ | $\underset{\sim}{X} 5:\{2,1 / \sqrt{ } 2, \underline{1}, 5, \underline{\sqrt{2}}, 3\}$ |
| $\{\mathrm{I} 4, \mathrm{I} 6\}$ | A4 $\cap$ A6 | $\underset{\sim}{X_{6}}:\{3 / 5, \underline{4 / 5}, \underline{3 / 4}, 6,7,8\}$ |
| $\{14,17\}$ | A4 ${ }^{\text {A }} 7$ | ${\underset{\sim}{x}}_{7}:\{\underline{2}, \underline{3}, \underline{2 / 3}, 3, \underline{\sqrt{13 / 3}}, 8\}$ |
| $\{16,17\}$ | A6^ A7 | $\underset{\sim}{x} 8:\{3 / 5,4 / 5, \underline{1}, 2, \underline{\sqrt{2}}, 6\}$ |
| $\{I 2, I 4, I 6, I 7\}$ |  | $\underset{\sim}{X} 9:\{\underline{1 / 2}, \underline{\sqrt{3} / 2}, 1 / \sqrt{3}, 5,2 / \sqrt{3}, 3\}$ |

(1) Step: $\tan \theta-\sin \theta / \cos \theta \rightarrow(\tan \theta \cos \theta-\sin \theta) / \cos \theta$
$\mathrm{f}^{\circ}\left(\underset{\sim}{\mathrm{X}}{ }_{1}\right)=3-1 / 4=11 / 4, \mathrm{~g}^{\circ}\left({\underset{\sim}{X}}_{1}\right)=(3 \times 4-1) / 4=11 / 4$
$\therefore f^{\circ}\left({\underset{\sim}{1}}_{1}\right)=g^{\circ}\left(X_{\sim}^{1}\right)$
$\therefore$ step holds over $\mathbb{C}^{n}$ and therefore on the $C$-set $\varnothing$; this has
no C-subset.
$\therefore$ The C-set of the step is $\varnothing$ and we have an A-step.
(2) Step: $(1-\tan \theta) /(1+\tan \theta) \rightarrow(\cot \theta-1) /(\cot \theta+1)$
$\mathrm{f}^{\circ}\left(\underset{\sim}{x} \mathrm{X}_{2}\right)=(1-3) /(1+3)=-1 / 2=(1 / 3-1) /(1 / 3+1)=\mathrm{g}^{\circ}\left({\underset{\sim}{x}}_{2}\right)$
$f^{\circ}(\underset{\sim}{X} 1)=(1-3) /(1+3)=-1 / 2 \neq 5 / 7=(6-1) /(6+1)=g^{\circ}\left(\underset{\sim}{X}{ }_{1}\right)$
The only C-subset of $\{I 3\}$ is $\varnothing$; step holds on $\{I 3\}$ but not
on $\varnothing$. Therefore it is not an A-step and its C-set is \{I3\}.
(3) Step: $(\tan \theta+\sec \theta-1) /(\tan \theta-\sec \theta+1) \rightarrow(1+\sin \theta) / \cos \theta$.

$$
\begin{aligned}
& f^{\circ}(\underset{\sim}{X} g)=(1 / \sqrt{ } 3+2 / \sqrt{3}-1) /(1 / \sqrt{ } 3-2 / \sqrt{3}+1)=\sqrt{3}=(1+1 / 2) /(\sqrt{3} / 2)=g^{\circ}(\underset{\sim}{X}) \\
& f^{\circ}(\underset{\sim}{X}{\underset{\sim}{3}})=(1 / 2+1 / 2-1) /(1 / 2-1 / 3+1)=0 \neq 1=(1+1) / 2=g^{\circ}\left(\underset{\sim}{X}{ }_{3}\right) \\
& \text { f. }{ }^{\circ}\left(\underset{\sim}{X} X_{4}\right)=(1+5 / 4-1) /(1-5 / 4+1)=5 / 3 \neq 2=(1+3 / 5) /(4 / 5)=g^{\circ}\left(\underset{\sim}{X}{ }_{4}\right) \\
& \left.f^{\circ}(\underset{\sim}{X} 5)=(1+\sqrt{2}-1) /(1-\sqrt{2}+1)=\sqrt{2}+1 \neq 3 / \sqrt{2}=(1+2) /(1 / \sqrt{3})=g^{\circ}(\underset{\sim}{X})_{5}\right) \\
& \mathrm{f}^{\circ}\left(\underset{\sim}{\mathrm{X}}{ }_{6}\right)=(3 / 4+7-1) /(3 / 4-7+1)=-9 / 7 \neq 2=(1+3 / 5) /(4 / 5)=g^{\circ}\left({\underset{\sim}{x}}_{6}\right) \\
& \mathrm{f}^{\circ}(\underset{\sim}{\mathrm{X}} 7)=(2 / 3+\sqrt{ } 13 / 3-1) /(2 / 3-\sqrt{ } 13 / 3+1)=(\sqrt{ } 13-1) /(5-\sqrt{ } 13) \neq 1=(1+2) / 3=9^{\circ}(\underset{\sim}{X}) \\
& f^{\circ}(\underset{\sim}{X} 8)=(1+\sqrt{2}-1) /(1-\sqrt{2}+1)=\sqrt{2}+1 \neq 2=(1+3 / 5) /(4 / 5)=g^{\circ}\left(\underset{\sim}{X} X_{8}\right)
\end{aligned}
$$

Thus the step holds on $\{I 2, I 4, I 6, I 7\}$ but not over any of its immediate C-subsets $\{I 2, I 4\},\{I 2, I 6\}, \ldots\{I 6, I 7\}$. This means that "the" C-set of the step is $\{I 2, I 4, I 6, I 7\}$ and this can be shown to be the C-set of the step.

Table 4.3 contains a selection of identities and their C-sets, found with the aid of the C -set search table (Table C.2) described in Chapter VII. Note that identities 7 and 11 have non-unique C-sets. It would be interesting to prove some of the identities in the table and verify that the identities in their C-sets are indeed "necessary" and sufficient.

## Identity

1. $\cos ^{4} A-\sin ^{4} A+1-2 \cos ^{2} A$
2. $(\sin A+\cos A)(1-\sin A \cos A) \equiv \sin ^{3} A+\cos ^{3} A$
3. $\frac{\sin A}{1+\cos A}+\frac{1+\cos A}{\sin A} \equiv 2 \csc A$
4. $\cos ^{6} A+\sin ^{6} A=1-3 \sin ^{2} A \cos ^{2} A$
5. $1-\sin A \equiv(\sec A-\tan A)(1+\sin A)$
6. $\frac{\csc A}{\csc A-1}+\frac{\csc A}{\csc A+1} \equiv 2 \sec ^{2} A$
7. $\frac{\csc A}{\cot A+\tan A} \equiv \cos A$
8. $(\sec A+\cos A)(\sec A-\cos A) \equiv \tan ^{2} A+\sin ^{2} A$
9. $\frac{1}{\cot A+\tan A} \equiv \sin A \cos A$
10. $\frac{1-\tan A}{1+\tan A} \equiv \frac{\cot A-1}{\cot A+1}$
11. $\frac{1+\tan ^{2} A}{1+\cot ^{2} A} \equiv \frac{\sin ^{2} A}{\cos ^{2} A}$
12. $\frac{\sec A-\tan A}{\sec A+\tan A} \equiv 1-2 \sec A \tan A+2 \tan ^{2} A$
13. $\frac{\tan A}{1-\cot A}+\frac{\cot A}{1-\tan A} \equiv \sec A \csc A+1$
14. $(\sin A+\cos A)(\cot A+\tan A)=\sec A+\csc A$
15. $\sec ^{4} A-\sec ^{2} A \equiv \tan ^{4} A+\tan ^{2} A$
16. $\csc ^{2} A-1 \equiv \cos A \csc A$
17. $(1+\cot A-\csc A)(1+\tan A+\sec A) \equiv 2$
18. $\frac{\cot A \cos A}{\cot A+\cos A} \equiv \frac{\cot A-\cos A}{\cot A \cos A}$
19. $\frac{\cos A \csc A-\sin A \sec A}{\cos A+\sin A} \equiv \csc A-\sec A$
20. $\frac{\tan A+\sec A-1}{\tan A-\sec A+1} \equiv \frac{1+\sin A}{\cos A}$

C-set
\{16\}
\{I6\}
$\{$ I1, I6 \}
\{I6\}
$\{I 2, I 4, I 6, I 7\}$
\{I3,I7,I8\}
$\{I 2, I 3, I 7, I 8\} \&$
$\{I 1, I 3, I 4, I 5, I 6\}$
$\{I 6, I 7\}$
$\{I 3, I 4, I 5, I 6\}$
\{I3\}
$\{I 3, I 4, I 5\} \&\{I 1, I 2, I 7, I 8\}$
\{I7\}
$\{$ I3, I7, I8 $\}$
$\{I 1, I 2, I 3, I 4, I 5, I 6, I 7, I 8\}$
\{I7\}
$\{11, I 6\}$
$\{$ I3, I7, I8 $\}$
$\{I 5, I 6\}$
$\{I 1, I 2\}$
$\{I 2, I 4, I 6, I 7\}$

Table 4.3 Identities and Their C-sets

This chapter is an attempt to answer the question: What is a small step? First we shall discuss some of the considerations that might enter into the human analysis of step-size. We shall then introduce the idea of $\Phi$-equivalence and use it to define three basic expression forms: the additive, the multiplicative and the exponential. These forms are then used to describe a schema for defining empirical models for small steps. It will be shown that we can derive smallstep models from this schema which agree well with human analysis. Human data for assessing agreement are obtained by a survey of human analysis of step-size.

## Discussion

A teacher checking a trigonometric proof would usually examine it for completeness, correctness of step and elegance. He is seldom conscious of the question of step-size since in practice students usually show their steps in sufficient detail. In fact in the opinion survey, many of the participants could not understand at first what we meant by a large step and a small step. Perhaps step-size is an artificial problem peculiar to the needs of our trigonometric proof checker, used to assess the acceptability of a proof.

Step-size may be considered as referring to the verifiability of a step. A step whose correctness is obvious or readily verified may be considered small. But what is obvious or readily verified is rather subjective, depending also on the teacher's own ability.

The teacher's assessment is influenced by other factors. His opinion of a student may influence his judgement. He may regard a step from one student as small and an identical step from another as large if he is not convinced that the latter can demonstrate it. The preceding steps of the proof may also influence him. Even the nature of the problem identity may be taken into account. A "trivial" one would be expected to be proved in greater detail than usual.

Although it is subjective, we believe there is a consensus of opinion on step-size. Indeed our survey supports this belief. There would be little basis for developing a proof-checker if teachers do not agree well among themselves.

While it may be desirable for a proof-checker to agree closely with human adjudication, closeness of agreement should not be an overriding factor. The possible harmful effect on the student of a "controversial" decision should be considered. One way of reducing this possibility is to ask the student to show his step in greater detail rather than to declare it large (he might not agree!).

Although incorrect steps can be classified for step-size, we shall confine step-size analysis to the correct steps only.

It was thought at one time that step-size might somehow be directly related to the $C$-set. Large steps could perhaps be associated with certain large C-sets. But such a possibility was soon dismissed when it was found that large steps can have small C-sets and vice versa. A good example is the following :
(1) $\frac{1+\tan \theta-\sec \theta}{\sec \theta+\tan \theta-1}+\frac{1+\sec \theta-\tan \theta}{\sec \theta+\tan \theta+1}$
(2) $\tan \theta+\csc \theta+\sec \theta-\sin ^{2} \theta+\cot \theta+\sec ^{2} \theta-1+\csc ^{2} \theta+\cot \theta \rightarrow$
$\frac{\sin \theta}{\cos \theta}+\frac{1}{\sin \theta}+\frac{1}{\cos \theta}-\left(1-\cos ^{2} \theta\right)+\frac{\cos \theta}{\sin \theta}+\tan ^{2} \theta+\cot ^{2} \theta+1 \frac{1}{\tan \theta}$

The C-sets of (1) and (2) are respectively $\{I 7\}$ and $\{I 1, I 2, \ldots I 8\}$. Yet clearly (1) is large while (2) is small. It is interesting to note the large proportion of students who could not prove the identity associated with the step (1), although it requires only the substitution of 17 .

The two steps above provide a vital insight into the nature of step-size. The first is not obvious as it stands and cannot be broken into substeps. The second, although involving all eight basic identities, can be easily followed because it can be resolved in to the eight substeps: $\tan \theta \rightarrow \sin \theta / \cos \theta, \csc \theta \rightarrow 1 / \sin \theta, \ldots \cot \theta \rightarrow 1 / \tan \theta$, each of which is obvious. The following appears to be a reasonable description of the human analysis of step-size.

Each teacher has his own corpus of primitive steps. These primitive steps are those he regards as being obviously small. When a teacher is analysing a non-primitive step, he will attempt to resolve it into primitive substeps. It will be considered large if and only if such a resolution is not possible.

We shall develop a scheme for empirical models of small steps, based on the above conception of the human step-size analyser. As a preliminary we shall define the $\Phi$-operations and use them to define the three basic expression forms mentioned previously.

## \$-Operations

The rational operations enable a very large number of distinct expressions to be derived from a given expression, in fact all the expressions A-equivalent to it. We wish to consider here a more restricted class, $\Phi$, of rational operations, by excluding certain rational operations. These operations, called the $\Phi$-operations, enable us to derive only a small, finite* number of $\Phi$-derivatives from an expression. They enable us to :
(a) rearrange terms and factors in any order,
(b) add and subtract an arbitrary number of zeroes, and to multiply and divide by, an arbitrary number of l's.
(c) remove or add redundant parentheses and many + or -
(d) collect common terms and factors and
(e) to add, subtract, multiply and divide (provided division is exact) integers.

中 is essentially the set of rules of algebraic operation which follows from the field axioms, the definitions of subtraction, division and indices (powers) together with certain notations. The distributivity axiom is excluded, but arithmetic operations on integers and the collection of common terms and factors are permitted. It should be noted that addition and multiplication are inherent operations of a field. The absence of the distributivity axiom means that the

[^10]important operations of expression expansion and factorisation are excluded from $\Phi$. Thus it is not possible to derive by $\phi$-operations only, $a^{2}+2 a b+b^{2}$ from $(a+b)^{2}$ or $c a+a b$ from $a(b+c)$.

To be more precise, we give below some of the basic rules of (1. We donote expressions by $e, e_{1}, e_{2}, \ldots$, terms by $t, t_{1}, t_{2}, \ldots$, factors by $\mathrm{f}, \mathrm{f}_{1}, \mathrm{f}_{2}, \ldots$ and integers by $\mathrm{n}, \mathrm{m}, \mathrm{n}_{1}, \mathrm{n}_{2}, \ldots$. The words "expressions", "terms" and "factors" are used here in the sense of the BNF definitions in Chapter IV. The rules are written as "f $\rightarrow \mathrm{g}$ " or "f $\rightarrow$ g", where "f $\rightarrow$ g" means that $g$ is derived from $f$ while $" f \leftrightarrow \rightarrow \mathrm{~g}$ " implies the two rules $" \mathrm{f} \rightarrow \mathrm{g}$ " and " $\mathrm{g} \rightarrow \mathrm{f}$ ". The rules written in the unidirectional form are meant to be strictly unidirectional. Thus with the rule $" f^{m} * f^{n} \rightarrow f^{m+n}$ " we can derive $f^{2+3}$ and $f^{5}$ from $f^{3+2}$ but not $f^{1+4}, f^{7-2}, f^{1} * f^{4}$ and $f^{7} / f^{2}$.

If $g$ is derivable from $f$ by $\Phi$-operations then we shall denote this by $\mathrm{f} \rightarrow \mathrm{g}: \mathrm{f} \neq \mathrm{g}$ indicates that g is not a $\Phi$-derivative of f 。

| $t_{1}+t_{2}<-1 t_{2}+t_{1}$ | $\mathrm{f}_{1} * \mathrm{f}_{2} \leftrightarrow \mathrm{f}_{2} * \mathrm{f}_{1}$ |
| :---: | :---: |
| $t_{1}+\left(t_{2}+t_{3}\right) \leftrightarrow\left(t_{1}+t_{2}\right)+t_{3} \leftrightarrow$ | $t_{1}+t_{2}+t_{3}$ |
| $\mathrm{f}_{1} *\left(\mathrm{f}_{2} * \mathrm{f}_{3}\right) \leftrightarrow\left(\mathrm{f}_{1} * \mathrm{f}_{2}\right) * \mathrm{f}_{3} \leftrightarrow$ | $\mathrm{f}_{1}{ } \mathrm{f}_{2} * \mathrm{f}_{3}$ |
| $t+0 \leftrightarrow t$ | f * $\mathbf{l}$ ¢ |
| $0 \leftrightarrow-0$ | $0-t \leftrightarrow-t \leftrightarrow-(t)$ |
| (e) $\leftrightarrow$ e $\leftrightarrow+(\mathrm{e})$ | $t_{1}+\left(-t_{2}\right) \leftrightarrow t_{1}-t_{2}$ |
| $-(-t) \leftrightarrow t$ | $-(t) \leftrightarrow-t$ |
| $-\left(t_{1}+t_{2}+\ldots+t_{n}\right) \leftrightarrow-t_{1}-t_{2}-\ldots-t_{n}$ |  |
| $\mathrm{f}_{1}^{\mathrm{m}} * \mathrm{f}_{2}^{\mathrm{m}} * \ldots * \mathrm{f}_{\mathrm{n}}^{\mathrm{m}} \leftrightarrow\left(\mathrm{f}_{1} * \mathrm{f}_{2} * \ldots\right.$ | $\left.\mathrm{f}_{\mathrm{n}}\right)^{m}$ |
| $\mathrm{f}^{\prime} \leftrightarrow \mathrm{f}$ | $\mathrm{f}^{-\mathrm{n}} \leftrightarrow 1 / \mathrm{f}^{\mathrm{n}}$ |

$\mathrm{f}_{1} / \mathrm{f}_{2} \leftrightarrow \mathrm{f}_{1} *_{\mathrm{f}_{2}^{-1}}$
$f * f * \ldots{ }^{\prime} f \rightarrow f^{m i}$ (m-fold)
$f^{m} f_{f}^{n} \rightarrow f^{m+n}$
$f^{m} / f^{n} \rightarrow f^{m-n}$
$t-t \rightarrow 0$
$\mathrm{f} / \mathrm{f} \rightarrow 1(\mathrm{f} \neq 0)$
$n_{1} * f+n_{2} * f+\ldots+n_{k} * f \quad \rightarrow \quad\left(n_{1}+n_{2}+\ldots+n_{k}\right) * f$
Examples: ( $a, b, c, d$ denote factors, terms or expressions as appropriate)
(1) $3+2-4 \stackrel{\Phi}{\rightarrow} 2+3-4 \rightarrow 5-4 \xrightarrow{\Phi} 1 \stackrel{\Phi}{\ddagger} 5-4$
(2) $\quad((a)) \stackrel{\Phi}{\rightarrow}{ }^{\Phi} \xrightarrow{\Phi}-(-a) \xrightarrow{\Phi}+(a) \xrightarrow{\Phi}(a+0+0)^{1}$
(3) $a-(b-c+d) \stackrel{\Phi}{\rightarrow} a-d-(b-c)$
(4) $\left(a * a * b^{3}\right)^{2} \xrightarrow{\Phi}\left(a^{2} * b^{3}\right)^{2} \xrightarrow{\Phi} b^{6} * a^{4}$
(5) $(a+b)^{3} a^{3}+3 a^{2} b+3 a b^{2}+b^{3}$
(6) $(\mathrm{a}+\mathrm{b}) / \mathrm{c} \Phi \mathrm{a} / \mathrm{c}+\mathrm{b} / \mathrm{c} \Phi(\mathrm{a}+\mathrm{b}) / \mathrm{c}$

## Three Basic Forms

Defn: $\quad \stackrel{(+}{+} \mathbf{i = 1}, t_{i}$, also written as $t_{1}(+) t_{2}(+) \ldots(+) t_{n}$ and $(+)\left\{t_{i} \mid i=1,2, \ldots n\right\}$, stands for the expression $t_{1}+t_{2}+\ldots+t_{n}$ or any of its $\Phi$-derivatives. $\stackrel{(\underset{i=1}{n}}{+} \mathrm{t}_{i}$ is said to be in the additive form and $t_{1}, t_{2}, \ldots t_{n}$ are its additive components or terms.
e.g. Let $t_{1}=a * b / c, t_{2}=(-2 / b)$ and $t_{3}=\left(-c^{*}(b-c)\right)$. Then $\stackrel{3}{(+)} t_{i=1}$ can be $(a * b / c)+(-2 / b)+\left(-c^{*}(b-c)\right)$ or $-2 / b+a * b / c-c^{*}(b-c)$ or $b * a / c-2 / b+c^{*}(c-b)$.
Defn: $\underset{\substack{n \\ i=1}}{\mathrm{n}} \mathrm{f}_{\mathrm{i}}$, also written as $f_{1}(*) f_{2}(*) \ldots(*) f_{n}$ and (*) $\left\{\mathrm{f}_{\mathrm{i}} \mid i=1, \ldots, n\right\}$ stands for the expression $f_{1} * f_{2} * \ldots * f_{n}$ or any expression $\Phi$-derivable
 are its multiplicative components or factors.
e.g. Let $f_{1}=(a+b)$ and $f_{2}=(a-b)$. Then ${ }_{\substack{(*) \\ i=1}}^{2} f_{i}$ can be $(a+b)$ * $(a-b)$ or $(a-b) *(b+a)$ but not $a^{2}-b^{2}$.

Defn: $f(\uparrow) n$ stands for $f \uparrow n$ or any of its $\Phi$-derivatives and is said to be in the exponential form, $n$ being the exponent of $f$. e.g. $\left(2 * a^{2} / b\right)(\uparrow) 3$ can be $2^{3 *} a^{2 * 3} / b^{3}$ and $8^{*} a^{6} / b^{3}$.

## A Schema for Small Steps

We present here a method for formulating empirical models for small steps. A model in this formulation consists of specifications for defining a subset of the set of all correct steps, this subset containing all and only the small steps in the model. Each model contains a set of primitive small steps together with a set of rules for composing small steps from other small steps. These ideas may be formalised as follows :

Let $\Sigma$ be the set of all correct steps, II a set of primitive small steps and $\Omega$ a set of rules for the composition of steps.

Then the set of small steps in the model, $\Sigma^{\circ}(\Pi, \Omega)$, also written as $\Sigma^{\circ}$, is defined by :
(1) $s \in \Pi \Rightarrow \operatorname{se} \sum^{0}$
(2) $s \varepsilon \Sigma^{\circ}$ if $s$ is derived from members of $\Sigma^{\circ}$ by rules of $\Omega$
(3) se $\sum^{\circ}$ if and only if $s \in \sum^{\circ}$ by virtue of (1) and (2) only.
$\Sigma^{\circ}(\Pi, \Omega)$ does not, however, define a small-step model until the set $\quad \pi$ of primitive steps and the set $\Omega$ of step-composition rules are specified. Until then it may be regarded as simply a schema for small-step models.

It can be seen that this formulation is based on our conception of the human analysis of step-size discussed earlier. The set $I$
corresponds to the corpus of primitive steps of a teacher and $\Omega$ is the set of rules he will allow the student to use for composing a small step from other small steps. Together II and $\Omega$ generate the set $\Gamma^{\circ}$ of all the small steps. A teacher whose $\Sigma^{\circ}$ is a proper subset of the $\Sigma^{\circ}$ of another teacher is a stricter judge than the other.

By a careful choice of $\Pi$ and $\Omega$ we can produce a good model for small steps, one which agrees well with human analysis. We have investigated two models, called Model-A and Model-B. Model-B is a modification of Model-A.

Model-A .. A Model for Small Steps
Model-A will be denoted by $\Sigma_{\AA}^{\circ}(I I, \Omega)$ or $\Sigma_{\AA}^{\circ}$ and the corresponding $\Pi$ and $\delta 2$ are subscripted with an 'A'. The specifications for $\Pi_{A}$ and $s_{A}$ are empirical, but they have been chosen to ensure a good model for small steps.

The Set $\mathrm{II}_{A}$
$\mathrm{I}_{\mathrm{A}}$ can be divided into two distinct classes: (l) the primitive A-steps and (2) the primitive T-steps. The primitive A-steps will be defined by their component count. $N(e)$ the component count of an expression e is defined as :
(1) $N(e)=0$ if $e$ is a constant or a trigonometric function.
(2) $N(e \uparrow n)=\left\{\begin{array}{l}N(e) \text { if } e \text { is a constant or if e is a trigonometric } \\ \quad \text { function and } n=0, l \text { or } 2 . \\ N(e)+1 \text { otherwise }\end{array}\right.$
(3) $\left.\underset{\sim}{n\left((+) e_{i}\right.}\right)=n+\sum_{i=1}^{n} N\left(e_{i}\right)$

```
(4) \(N\left(\underset{i=1}{n}\left(e_{i}\right)=n+\sum_{i=1}^{n} N\left(e_{i}\right)\right.\)
e.g. \(N(\sin \theta *(\sec \theta) \uparrow 2 *(1+3 * \cos \theta) \uparrow 3)\)
    \(=3+\mathrm{N}(\sin \theta)+\mathrm{N}((\sec \theta) \uparrow 2)+\mathrm{N}((1+3 * \cos \theta) \uparrow 3)\)
    \(=3+0+N(\sec \theta)+N((1+3 * \cos \theta))+1\)
    \(=4+\mathrm{N}(\sec \theta)+\mathrm{N}(1+3 * \cos \theta)\)
    \(=4+0+2+N(1)+N(3 * \cos \theta)\)
    \(=4+0+2+0+2+N(3)+N(\cos \theta)\)
    \(=4+0+2+0+2+0+0\)
    \(=8\)
```

The component count of a step $f \rightarrow g$ is defined as $N(f)+N(g)$. $N(e)$ gives a rough indication of the size and complexity of the expression e. We define a primitive A-step $f \rightarrow g$ to be one with $N(f)+N(g)<k$. Whether or not an "optimal" value for $k$ exists is not clear, but the closeness of agreement model-A has with human analysis is not very sensitive to variations in the value of $k$, provided it is neither too large nor too small. From our investigation, we have found 20 to be a good, although rather arbitrary, value for $k$. We shall take this to be our value of k .
e.g. (I) $\tan \theta \rightarrow \sin \theta / \cos \theta$ is a $T-s t e p$ and cannot therefore be a primitive A-step.
(2) $\sin \theta(1+\sin \theta) \rightarrow \sin \theta+\sin ^{2} \theta$ is an $A-s t e p$ with a component count of 6 , and is therefore a primitive $A-s t e p$. $(1+\sec \theta) /(\sec \theta \tan \theta+\tan \theta+2 \tan \theta-2 \sin \theta) \rightarrow(1+\sec \theta) /(\sec \theta \tan \theta$ $+3 \tan \theta-2 \sin \theta$ ) is not a primitive A-step since it has a component count of $25(\geqslant 20)$. (It is however a small step in Model-A.)

In Model-A, a primitive T -step must have a singleton C-set,* i.e. one containing only one reference identity. In a primitive $T$-step the reference identity must be substituted in its standard form (as in Table 4.1) or in one of its permitted variants outlined below. Let $E_{l} \rightarrow E_{r}$ be the reference identity substituted in the standard form. Then :
(1) $f \rightarrow g$ is a permitted variant if $f-g$ or $g-f$ is $\Phi^{\prime}$-derivable** from $E_{\ell}-E_{r}$.
(2) $f \rightarrow g$ is a permitted variant if $f / g$ is $\Phi^{\prime}$-derivable from $f^{\prime} / g^{\prime}\left(g^{\prime} \neq 0\right)$, and $f^{\prime} \rightarrow g^{\prime}$ is itself a permitted variant.
(3) $f \rightarrow 0$ is a permitted variant if $f / g \rightarrow 0$ is a permitted variant.
e.g. (1) $\tan \theta+\cot \theta \rightarrow 1 /(\sin \theta * \cos \theta)$ has the $C-$ set $\{I 3, I 4, I 5, I 6\}$ and cannot be a primitive T-step.
(2) $1 / \sin \theta \rightarrow \csc \theta, \csc \theta-1 / \sin \theta \rightarrow 0, \sin \theta \rightarrow 1 / \csc \theta,(\csc \theta \cdot \sin \theta-1) / \csc \theta \rightarrow 0$ and $\csc \theta_{0} \sin \theta-1 \rightarrow 0$ are primitive $T-s t e p s$, being permitted variants of the standard form $\csc \theta \rightarrow 1 / \sin \theta$.
(3) Permitted variants of $\sin ^{2} \theta+\cos ^{2} \theta \rightarrow 1$ include $\sin ^{2} \theta-1 \rightarrow-\cos ^{2} \theta$ and $\left(1-\cos ^{2} \theta\right) / \sin ^{2} \theta \rightarrow 1$.

## The Set $\Omega_{A}$

$\Omega_{A}$ consists of the following rules for step-composition :
$w_{1}:$ from $e_{i} \rightarrow e_{i}^{\prime}(i=1,2, \ldots n)$ derive $\underset{i=1}{(+)} e_{i} \rightarrow \underset{i=1}{(+)} e_{i}^{\prime} ;$
$w_{2}=\operatorname{from} e_{i} \rightarrow e_{i}^{\prime}(i=1,2, \ldots n)$ derive $\underset{i=1}{\left(\frac{n}{n}\right)} e_{i} \rightarrow \underset{i=1}{\left(\frac{n}{*}\right)} e_{i}^{\prime} ;$

[^11]$w_{3}:$ from $e \rightarrow e^{\prime}$ derive $e(\uparrow) m \rightarrow e^{\prime}(\uparrow) m$ ( $m$ an integer);

$W_{5}:$ from $e \rightarrow e^{\prime}$ derive $e^{\prime} \rightarrow e,-e \rightarrow e^{\prime}, e-e^{\prime} \rightarrow 0, e / e^{\prime} \rightarrow 1\left(e^{\prime} \neq 0\right)$ and reciprocal of $e \rightarrow$ reciprocal of $e^{\prime}$.

The rule $w_{1}$ in effect says that if each of the steps $e_{i} \rightarrow e_{i}^{\prime}$ ( $i=1,2, \ldots n$ ) is small then so is any step of the form $\underset{i=1}{n}+e_{i} \rightarrow(+) e_{i}^{\prime}$. To illustrate, if $1-\cos ^{2} \theta \rightarrow \sin ^{2} \theta$ and $\tan \theta \rightarrow \sin \theta \sec \theta$ are small then so are, say, $1-\cos ^{2} \theta+\tan \theta \rightarrow \sin ^{2} \theta+\sin \theta \sec \theta$ and $1+\left(\tan \theta-\cos ^{2} \theta\right) \rightarrow$ $\sin \theta \sec \theta+\sin ^{2} \theta$, since they have the form $\left(1-\cos ^{2} \theta\right)(+) \tan \theta \rightarrow$ $\sin ^{2} \theta(+) \sin \theta \sec \theta$. The interpretation of $w_{2}, w_{3}$ and $w_{5}$ should now be obvious. W4 perhaps requires some elaboration and this is best done by an example.

Suppose $\sin \theta \sec \theta \rightarrow \tan \theta$ and $\sin \theta \sec ^{2} \theta \rightarrow\left(1+\tan ^{2} \theta\right) / \csc \theta$ are small. Then $\sin \theta\left(\sec \theta+\sec ^{2} \theta\right) \rightarrow \tan \theta+\left(1+\tan ^{2} \theta\right) / \csc \theta$ is small since it has the form $\sin \theta(*)\left(\sec \theta(+)\left(\sec ^{2} \theta\right) \rightarrow \tan \theta(+)\left(1+\tan ^{2} \theta\right) / \csc \theta\right.$.

In the same way $(\tan \theta+\sec \theta) / \sec \theta \rightarrow \sin \theta+1$ may be regarded as being derived from $\tan \theta / \sec \theta \rightarrow \sin \theta$ and $\sec \theta / \sec \theta \rightarrow 1$ using the composition rule $\mathrm{w}_{4}$.

By a composite application of the step-composition rules we can obtain small steps of considerable complexity from very simple ones. $(1+\sec \theta) /(\sec \theta \tan \theta-2 \sin \theta-\tan \theta) \rightarrow(1+1 / \cos \theta) /(1 / \cos \theta * \sin \theta / \cos \theta-2 \sin \theta-$ $\sin \theta / \cos \theta)$ is a fairly complex step built up from the "irreducible" steps: $1 \rightarrow 1, \sec \theta \rightarrow 1 / \cos \theta, \sec \theta \rightarrow 1 / \cos \theta, \tan \theta \rightarrow \sin \theta / \cos \theta, 2 \rightarrow 2, \sin \theta \rightarrow \sin \theta$ and $\tan \theta \rightarrow \sin \theta / \cos \theta$.

To test for the use of the step-composition rules $w_{1}, w_{2}, w_{3}$ and $w_{4}$ we need to decompose a step into its component substeps. We call this process substep resolution. Each of the rules has the corresponding resolution indicated below.
 with $e_{i} \equiv e_{i}(i=1,2, \ldots n)$ then $e_{i} \rightarrow e^{\prime}{ }_{i}(i=1,2, \ldots n)$ are substeps.
(2) Multiplicative Resolution: If a step is expressible as $\underset{i=1}{n}(\star) e_{i} \rightarrow$ $\underset{\substack{(*) \\ i=1}}{\left({ }^{n}\right)}{ }_{i}$ with $e_{i} \equiv e_{i}^{\prime}(i=1,2, \ldots n)$ then $e_{i} \rightarrow e_{i}^{\prime}(i=1,2, \ldots n)$ are substeps.
(3) Exponential Resolution: If a step is expressible as $e(\uparrow) m \rightarrow$ $e^{\prime}(\uparrow) m$ with $e \equiv e^{\prime}$ (or $\left.e \equiv-e^{\prime}\right)$ then $e \rightarrow e^{\prime}$ (or $e \rightarrow-e^{\prime}$ ) is a substep.
(4) Factored Resolution: If a step is expressible as $f(*) \underset{i=1}{n} \underset{i}{n} \quad e_{i} \rightarrow$ $\stackrel{n}{(+)} g_{i=1}$ with $f(*) e_{i}=g_{i}(i=1,2, \ldots n)$ then $f(*) e_{i} \rightarrow g_{i}(i=1,2, \ldots n)$ are substeps.

In analysing a step there are two basic approaches that we can adopt. One is to check a step or substep for primitiveness (including the use of $\mathrm{w}_{5}$ ) first and performing substep resolution only when this test fails. The rationalé here is to avoid unnecessary resolution on a step when it is already primitive. Thị is especially important for the primitive A-steps since they are often resolvable.

The second approach is to resolve a step as far as possible until every derived substep is irresolvable. These substeps are then tested for primitiveness. In this approach we economise on the tests for primitiveness. It should be noted that sometimes a step
is not uniquely resolvable since at each stage of substep resolution more than one kind (multiplicative, additive, factored) of resolution may be possible.

With either approach we end up with two possibilities. Either (1) we have a resolution into primitive steps only or (2) it is not possible to resolve the step into primitive steps only. We conclude that the step is small if case (l) prevails and that the step is large in case (2).

Whether the first approach is preferable to the second or not depends on the type of expressions normally encountered as well as the relative costs of testing for primitiveness and performing substep resolution. However these two approaches represent extremes between which intermediate approaches are possible.

Model-A has not yet been implemented. However, its precursor, Model-O has already been written as a FORTRAN program called Super-2 and this is briefly described in Chapter VII. Model-o has much in common with Model-A, differing from it mainly in the following :
(1) all A-steps are primitive;
(2) factored resolution is not allowed;
(3) resolution is done at the primary level only (see Chapter VII);
(4) the criteria for primitive $T-s t e p s$ in Model-A are approximated by numeric ones (see description of Super-2).

Super-2 can be modified quite easily to implement Model-A, although the programming effort required would be substantial.

The criteria for primitive $T$-steps would be rather messy to implement because of the number of permitted variants to be considered.

The unwieldiness of the definition of primitive T-steps in Model-A led us to the alternative definition: A T-step is primitive if and only if it has a singleton $C$-set and a component count not exceeding 5. This definition will be very cheap to implement. It will also be found to be a good empirical criterion. We shall designate as Model-B this new model derived from Model-A by this alternative definition for primitive T-steps.

Adequacy of Model-A and Model-B
The adequacy of a given model can be gauged by comparing its analysis with the corresponding human analysis. The necessary comparative data can be generated by choosing (1) a sample of steps and (2) a sample of human judges who are required to express their opinions on the size of each sample step. The opinion data obtained in this way may be treated as a sample of human analysis to be compared with the corresponding analysis in the model.

Table C. 3 shows the 207 steps we have chosen as our sample. These steps have been generated from the expressions contained in the sixteen proofs shown in the same table. Each proof $e_{1} \rightarrow e_{2} \rightarrow \ldots \rightarrow e_{n}$ generates the $\binom{n}{2}$ steps $e_{i} \rightarrow e_{j}(1 \leqslant i<j \leqslant n)$. In the table, step $e_{i} \rightarrow e_{j}$ is shown as $I$ rt J.

Although we could have chosen our sample steps to reflect more realistically the kind of steps TPS would normally expect we have not done this. Such a sample might fail to show up adequately any
serious weakness our models may have. We want our sample steps to cover a rich variety of step-sizes so that our models may be subjected to a severe test.

Our sample of human judges consists of fourteen students and teachers familiar with elementary trigonometry. They are designated HO-1, HO-2, .. HO-14. Table C.l shows their expressed opinions on the sample steps with the entries 'O' and '1' indicating 'small' and 'large' respectively. The same table also displays the corresponding data for six machine-related opinions which we designate MO-1, MO-2; .. MO-6. MO-1, MO-2 and MO-3 are from three variants of Model-O, and for them we enter algebraic steps as '2' rather than '0'.

The entries for MO-4 represent the analysis of Model-A performed by hand simulation. MO-5 does not represent any small step model. Its data are assigned by hand to ensure the best possible agreement with the available human data. Each entry is 0 or 1 whichever has the largest number of agreements with the corresponding human entries. The data for MO-6 are assigned at random.

The figures under AGREEMENT COUNT refer to the number of matches the entries of the $\mathrm{MO}-\mathrm{i}(i=1,2, . .6)$ have with the corresponding human entries. As an example MO-2 has an agreement count of 6 for step 34 while MO-5 has a count of 8.

A hand-simulation of Model-B has also been performed on the sample steps. The results have not been separately represented in the table because (for our sample steps) they happen to coincide with the analysis of Model-A. Thus MO-4 also represents Model-B.

## Evaluating Agreement

One difficulty in evaluating the agreement between a machine opinion and the human opinions is the apparent lack of a standard method for interpreting the data. In view of this we used the intuitive index given by the percentage of agreement counts between a machine opinion and the human opinions.

|  |  |  | но | HO AGRE | MENT |
| :---: | :---: | :---: | :---: | :---: | :---: |
|  |  |  |  | COUNT | PERCEN' |
|  |  |  | НО- 1 | 2342 | 87.03 |
|  |  |  | HO- 2 | 2332 | 86.66 |
| MO | VS HO AG | EMENT | HO- 3 | 2300 | 85.47 |
|  | COUNT | PERCENT | HO- 4 | 2334 | 86.73 |
| MO-1 | 2275 | 78.50 | HO- 5 | 2366 | 87.92 |
| MO-2 | 2333 | 80.50 | HO- 6 | 2388 | 88.74 |
| MO-3 | 2305 | 79.54 | HO- 7 | 2392 | 88.89 |
| MO-4 | 2607 | 89.96 | HO- 8 | 2410 | 89.56 |
| $\mathrm{MO}_{\mathrm{O}-5}$ | 2655 | 91.61 | HO-9 | 2386 | 88.67 |
| MO-6 | 1337 | 46.14 | HO-10 | 2242 | 83.31 |
|  |  |  | HO-11 | 2396 | 89.04 |
|  |  |  | HO-12 | 2410 | 89.56 |
|  |  |  | HO-13 | 2382 | 88.52 |
|  |  |  | HO-14 | 2360 | 87.70 |
|  |  |  | MEAN | 7.70 | D DEV = |

## Table 5.1 Agreement Percentages

Table 5.1 gives the total agreement count of each machine opinion (under "MO VS HO AGREEMENT") as well as the corresponding percentage agreement on the base of $2898(=14 \times 207)$. The table also gives (under "HO VS HO AGREEMENT") the agreement count and percentage of each HO. Here the count is taken over the matches each HO enjoys with the remaining thirteen HOs and the percentage is computed on the base of 2691 ( $=13 \times 207$ ). The HO-VS-HO agreement percentage has the average value $87.70 \pm 1.74 \%$. The small standard deviation indicates a good agreement among the human judges, a state of affairs we expect.

The percentage agreement 46.14 \% for MO-6 gives the figure for purely random data, and serves as a useful "lower bound" for the agreement percentage. The figure $91.61 \%$ for MO-5 gives the "best possible" figure for the given human data. The value for MO-4 is $89.96 \%$ is very close to the highest possible value and is better than the best figure for the HOs, viz. $89.56 \%$ for $H O-12$. It is also higher than the value $87.70 \pm 1.74 \%$. The figures for $M O-1, M O-2$ and MO-3, though lower than for MO-4 and the HO-VS-HO values, are respectably higher than the one for the random data MO-6. The "poor" agreement for MO-1, MO-2 and MO-3 are mainly because they are more "forgiving" especially in treating all A-steps as small.

Because we do not know the underlying statistical behaviour of our opinion data we have not been able to make precise statements on them. We could not say that the agreement between MO-4 and the human judges is significantly better than that which exists between HO-12 and the remaining judges. Nevertheless because of the size of our sample (207 steps and 14 judges) we feel justified in claiming that Model-A and Model-B agree well with the human judges, and in fact better than they do among themselves. Thus Model-A and Model-B are indeed adequate models for small steps.

## Chapter VI

## Assisting Proof Construction

In this chapter we shall consider how we can assist the student in his proof. We shall regard as a form of assistance any information that can guide him to construct an acceptable proof.

A major source of assistance already exists in the proofchecking process. In informing the student that his step is incorrect $T P S$ enables him to locate his error quickly and also prevents him from propagating the error. The proofchecker can also be modified to provide an identity-checking service. Whenever the student is uncertain about an identity, such as a basic one, he can enter it for verification.

There are more direct forms of assistance which we shall discuss shortly. But first we introduce a few more terms. We have the usual initial and target expressions $e_{o}$ and $e_{n}$ and a proof for it has the form $e_{o}$ 李 $e_{n}$. Let $e_{o} \stackrel{\star}{+} e_{i}$ be the current stage of a proof. Then we have $e_{i}{ }^{\rightarrow} e_{n}$ as the current residual step or residual. We shall denote the $j^{\text {th }}$ residual $e_{j} \rightarrow e_{n}$ by rsd-j. The aim of a proof can be considered to be one of whittling down the current residual into one which is a small step.

TPS can be designed to render the following forms of assistance :-
(1) To present the student with a set of basic identities
which are relevant for completing his proof. This set can be the $c-s e t$ of the current residual or an appropriate subset of it. If the $C-s e t$ is empty then the student may be advised that no further substitutions are required.
(2) To provide the student with a "next-step" $e_{i} \rightarrow e_{i+1}$ to enable him to continue. To be useful this next-step must bring him closer to the target expression $e_{n}$.
(3) To locate the incorrect substeps in a step. This can be useful when the step itself is rather large and complex and the incorrect parts are not obvious from inspection. This can be effected with the help of substep resolution. To suggest a promising proof strategy. As a case in point this is useful when the student cannot get started. This often happens when the direct derivation of one side from the other does not appear to be feasible. On the other hand the student may also be discouraged from pursuing any further a strategy that is not promising. To give the student timely warning that his proof is "going astray". This happens when the last expressions derived .. $e_{i-2}, e_{i-1}{ }^{\prime} e_{i}$ are getting further and further away from the target expression.
(6) To complete the student's partial proof from where he gives up. This may be preferable to giving him an entirely fresh proof in that he has the benefit of seeing how he could have completed the proof himself. In trying to provide the above forms of assistance TPS
faces one major problem. This the lack of a sensitive "measure" of the "distance" between two expressions. This makes it rather difficult to automatically construct a next step, to determine whether the proof is straying - in fact makes it difficult to generate a proof automatically. Much of this difficulty can be overcome with the aid of a companion proof $E_{o} \nrightarrow E_{m}$ for the problem identity $e_{o} \equiv e_{n}$ : We assume that E and eo are identical as are $E_{m}$ and $e_{n}$. This means that we are assuming that it is of the same strategy as the student's proof. We also assume that it is a good proof in that $E_{0}, E_{1}, E_{2}, \ldots$ are progressively closer to $E_{m}$.

By comparing $e_{i}$ against $E_{o}, E_{1}, E_{2}, \ldots$ in turn (we can start with an expression later than Eo if we already know the stage the student's proof last "reached") we can find one, Ej say, which is not the same as ei but which is closest to it on the target expression side of $e_{i}$. Then useful basic identities for the student may be taken as the c-set of $e_{i} \rightarrow E_{j}$ or of $e_{i} \rightarrow E_{j+1} \ldots$ or of $e_{i} \rightarrow E_{m}$ whichever is most appropriate. If the current residual $e_{i} \rightarrow E_{m} h a s$ an empty C-set then it is algebraic. If $e_{i} \rightarrow E_{j}$ is a small step, then it can be presented to the student as a next step. If it is not small then it is still nearer from ef than the target expression and the student may be prompted to derive Ej first, thus bringing him a stage closer to $E_{m}$. If the student abandons his proof then TPS may complete it as $e_{i} \rightarrow E_{j} \rightarrow E_{j+1} \rightarrow$ ... $\rightarrow E_{m,}$ filling in an intermediate step or two should
$e_{i} \rightarrow E_{j}$ be large.
If the student's proof is diverging from the target expression, then $e_{i}$ will be further away from it than $e_{i-1}$ and/or $e_{i-2}$ and/or $e_{i-2}$ and so on. However because we lack a sensitive measure for distance, we may fail to discover the divergence solely by comparing $e_{i}, e_{i-1}, e_{i-2}, \ldots$ with $E_{m}$ since when two expressions are sufficiently remote from a third, it might be difficult to find out which of them is nearer to the third. Therefore the comparison may have to be made against some other intermediate expressions of the companion proof.

One way of making a companion proof available is to store it with the problem identity. An obvious disadvantage here is that TPS must confine its assistance to those problem identities for which comparison proofs have been prepared. Another disadvantage is that the student may use a strategy different from that of a companion proof; it is not easy to modify a companion proof to suit the student's strategy. Because of these objections we propose instead to incorporate an automatic proof construction capability into TPS. This would be more flexible, and powerful and obviates any need to restrict the student's proofs.

Problem-Solving Systems
Automatic problem-solving and theorem-proving are already important areas of investigation in artificial intelligence. In theorem-proving most of the effort has
been theoretical in nature. The works in problem-solving have been more practical. Examples can be found in Newell et al. [51], Slagle [66] and Quinlan and Hunt [57].

Surprisingly little work has been done in the area of trigonometry, possibly because the problem appears to be trivial. Johnson and Holden [35] and Newell et al. [51] have dealt briefly with the subject. In both cases trigonometry has been only an area of application for a more general system. We shall discuss only the work of Johnson and Holden because they have treated the subject more fully.

In Johnson and Holden's system an identity is converted into a standard form before it is proved. This makes it very much easier to prove. In the standard form, trigonometric functions are oxdered, parentheses removed, negative terms transposed and denominators eliminated by rationalisation and cross-multiplication. As an example the standard form for $\frac{\tan \theta-\sin 0}{1-\cos \theta} \equiv 1+\sec \theta$ is $\sin 0 \tan \theta+\cos \theta+\cos \theta \sec \theta \equiv \sec \theta+1$. This approach is however unsuitable for TPS because the proofs produced are stereotype. Johnson and Holden were mainly concerned with establishing the correctness of an identity, and not the elegance of its proof. But the correctness of an identity can be determined very trivially in TPS using our numeric test. In fact Johnson and Holden could have simplified their task even further by expressing all trigonometric functions in terms of $\sin \theta$ and $\cos \theta$. In
this way the only substitution that may be required would be for $\sin ^{2} \theta+\cos ^{2} \theta \equiv 1$.

Most problem-solving systems adopt a heuristic search approach. A heuristic is a problem-solving strategy with a good chance of success but success is not guaranteed. It involves trial-and-error search of profitable paths.

Ernst and Newell [20] regard a heuristic search as consisting of operators and objects. An operator may or may not be applicable to a given object. Applied to an object it produces another object. A heuristic search problem has the form:

Given: an initial situation represented as an object, a desired situation represented as an object, a set of operators.

To Find: a sequence of operators that will transform the initial situation into the desired situation.

To solve a problem is to search the solution tree defined by the initial situation and the operators for a path from the initial situation to the goal situation. For instance

If the desired situation is ag and the initial situation $a_{0}$ and $\varnothing_{1}, \varnothing_{2}, \varnothing_{3}, \ldots$ are operators (see figure on the right) then the sequence of operators

$\varphi_{3} \cdot \varphi_{2}, \varnothing_{8}, \varphi_{9}$ is a solution since $\varnothing_{9}\left(\varnothing_{8}\left(\varphi_{2}\left(\varphi_{3}\left(a_{0}\right)\right)\right)=a_{8}\right.$. Applied to our problem the objects are trigonometric expressions while the operators are the various rational algebraic operations and trigonometric substitutions.

An important requirement in heuristic problem-solving is a criterion for solution progress so that the search can be guided efficiently and effectively. GPS [20] employs means-ends analysis to guide the tree search. This is done by taking the difference between what is given and what is desired, the difference indicating some discrepancy to be removed. The problem may also be broken down into simpler subproblems. Differences are removed progressively with the aid of a table-of-connections which associates with cach difference type a list of operators capable of reducing the difference.

## Heuristic Generation of Trigonometric Proofs

To develop a heuristic generator of trigonometric proof , we must first of all decide on our choice of indicators of expression differences. This choice determines our criteria for proof progress as well as our choice of operators for removing the differences indicated. Preferably the types of differences chosen should be:
(1) sensitive to changes in the difference; and
(2) simple and cheap to compute.

We propose the following indicators of difference between two expressions $f$ and $g$ :
(1) the resolvability of $f \rightarrow g$ into substeps,
(2) the $C-s e t$ of $f \rightarrow g$,
(3) the primitiveness of $f \rightarrow g$,
(4) the presence of a latent structure (q.v.) in $f \rightarrow g$. We shall now examine our criteria for progress. Let
$e_{i} \rightarrow e_{n}$ be the current residual and $e_{i+1} \rightarrow e_{n}$ the next residual. The new step $e_{i} \rightarrow e_{i+1}$ will be regarded as having made progress if any of the following happens:
(1) $e_{i} \rightarrow e_{n}$ is not resolvable but $e_{i+1} \rightarrow e_{n}$ is,
(2) the $C$-set of $e_{i+1} \rightarrow e_{n}$ is a proper subset of the $C-s e t$ of $e_{i} \rightarrow e_{n}$,
(3) $e_{i} \rightarrow e_{n}$ is not primitive but $e_{i+1} \rightarrow e_{n}$ is,
(4) $e_{i} \rightarrow e_{n}$ has no latent structure but $e_{i+l} \rightarrow e_{n}$ 'has. Unlike proof-checking, in which we need to be concessive, we will have a stricter requirement for primitiveness. It will be similar to that in Model-B except that for a T-step to be primitive, tts component count must be less than 5, while primitive $A-s t e p s$ should not have a count exceeding 10 . The above criteria reflects our conception of the proof process as one of removing the differences that exist between two equivalent expressions. There are two kinds of differences, algebraic or $A-d i f f e r e n c e s ~ a n d ~ t r i g o n o m e t r i c ~ o r ~ T-d i f f e r e n c e s . ~$ The T-differences are represented by the $C-s e t$ of the expressions. The $A-d i f f e r e n c e s ~ r e f e r ~ t o ~ s t r u c t u r a l ~ d i s s i m i-~$ larity. When a step is resolvable it indicates some structural
similarity that can be used to break it into smaller substeps. A latent structure can be used to guide substitution.

To effect the above forms of proof progress we have the following classes of operations :
(1) substep resolution,
(2) C-set reduction,
(3) algebraic manipulation, and
(4) latent structure probing.

## Substep Resolution

If the current residual $e_{i} \rightarrow e_{n}$ is resolvable, then the problem of proving $e_{i} \equiv e_{n}$ can be converted into the problem of proving the "subidentities" corresponding to the substeps. This latter problem is normally very much simpler than the original one. For this reason we shall treat resolution as one of the most important heuristics for proof generation.

An irresolvable step may become resolvable after suitable algebraic manipulation and/or trigonometric substitution. The four types of resolution may be tried in turn as appropriate and as required. The practical problems of resolution are considered in the next chapter.

## C-set Reduction

This is done by substituting for basic identities belonging to the $C-s e t$ of the current residual. The substitution process is not an easy one. Various algebraic manipulations may have to be attempted first before substitution is
possible. This is because the functions, corresponding to an identity to be substituted for, may occur in a form not favourable for substitution. As an example we can substitute for I7 in $\left(\sec ^{2} \theta-1\right) / \sin \theta \equiv \tan ^{2} \theta / \sin \theta$ but not in $\frac{1+\tan \theta-\sec \theta}{\sec \theta+\tan \theta-1} \equiv \frac{1+\sec \theta-\tan \theta}{\sec \theta+\tan \theta+1}$ as it stands. Even when a favourable situation exists, there may be several alternatives for substitution and many trial-and-error efforts may have to be made before the basic identity being substituted for can be removed from the $C-s e t$. Even when a substitution is done correctly, C-set reduction may not occur. This happens when further substitutions for the same identity are required, often $1 n$ conjunction with some algebraic manipulation.

To expedite the $C-s e t$ reduction process we suggest the following guidelines :-
(1) Attempt the elimination of one basic identity at a time.
(2) Attempt removing the identities in the order II,I2,I3,.. I7,I8. This means trying for the non-Pythagorean ones first - these are simplex to eliminate than the Pythagoreans. It should be understood that we try only for members of the $C-s e t$.
(3) To remove Il, replace $\csc \theta$ by $1 / \sin \theta$ rather than $\sin \theta$ by $1 /$ csce. Similar remarks for $I 2, I 3, I 4$ and $I 5$. For last two, replace $\tan \theta$ by $\sin \theta / \cos \theta$ and $\cot \theta$ by $\cos \theta / \sin \theta$ consistently.
(4) When C-set contains I3,I4,I5, and they have not been removed individually, then remove them together by substituting for $I 4$ and I5 only.

If a step is sparse* with respect to the c-set express
all functions in terms of $\sin \theta$ and $\cos \theta$.

## Algebraic Manipulation

As we have mentioned earlier, algebraic manipulation (AM) may make a step resolvable or favourable for substitution. For our work, we restrict our AM to a small repertoire of algebraic operations such as the simplification, rationalisation, simple factorisation and expansion of expressions. We have chosen only those useful operations which are relatively cheap to apply. Thus although a much more general factorisation capability than we have would be very useful for substep resolution, we have not included it because it is relatively costly to implement.
our repertoire of algebraic operations will be the following :

## AM-1: Simplification

Reducing the size of an expression by collecting common terms and factors, and removing zero terms and unit factors and powers.
e.g. $a-b c+2 a \rightarrow 3 a-b c$
$\mathrm{a}+\mathrm{b}-\mathrm{a} \rightarrow \mathrm{b}$
$a x /(a y) \rightarrow x / y$
$\frac{a \cdot b^{2} \cdot 2 a}{b}+2 a^{2} b$

[^12]AM-2: Rationalisation
Reducing a sum of terms into a ratio of two polynomial expressions.
$e \cdot g \cdot \frac{a}{2 b}-\frac{c}{d}+e \rightarrow \frac{a d-2 b c+2 b d e}{2 b d}$

## AM-3: Unrationalisation

Converse of rationalisation.
$e \cdot g \cdot \frac{c d-b c+(2-e)}{d} \rightarrow \frac{c d}{d}-\frac{b c}{d}+\frac{(2-e)}{d}$

## AM-4: Levelling

Converting a multi-level expression into a single or two-level one.
$e . g \cdot \frac{(a+b / c)}{\frac{c+d}{p q}} \rightarrow \frac{(a c+b) p q}{(c+d) c}$

## AM-5: Simple Factorisation

Factorisation based on any of the following formulae : $a^{2 n}-b^{2 n} \rightarrow\left(a^{n}-b^{n}\right)\left(a^{n}+b^{n}\right) \quad(n$ is an integer, omitted if 1$)$
$a^{3 n}-b^{3 n} \rightarrow\left(a^{n}-b^{n}\right)\left(a^{2 n}+a^{n} b^{n}+b^{2 n}\right)$
$a^{3 n}+b^{3 n} \rightarrow\left(a^{n}+b^{n}\right)\left(a^{2 n}-a^{n} b^{n}+b^{2 n}\right)$
$\left.\underset{\substack{k \\ i=1}}{\mathbf{k})}\left[a(*) b_{i}\right] \rightarrow a(*)\left[\begin{array}{l}k \\ i=1 \\ +\end{array}\right) b_{i}\right]$
AM-6: Guided Factorisation
Here we try to derive a factor in one expression of a step, which is already present in the other expression. Whether or not a given expression is a factor can be determined by the remainder theorem (again using a numeric test). e.g. In the step $\sin ^{3} \theta-\cos ^{3} \theta \rightarrow(\sin \theta-\cos \theta)(1+\sin \theta \cos \theta)$,

$$
(\sin \theta-\cos \theta) \text { is a factor to test for in } \sin ^{3} \theta-\cos ^{3} \theta
$$

AM-7: Expansion
A single-level expansion of expressions of the form $\left.\left.\underset{i=1}{(\stackrel{k}{+}) a_{i}}\right) *\binom{\ell}{j=1} b_{j}\right)$ and $\left(\begin{array}{l}k \\ i=1\end{array}+t_{i}\right)^{n}$ and distribution of powers in $\left(\begin{array}{c}\left({ }^{k}\right. \\ i=1 \\ \left(f_{i}\right)\end{array}\right)^{n} \quad\left(\rightarrow \underset{i=1}{k}(*) f_{i}^{n}\right)$.
e.g. $(a+b)(c-d) \rightarrow a c-a d+b c-b d$
$\left(a b^{2} / c\right)^{3} \rightarrow a^{3} b^{6} / c^{3}$

## AM-B: Addition of Identity

This can be roughly represented as :
(1) $e \rightarrow e+a-a$
(2) e $\quad$ ( $e^{*} a / a \quad(a \neq 0)$

The 'a' above is not arbitrary, but may be a term or a factor in the target expression.
e.g.

| $\underline{e}$ | $\underline{a}$ |
| :---: | :---: |
| $\csc -\cot$ | $\csc +\cot$ |
| $\frac{1}{\sec -\tan }$ | $\sec +t \tan$ |

result
$\frac{(\csc -\cot ) *(\csc +\cot )}{(c s c+\cot )} \equiv \frac{1}{\csc +\cot }$
$\frac{1}{\sec -t a n} \sec +t a n$

$$
\frac{(s e c+t a n)}{(\sec -\tan )(\sec +\tan )} \equiv(\sec +t a n)
$$

## Latent structure Probing

C-set determination enables a proof constructor to find the basic identities required to prove an identity. This gives it a very good measure of look-ahead: But even so, the task of proving the identity is in general not trivial. It is difficult, merely by inspecting the identity, to predict a sequence of algebraic transformations and trigonometric substitutions that will constitute a proof. However, for an identity whose C-set is singleton, it is sometimes possible to predict a useful form into which it can be converted.

As a case in point, $\cot ^{4} \theta-\csc ^{4} \theta \equiv 1-2 \csc ^{2} \theta$, which has the singleton C-set \{I8\}, is expressible in the form: $f-\left(\csc ^{2} \theta-1\right)^{2} \equiv f-\left(\cot ^{2} \theta\right)^{2}$. The $f$ can be shown to be $\cot ^{4} \theta-2 \csc ^{2} \theta+1$ in this case. This shows that the identity can be proved by deriving $f-\left(\csc ^{2} \theta-1\right)^{2}$ from $\cot ^{4} \theta-\csc ^{4} \theta$ via a sequence of A-steps, adding the known T-step $f-\left(\csc ^{2} \theta-1\right)^{2} \rightarrow f-\left(\cot ^{2} \theta\right)^{2}$, and then deriving $l-2 \csc ^{2} \theta$ from $f-\left(\cot ^{2} \theta\right)^{2}$ via another sequence of A-steps. Note that $\csc ^{2} \theta-1 \equiv \cot ^{2} \theta$ implied in the above form is a permitted variant of I8. The above form is a special case of the structure $f_{ \pm} g_{l}^{n} \equiv f_{ \pm} g_{r}^{n}$ where $n$ is some positive integer and $g_{\ell} g_{r}$ is a permitted variant of a reference identity. We have found the following eight structures to be useful; f is an arbitrary expression and $g_{\ell} \equiv g_{r}$ is a permitted variant.
(1) $\pm g_{\ell}: \pm g_{r}$
(5) $f * g_{\ell}^{n}: f * g_{r}^{n}$
(2) $\pm \mathrm{ng}_{\ell}: \pm \mathrm{ng}_{r}$
(6) $f \pm g_{\ell}: f \pm g_{r}$
(3) $\pm g_{l}^{n}: \pm g_{r}^{n}$
(7) $f \pm g_{l}^{n}: f \pm g_{r}^{n}$
(4) $f * g_{\ell}: f *_{r}$
(8) $\mathrm{f}_{ \pm} \mathrm{ng}_{\ell}: \mathrm{f}_{ \pm} \mathrm{ng}_{r}$

The structure (1) is a special case of (2) and of (3), just as (6) is a special case of (7) and (8). In the structures (1), (2), (3) and (7), $g_{\ell}$ and $g_{r}$ are determined uniquely. But in (4) and (5) they are determined up to $g_{\ell}^{\prime}$ and $g^{\prime} r^{\text {where }}$ $g^{\prime}{ }_{\ell} / g^{\prime}{ }_{r} \equiv g_{\ell} / g_{r}\left(g_{r} \neq 0\right)$ * and in (6) and (8), they are

[^13]determined up to $g_{l}^{\prime}$ and $g^{\prime}{ }_{r}$ where $g_{l}^{\prime}-g^{\prime}{ }_{r} \equiv g_{l}-g_{r} \cdot *$
An identity which can be transformed into one of these structures is said to possess a latent structure. Thus $\cot ^{4} \theta-\csc ^{4} \theta \equiv 1-2 \csc ^{2} \theta$ has a latent structure. Whether an identity, with a singleton $C$-set, has a latent structure or not can be found by simple numeric tests.

The rationalé behind latent structures can be briefly explained as follows. Suppose identity $f_{\ell} \equiv f_{r}$ has a singleton C-set corresponding to the reference identity $r \equiv 0$. In the $X$-form, Thm 3 tells us that $f_{\ell}-f_{r}$ is related to $r$. However this relation is too general. Suppose $g_{\ell} \equiv g_{r}$ is a permitted variant of $r \equiv 0$, and let $f$ be an arbitrary expression and $n$ a positive integer. Then it may be possible to express $f_{\ell}: f_{r}$ in terms of $g_{\ell}$ and $g_{r}$ in one of the structures above.

Let $u_{1}, u_{2}, v_{1}$ and $v_{2}$ be the values of $f_{\ell}^{\circ}, f_{r}^{\circ}, g_{\ell}^{\circ}$ and $g_{r}^{\circ}$ computed at an arbitrary point. Then $f_{\ell}: f_{r}$ has one of the structures shown in Table 6.1 , if its values satisfy the corresponding numeric test indicated.

To probe an identity $f_{\ell} \equiv \mathrm{f}_{\mathbf{r}}$ for a latent structure, it must first be verified to have a singleton $C$-set. If the series of tests in Table 6.1 fails for a given permitted

[^14]variant, then it may be repeated for another. In each series of tests, the $n$ may be varied to take any desired value, in practice $n=2,3,4, \ldots 9$ would be quite adequate. If all possible tests for $f_{\ell}: f_{r} f a i l$, then they may be repeated for $f_{r}: f_{\ell}$ and for $1 / f_{\ell}: 1 / f_{r}$. However for certain tests, a repetition for $1 / f_{\ell}: 1 / f_{r}$ would be redundant. Similarly for some structures, there is no need to test for every permitted variant. As an example, for the structure $f^{*} g_{\ell}: f^{*} g_{r}$, it would be useless to repeat a test for permitted variants which are multiples of $g_{\ell}: g_{x}$.

| Structure | Numeric Test |
| :---: | :---: |
| $[1] \pm g_{i}: \pm g_{r}$ | $u_{1} \pm v_{1} \& u_{2}= \pm v_{2}$ (i.e. $u_{1}=v_{1} \& u_{2}=v_{2}$ for the structure $g_{\ell}: g_{r}$ and $u_{1}=-v_{1} \& u_{2}=-v_{2}$ for $\left.-g_{\ell}:-g_{r}\right)$ |
| $[2] \pm \mathrm{ng}_{\ell}: \pm \mathrm{ng}_{r}$ | $u_{1}= \pm n v_{1}$ \& $u_{2}= \pm n v_{2}$ (for given $n$ ) |
| [ 3] $\pm \mathrm{g}_{\mathrm{R}}^{\mathrm{n}}: \pm \mathrm{g}_{r}^{n}$ | $u_{1}= \pm v_{1}^{n} \quad \& \quad u_{2}= \pm v^{n}$ |
| $[4] f * g_{\ell}: \mathrm{f}^{*} \mathrm{~g}_{r}$ | $\mathrm{u}_{1} / \mathrm{u}_{2}=\mathrm{v}_{1} / \mathrm{v}_{2}\left(\mathrm{provided} \mathrm{u}_{2} \neq 0\right)$ and [1] not satisfied |
| [5]f* $g_{\ell}^{n}: \mathrm{f}^{*} \mathrm{~g}_{r}^{\mathrm{n}}$ | $u_{1} / u_{2}=\left(v_{1} / v_{2}\right)^{n}\left(\right.$ provided $\left.u_{2} \neq 0\right)$ and [3] not satisfied |
|  | $u_{1}-u_{2}= \pm\left(v_{1}-v_{2}\right)$ and [1] not satisfied |
| $[7] f \pm g_{l}^{n}: f \pm g_{x}^{n}$ | $u_{1}-u_{2}= \pm\left(v_{1}^{n}-v_{2}^{n}\right)$ and $[3]$ not satisfied |
| $[8] f \pm n g_{l}: \mathrm{f}^{ \pm} \mathrm{ng} g_{r}$ | $u_{1}-u_{2}= \pm\left(n v_{1}-n v_{2}\right)$ and [2] not satisfied |

Table 6.1 Test for Latent Structures

It is clear that latent structures give a proof constructor an additional measure of look-ahead, enabling it to perform goal-oriented algebraic manipulations.

Table 6.2 contains several examples of latent structures. Table $C$. 4 in Appendix $C$ shows the results of a latent structure analysis on the sample steps. Here the probes are performed on the derived substeps, or on the steps if they are not resolved. It can be seen that most of the structures are of type (1). This is because the substeps are often the permitted variants of the reference identities.

| Step | Detected Structure |  | Actual Structure |
| :---: | :---: | :---: | :---: |
| $(\sin -\cos )^{2}+1-2 \mathrm{sin} . \cos$ | (6) | $\mathrm{f}+\left(\sin ^{2}+\cos ^{2}\right) \rightarrow \mathrm{f}+1$ | $\begin{aligned} & -2 \cdot \sin \cdot \cos +\left(\sin ^{2}+\cos ^{2}\right) \\ & \rightarrow-2 \sin \cdot \cos +1 \end{aligned}$ |
| $\cos ^{2}$ * $\sec ^{2}+1$ | (3) | $\left(\cos ^{*} \sec \right)^{2} \rightarrow i^{2}$ | $\left(\operatorname{cos*}^{* s e c}\right)^{2}+1^{2}$ |
| $\sec ^{4}-\sec ^{2}+\tan ^{4}-\tan ^{2}$ | - | unclassified | - - |
| $\left(\tan ^{2}+1\right)^{2}-\sec ^{2} \rightarrow \tan ^{4}+\tan ^{2}$ | (6) | $f-\left(\sec ^{2}-\tan ^{2}-1\right) \rightarrow f-0$ | $\begin{aligned} & \left(\tan ^{4}+\tan ^{2}\right)-\left(\sec ^{2}-\tan ^{2}-1\right) \\ & \rightarrow \tan ^{4}+\tan ^{2} \end{aligned}$ |
| $\frac{1}{s e c-t a n}+\text { secttan }$ | (4) | $\begin{aligned} & \mathrm{f} \mathrm{l}_{\mathrm{l} \rightarrow \mathrm{f} *\left(\sec ^{2}-\tan ^{2}\right)}^{\text {(equiv. to }} \\ & \frac{\mathrm{g}}{\sec ^{2}-\tan ^{2}} \rightarrow \frac{g}{1} \text { ) } \end{aligned}$ | $\frac{1}{\sec -\tan } \rightarrow \frac{\sec ^{2}-\tan ^{2}}{\sec -\tan }$ |
| sec. $\tan -2 \sin -\tan \rightarrow$ <br> (1+sec) (tan-2sin) | (8) | f-2tan ¢f-2sin.sec $^{\text {c }}$ | ```(sec.tan+tan-2sin)-2tan ->(sec.tan+tan-2sin)- 2sin.sec``` |
| $\cot ^{4}-\csc ^{4} \rightarrow 1-2 \mathrm{csc}^{2}$ | (7) | $f-\left(\csc ^{2}-1\right)^{2} \rightarrow f-\left(\cot ^{2}\right)^{2}$ | $\begin{aligned} & \left(\cot ^{4}-2 \csc ^{2}+1\right)-\left(\csc ^{2}-1\right)^{2} \\ & \rightarrow\left(\cot ^{4}-2 \csc ^{2}+1\right)-\left(\cot ^{2}\right)^{2} \end{aligned}$ |

Table 6.2 Examples of Latent Structure

## A Heuristic Proof Constructor

The flowchart in Figure 6.1 shows the general set-up of a heuristic proof constructor (HPC). The formulation Is an ad hoc one and needless to say there are other ways of organising our various heuristics into a proof generator. But our immediate aim is to demonstrate the feasibility of constructing a proof generator using our heuristics.

HPC maintains an identity list which starts off with the identity to be proved. Let $L(\theta) \equiv R(\theta)$ be this problem identity. The proof strategy chosen is $L(\theta) \xrightarrow[\rightarrow]{*} R(\theta)$, or equivalently $R(\theta)$ 京 $L(\theta)$ since the proof will be essentially bidirectional in the construction.

If $L(\theta) \rightarrow R(\theta)$ is already primitive then there is nothing to prove. If it is a large A-step then the proof will consist of algebraic manipulations to reduce the step size. If it is a sparse step then the trigonometric functions will all be converted into their $\sin \theta, \cos \theta$ equivalents.

HPC continually tries to decompose the identity into subidentities. In fact substep resolution is given top priority in $H P C . \quad$ If an identity is resolvable into sub1dentities, then it is deactivated and the subidentities appended to the list to be proved in turn. Although subIdentities are proved individually the proof displayed to the student, or any part of it, will have the usual form. This is done by combining the various substeps of a step.


Main Flowchart


C-set Reduction

Overlapping operations are prohibited to avoid large steps. The resolution is carried out in stages if necessary, starting with a primary one (see Chapter VII). When a given stage of resolution is unsuccessful another stage is attempted. The reason for resolving in stages is to take advantage of the way in which subexpressions occur. Often a primary resolution has as much chance of succeeding as the complete resolution. A complete resolution is on the average much costlier to perform than a primary one.

C-set reduction and latent structure probing can be carried out as explained earlier. For algebraic manipulation each applicable AM may have to be attempted in turn, each such AM, e.g. factorisation or simplification, being immediately followed by an attempt at resolution and c-set reduction.

The original identity is proved when the identity list is empty, i.e. has no active entries. If the list is not empty then each entry must be proved in turn. If the list cannot be emptied in this way, then the original identity will be proved all over again, this time using the strategy $L(0)-R(\theta) \nmid 0 . \quad$ If this again fails no new strategy will be attempted, and no proof is produced.

We have hand-simulated HPC on some sixty problem identities and have succeeded in producing a proof for each. The following illustrates our hand-simulation on three of
the identities. In order to be brief we have omitted much of the details of the simulation, especially in the second and third problems. We use the following abbreviations: $X=$ unsuccessful attempt, $/=s u c c e s s f u l, \varnothing$ empty set, $S R=$ substep resolution, $C R=C-s e t$ reduction, $A M=a l g e b r a i c$ manipulation, LS=left side.

## Hand Simulation of HPC

(1) Prove: $\cos ^{4} \theta-\sin ^{4} \theta+1 \equiv 2 \cos ^{2} \theta$

Select strategy LS $\underset{\rightarrow}{*}$ RS
C-set of step LS $\rightarrow$ RS is \{I6\}
Step not primitive
C-set not empty
Step not sparse
Try SR - X
Try CR - : Probe latent structure - X

- Substitute in LS to give $\left(i-\sin ^{2} \theta\right)^{2}-\sin ^{2} \theta+1$ (new tentative residual is $\left(1-\sin ^{2} \theta\right)^{2}$ $\sin ^{2} \theta+1 \rightarrow 2 \cos ^{2} \theta$ )
- C-set not reduced (to $\varnothing$ )
- Try SR - X
- Try latent structures - $\sqrt{ }$
- Detected structure is $2 *\left(1-\sin ^{2} \theta\right) \rightarrow 2 * \cos ^{2} \theta$
- Convert tentative residual to this form.
- Deactivate current problem identity
- Problem List empty.

Understandably many of the non-essential steps in
the simulation have been omitted in this description.
The derived proof (suitable for display to the student)
is constructed from this internal solution. overlapping
of "internal steps" are avoided in constructing this
"external" proof.
Derived Proof
$\cos ^{4} \theta-\sin ^{4} \theta+1$
$=\left(1-\sin ^{2} \theta\right)^{2}-\sin ^{4} \theta+1$
(substitution)
$=1-2 \sin ^{2} \theta+\sin ^{4} \theta-\sin ^{4} \theta+1$
(goal-directed transformation
$=2-2 \sin ^{2} \dot{\theta}$
$=2\left(1-\sin ^{2} \theta\right)$
$=2 \cos ^{2} \theta \quad Q E D$
(2) Prove: $\frac{1-\sin \theta}{1+\sin \theta} \equiv(\sec \theta-\tan \theta)^{2}$

C-set is $\{I 2, I 4, I 6, I 7\} \quad$ (not empty)
Step not primitive
Step sparse - convert identity to new identity $\frac{1-\sin \theta}{1+\sin \theta} \equiv$ $\left(\frac{1}{\cos \theta}-\frac{\sin \theta}{\cos \theta}\right)^{2}$
New C-set is \{I6\}
Try SR - X
Try CR - . Probe latent structure - /

- Detected structure is $f * l \rightarrow f *\left(\frac{1-\sin ^{2} \theta}{\cos ^{2} \theta}\right)$
with $\mathrm{f}=\frac{(1-\sin \theta)}{(1+\sin \theta)}$
- Guided by detected structure, transform new identity to the above form.

Derived Proof
$(\sec \theta-\tan \theta)^{2}$
$=\left(\frac{1}{\cos \theta}-\frac{\sin \theta}{\cos \theta}\right)^{2}$
$=\left(\frac{1-\sin \theta}{\cos \theta}\right)^{2}$
$=\frac{(1-\sin \theta)^{2}}{\cos ^{2} \theta}$
$=\frac{1-\sin \theta}{1+\sin \theta} \cdot \frac{(1-\sin \theta)(1+\sin \theta)}{\cos ^{2} \theta}$
$=\frac{1-\sin \theta}{1+\sin \theta} \cdot \frac{1-\sin ^{2} \theta}{\cos ^{2} \theta}$
$=\frac{l-\sin \theta}{1+\sin \theta} \quad$ QED
Prove: $\cos ^{6} \theta+\sin ^{6} \theta \equiv 1-3 \sin ^{2} \theta \cos ^{2} \theta$
C-set is \{I6\} (Singleton, non-empty)
Identity not sparse
Try SR - X
Try CR - X (no latent structure)
Try AM - . applying AM-5 (factorisation) to LS we derive $\left(\cos ^{2} \theta+\sin ^{2} \theta\right)\left(\cos ^{4} \theta-\sin ^{2} 0 \cos ^{2} \theta+\sin ^{4} \theta\right)$ - Try SR - $J$ obtaining the substeps
$\cos ^{2} \theta+\sin ^{2} \theta \rightarrow 1 \quad($ this is primitive) and $\cos ^{4} \theta-\sin ^{2} \theta \cdot \cos ^{2} \theta+\sin ^{4} \theta \rightarrow 1-3 \sin ^{2} \theta \cos ^{2} \theta$

- Append new subidentities to problem list and deactivate current identity (lst one need no further action)


## New Subidentity

Prove: $\cos ^{4} \theta-\sin ^{2} \theta \cos ^{2} \theta+\sin ^{4} \theta \equiv 1-3 \sin ^{2} \theta \cos ^{2} \theta$
C-set is $\{I 6\}$
Try SR - X
Try CR - . Probe latent structure - /

- Detect $\mathrm{f}+\left(\sin ^{2} \theta+\cos ^{2} \theta\right)^{2} \rightarrow \mathrm{f}+\mathrm{I}^{2}$
- Transform subidentity to this structure

Derived proof:
$\cos ^{6} \theta+\sin ^{6} \theta$
$=\left(\cos ^{2} \theta+\sin ^{2} \theta\right)\left(\cos ^{4} \theta+\sin ^{4} \theta-\cos ^{2} \theta \sin ^{2} \theta\right)$
$=1 *\left(\cos ^{4} \theta+\sin ^{4} \theta-\cos ^{2} \theta \sin ^{2} \theta\right)$
$=\left(\cos ^{2} \theta+\sin ^{2} \theta\right)^{2}-3 \sin ^{2} \theta \cos ^{2} \theta$
$=1-3 \sin ^{2} \theta \cos ^{2} \theta \quad$ QED

In our hand-simulation we have found some sections of the program and several minor heuristics to be of little use. Perhaps some of these may be removed without detriment
to the effectiveness of HPC. But until we have carried out adequate field study we are not certain how we can best reorganise $H P C$.

In this chapter we have proposed a method for generating proofs. This method we have demonstrated to be effective. Such a proof-generating capacity can be used to aid in the dispensing of assistance for proof as explained earlier in the chapter.

## Chapter VII

## PRACTICAL CONSIDERATIONS

Although there was time for implementing only the proof-checking program Super-2, we have considered many of the practical problems of implementing TPS. In particular we have looked into the question of C-set determination, subset resolution and data structures. Some of the solutions we propose have already been adopted in Super-2. In the final section of this chapter, super-2/will be briefly described.

## C-Set Determination

The purpose of C-set determination is to find a minimal C-set on which a step holds. This involves testing the step, using the representative point technique, over various $S$-sets to find a maximal one over which it holds.

In Super-2 the representative points are based on a small set of values. These values, thirty two of them, are shown in Table 7.l, listed to 9 decimal places only. The first six are arbitrary and are designated as $\sin ^{\circ}, \cos ^{\circ}, \ldots \cot ^{\circ}$ (SIN., $\operatorname{COS} ., \ldots \operatorname{COT}^{\text {. }}$ in the table). The remaining values are derived as shown; $X, Y$ and $Z$ represent three arbitrary arguments. As an illustration, entry 11 has the value $\cos ^{\circ} / \sin ^{\circ}$ while entry 30 has the value $\cos X / \operatorname{coty}$.

Each representative point is made up of six values from the table. In the C-set search table (Table C.2, see later) each $R P$ is represented by its substitution set, which is simply an ordered sextuple of pointers to the substitution table.
SIN=SIN.
COS=COS.
TANETAN.
2.711166337
4.927116030
CSC=CSC.
SEC=SEC.
7.001775210
15.331701000
COT=COT.
CSC=1/SIN.
21.030379100
.331407880
.368844946
.202958484
1.112963716
.898501888
.937020590
.349274123
2.682765566
1.067212407
2.863080698
.372749678
.721523394
.692390058
1.042076479
1.385956448
1.444272616
.959622465
.437011085
1.091319700
.115752197
7.273423693
7.273423693
- 137486835
. 363970348
.345615 .309
.899186009
(WHERE $X=1.214, Y=0.806,2=0.412$ )
SUBSTITUTION TABLE
Table 7.1

## Examples

C-set
$\mathrm{CO}=\varnothing$
$\mathrm{C} 22=\{I 1, I 2, I 3, I 4, I 5\}$
$C 42=\{I 1, I 6, I 7\}$
C94=\{II,I3,I4,I5,I7\}

| on Set | Representative Point |
| :---: | :---: |
| ( $1,2,3,4,5,6$ ) | $\left(\sin { }^{\circ}, \cos ^{\circ}, \tan ^{\circ}, \csc ^{\circ}, \sec ^{\circ}\right.$ |
| $(1,2,10,7,8,11)$ | $\begin{aligned} & \left(\sin ^{\circ}, \cos ^{\circ}, \sin ^{\circ} / \cos ^{\circ}, 1 / \sin ^{\circ},\right. \\ & \left.1 / \cos ^{\circ}, \cos ^{\circ} / \sin ^{\circ}\right) \end{aligned}$ |
| $(12,13,24,15,25,6)$ | $\left(\sin X, \cos X, \tan Z, \csc X, \sec Z, \cot { }^{\circ}\right.$ |
| $(28,2,14,29,16,17)$ | $\begin{aligned} & \left(\cos ^{\circ} \tan X, \cos ^{\circ}, \tan X, \frac{1}{\left(\cos ^{\circ} \tan X\right)},\right. \\ & \sec X, \cot X) \end{aligned}$ |

The RPs above can be easily shown to satisfy their respective requirements. As an example, the $R P$ for $C 42$ satisfies II,I6 and I7 $\left(\csc X=1 / \sin X, \sin ^{2} X+\cos ^{2} X=1\right.$ and $\left.\sec ^{2} Z=\tan ^{2} Z+1\right)$ but not I2,I3,I4,I5 and I8 $\left(\sec Z \neq 1 / \cos X, \cot ^{\circ} \neq 1 / \tan Z, \tan Z \neq \sin X / \cos X, \cot ^{\circ} \neq \cos X / \sin X\right.$, $\left.\csc ^{2} X \neq \cot ^{2}+1\right)$. From the above examples the reader should have an insight into the way in which we have assigned values to the various representative points in the search table.

## Zero Approximation

In testing for a step $f \rightarrow g$ over a sampling set $S$, RPT uses the criterion $f^{\circ}(\underset{\sim}{X}(S))=g^{\circ}(\underset{\sim}{X}(S))$ or equivalently $f^{\circ}(\underset{\sim}{X}(S))-g^{0}(\underset{\sim}{X}(S))=0, \underset{\sim}{X}(S)$ being the RP of $S$. However when the test is performed on a computer, we should allow for errors due to limited precision arithmetic by replacing the criterion by $\left.\left.\mid f^{\circ} \underset{\sim}{X}(S)\right)-g^{\circ} \underset{\sim}{X}(S)\right) \mid<\varepsilon$, where $\varepsilon$ is a tolerance factor. $\varepsilon$ should neither be too large nor too small.

Our experiment has shown that for a fairly broad range of values for $\varepsilon$ no incorrect conclusions are incurred. This involves a test on some 10,000 steps for various values of $\varepsilon$ and using the RPs we have just described. The computation was performed in single-precision
arithmetic on a CDC 6400. In this experiment, no error occurred for $10^{-1.1}<\varepsilon<10^{-4}$. In Super-2 we adopt $\varepsilon=10^{-8}$.

## Finding the C-set of a step

The set $\ell$ can be arranged into a network whose nodes are C-sets and whose directed edges join C-sets to their immediate C-subsets. A portion of this network is shown in Figure 7.1. C97 the largest C-set is the "earliest" node while the empty C-set CO is terminal, having no C-subsets.

Using this network we have the following algorithmn for finding
"the" C-set of a step:
[1] Test step at initial node C97. If test succeeds set i\&97
and go to [2]; otherwise step is incorrect. Exit.
[2] Test step at each immediate successor node of Ci in turn until either [a] it succeeds at $C j$ or [b] each test fails and there is no other successor node to test at. If [a], set $i \nleftarrow j$ and go to [2]; else it is [b] and the desired C-set is Ci. Exit.

It may be noted that this procedure produces only one C-set of a step.

This search algorithm is not the best possible since it requires more tests than are normally necessary. It initiates the search at c97 and this has more than twenty successor nodes. This means that a C-set search may require more than thirty tests since the earlier nodes have many successors. However most of the steps encountered in practice have a rather small (few elements) C-set and therefore a very significant saving is made in the required number of tests if we


Figure 7.1 C-set Search Network
can somehow initiate the search at a later node than C97. Such an improved procedure can indeed be devised requiring on the average less than six tests to effect a search. It is based on the configuration (see below) of a step, i.e. the types of functions occurring in it.

## Configuration-Directed Search

The binary sequence $\mathrm{b}_{1} \mathrm{~b}_{2} \ldots \mathrm{~b}_{6}$ defines the configuration of a step; $b_{i}$ is 1 or 0 depending on whether or not the ith trigonometric function occurs in the step. Thus $\sin \theta, \cos \theta, \ldots \cot \theta$ are $£ l a g g e d$ by $\mathrm{b}_{1}, \mathrm{~b}_{2}, \ldots \mathrm{~b}_{6}$ respectively. As an example the configuration of (l-tan 0 ) $(1-\cot \theta) \rightarrow 2-\sec \theta \csc \theta$ is $0011 l l$.

The largest C-set a (correct) step may have depends on its configuration, but it usually much smaller than C97. A step in which only $\sin \theta$ and $\cos \theta$ occur cannot have a $C$-set which is a superset of \{I6\}. This is because if its C-set is larger than (is a superset of) 16 then the correctness of the step must depend on some governing relation (i.e. basic identity) involving some function other than $\sin \theta$ and $\cos \theta$. But this is impossible since this step contains only these two functions and so cannot be dependent on any other function. Thus a step with the configuration 110000 must either be an A-step or have the C-set \{I6\}, provided it is correct.

Given a set of basic identities we may, by substitution among them, eliminate certain functions to derive new relations. As an example, we can derive $1 / \csc ^{2} \theta+1 / \sec ^{2} \theta \equiv 1$, involving only $\csc \theta$ and $\sec \theta$, from $\{I 1, I 2, I 6\}$. A step with the configuration 000110 could
therefore be dependent on $1 / \csc ^{2} \theta+1 / \sec ^{2} \theta \equiv 1$ for its correctness. Expressed in terms of our basic identities, this means its correctness could depend on $\{I 1, I 2, I 6\}$.

We shall refer to our basic identities and all those identities derivable from among them by substitution as operating identities. These include Jl, ...J4. The basic identities from which an operating identity is derived will be called its spanning identities. Thus the spanning identities of $1 / \csc ^{2} \theta+1 / \sec ^{2} \theta \equiv 1$ are $I 1, I 2$ and $I 6$.

For a given configuration, the largest $C$-set possible for a step may be obtained in the following manner. Collect all the operating identities ("implied" ones may be omitted) whose functions are indicated in the configuration. Then the spanning identities of this collection is the required largest C-set. We shall call this largest C-set the entry C-set of the configuration.

```
e.g. configuration : 010110
```

Operating identities: $\sec \theta \equiv 1 / \cos \theta, \cos ^{2} \theta+1 / \csc ^{2} \theta \equiv 1$
Spanning identities $: \csc \theta \equiv 1 / \sin \theta, \sec \theta \equiv 1 / \cos \theta, \sin ^{2} \theta+\cos ^{2} \theta \equiv 1$
Entry C-set : \{I1,I2,I6\}.

In a configuration-directed search, we avoid a great number of tests by initiating the C-set search at the entry C-set. The method we have actually experimented with is a configuration-directed one, but it is based on a C-set search table instead of the network. The C-set Search Table

The C-set search table, given in Table C. 2 is a modification of the network organised as a table. It has 153 entries, beginning
with entry-0 and ending in entry-152, and is oryanised int threod sections :
(1) (entries $0 \rightarrow 46$ ) associated with non-Pythagorean C-sets only;
(2) (entries $47 \rightarrow 53$ ) associated with Pythagorean C-sets only;
(3) (entries $54 \rightarrow 152$ ) associated with hybrid C-sets only; i.e. C-sets with both Pythagorean as well as non-Pythagorean elements. Each table entry has the following fields (from left to right): spanning C-set
(2) C-set sequence number
(3) substitution set of C-set
(4) configuration
(5) successor nodes (entry numbers)
(6) Operating identities.

## Example: Entry-61

$\begin{array}{ll}\text { Spanning C-set } & :\{I 1, I 2, I 6\} \\ \text { C-set seq. no. } & : 53 \\ \text { Substitution set } & :(12,13,3,15,16,6) \\ \text { Configuration } & : 110110 \\ \text { Successor nodes } & : 71,72 \\ \text { Operating Identities : } 11, I 2, I 6 \text { (same as spanning identities) } \\ \text { The successor nodes of an entry represent immediate C-subsets }\end{array}$ of its C-set, but these sets must be all Pythagorean, or all non-Pythagorean or all hybrid. Thus although $\{I 1, I 2, I 6\}$ has three immediate C-subsets, $\{I 1,12\}$ is not one of its successors in entry-6l, since it is non-hybrid. Entry-74 has no successors for, although \{Il,I3,I8\} has immediate C-subsets of the same kind (hybrid), they exceed* the configuration.

[^15]The spanning C-sets of those entries in the table, for which their configurations are indicated, are the entry C-sets of the configurations. It will be seen on inspection that in each section of the C-set search table the entries are ordered by configuration from the densest* to the sparsest (not including entries without configuration shown). Within configurations of a given density, the ordering is numeric, from larger down to smaller.

The following procedure for finding the C-set of a step, using the C-set search table has been used. In testing at a given entry, the computation of expression values is made at the representative point indicated by the substitution set.
[1] (Step Correct?) Test at entry-152. If successful, go to [2], otherwise step is incorrect and there is no C-set. Exit.
[2] (A-step?) Test at entry-0. If test fails go to [3], otherwise step is algebraic and C-set is $\varnothing$, the empty set. Exit.
[3] (non-Pythagorean?) Test at entry-1. If test fails, go to [4], otherwise step is non-Pythagorean. Enter this section of table at entry with a matching configuration with the step. Let this be entry-i. Go to [6].
[4] (Pythagorean?) Test at entry-47. If test fails go to [5], otherwise it is Pythagorean. Enter this section of table at entry-i, where the configurations of the step and this entry agree most closely. (If these configurations are respectively F1 and F2, then they must satisfy F2=Fl•A.F2 where•A. is the

[^16]FORTRAN •AND. masking function). Go to [6].
[5] (Step is hybrid). Attempt entering this section of table at entry-i, whose configuration matches that of the step. If succeed in locating such an entry, go to [6]. Else test at entries $-97,98, \ldots .116$ and entries $-149,150,151$ (configuration shown as XXXXXX) in turn until either [a] it succeeds at some entry, say entry-i or [b] all the tests fail. If [a] is the case go to [6]; if [b] then required $C$-set is the largest, c97. Exit.
[6] (Track down C-set). Two cases are possible: [a] entry-i has no successor (immediate C-subset) or [b] entry-i has one or more successors. In the case [a], the C-set of entry-i is the required one. In case [b], test for each of the successors in turn. Then either [i] it succeeds at say entry-j or [ii] all successors fail. In case [i], set $i \nleftarrow j$ and go to beginning of [6]. In case [ii] the step fails to hold on any of the C-subsets of the C-set of entry-i and so the latter is the required c-set. Exit.

## Remarks on the Search Table

(1) Every C-set is represented in the search table.
(2) The following entries have the special functions indicated.

| Entry | Corresponding C-set | For Testing Whether or not Step is: |
| :---: | :---: | :---: |
| 0 | [ ] | algebraic |
| 152 | $[1,2,3,4,5,6,7,8]$ | correct |
| 1 | [ $1,2,3,4,5]$ | non-Pythagorean |
| 47 | [6, 7,8$]$ | Pythagorean |

(3) The successors of entry-152 are those with configuration shown as XXXXXX. Because there are so many of them, they are not indicated in the field for successor nodes for entry-152.
(4) The entries 149,150 and 151 should have been placed with those other entries with configuration shown as Xxxxxx. However their omission was discovered only after the table has been constructed. This explains the break in the sequence of successors of C 97.
(5) Some configurations, e.g. llllol and 001lll, are absent in the hybrid section. However they are already covered by some other entries.
(6) Some configurations, e.g. entries-88 and 93, have multiple entry C-sets. In fact implicitly, 111111 in the hybrid section has several entry C-sets too.
(7) A full C-set search table is not required for proof-checking. Since in this case, the system is interested only in whether or not a step is correct, algebraic or has a singleton C-set, only entries for $\mathrm{CO}, \mathrm{Cl}, \mathrm{C} 2, \ldots \mathrm{C}, \ldots$ and $\mathrm{C97}$ (and \{J1\},...\{J4\}) are necessary.

## Substep Resolution

There are four types of resolution to implement. Exponential resolution presents little problem. Factored resolution can be converted, either explicitly or implicitly, into the additive case by expanding $f(*)\binom{(\underset{i=1}{k}}{i=1}$ into the form $\left.\underset{i=1}{\substack{k \\+\\ i}}\right) f(*) e_{i}$. We are left with the multiplicative and additive cases to consider, but since these are very similar, we shall treat only the additive case.

The additive resolution problem may be stated as follows: given two equivalent expressions $e$ and $e^{\prime}$, resolve $e$ and $e^{\prime}$ into $k$ terms each, giving $e_{1}, e_{2}, \ldots e_{k}$ and $e 1, e_{1}, \ldots e_{k}^{\prime}$ respectively, such that $e_{i}=e_{i}^{\prime}(i=1,2, \ldots k)$. The difficulty is that $k$ is not known before hand. The components derived from the expressions of a step have to be regrouped into matching terms.

## Expression Decomposition

Given an expression remove all its outermost parentheses, if any, and separate the resultant expression into its terms. This process is called a primary decomposition. The decomposition of $\mathrm{ab}-(\mathrm{c}-\mathrm{d})$ into ab and $-(\mathrm{c}-\mathrm{d})$ is primary, but not the decomposition of say, $a b-(c-d)$ into $a b,-c$ and $d$ or of $a+(b+c)$ into $a, b$ and $c$. If an expression undergoes two or more successive primary decompositions, then the resultant decomposition will be called secondary provided it is not the same as the primary decomposition. Thus $a+b-c$ has no secondary decomposition.

Components will be described as primary or secondary depending on whether they are derived by a primary or a secondary decomposition.

## Component Matching

Let $e \rightarrow e^{\prime}$ be a correct step and let the sets $\varepsilon=\left\{e_{1}, e_{2}, \ldots e_{n}\right\}$ and $\varepsilon^{\prime}=\left\{e\left\{, e\left\{, \ldots e_{n}^{\prime},\right\}\right.\right.$ be the derived components of $e$ and $e^{\prime}$ : respectively. Thus $(+) \varepsilon_{i}(+) \varepsilon^{\prime}\left((+) \varepsilon\right.$ means $\left.\underset{i=1}{(+)} \mathrm{m}_{i}\right)$. To resolve the step into $k$ substeps we impose a $k$-partition on $\varepsilon$ and $\varepsilon^{\prime}$. Let this partition yield $\left\{E_{1}, E_{2}, \ldots E_{k}\right\}$ and $\left\{E\left\{, E_{2}, \ldots E_{k}^{\prime}\right\}\right.$ where $\varepsilon=\mathcal{U}_{i=1}^{k} E_{i}$, $E^{\prime}=\prod_{i=1}^{k} E_{i}^{\prime}, E_{i} \cap E_{j}=\varnothing$ and $E_{i}^{\prime} \cap E_{j}^{\prime}=\varnothing(i \neq j)$. Furthermore we require the partition to satisfy: $(+) E_{i}=(+) E_{1}^{1}(i=1,2, \ldots k)$. Thus we are

There are $S(n, k)$ ways of distributing $n$ distinct objects into $k$, non-distinct cells such that none is empty and such that the order of the objects in a cell is irrelevant. Here $S(n, k)$ is Stirling's number of the second kind and is given by the formula
$\frac{1}{n!} \sum_{i=1}^{n}(-1)^{i}\binom{n}{i}(n-i)^{r}$ (see Liu [39], p. 38). It follows that the number of ways of partitioning a set of $n$ distinct elements into k classes is also $S(\mathrm{n}, \mathrm{k})$.

Assuming distinct components, we have $S(n, k)$ and $S\left(n^{\prime}, k\right)$ ways of $k$-partitioning $\varepsilon$ and $\varepsilon^{\prime}$. For each such partitioning of $\varepsilon$ and of $\varepsilon^{\prime}$ there are k! possible l-l mappings between the two sets of classes. Considering all possible k-partitionings there are a total of $T 1=S(n, k) \times S\left(n^{\prime}, k\right) \times k!$ such mappings. From among these mappings we seek one, $g$ say, satisfying: $g\left(E_{i}\right)=E_{i}^{\prime}$ and $(+) E_{i} \equiv(+) E_{i}^{\prime}$ ( $\mathrm{i}=1,2, \ldots . \mathrm{k}) \ldots\left({ }^{(*)}\right.$. Tl represents the number of $1-1$ mappings we may have to try before finding one satisfying the requirements (*), or discovering that no such match exists. Considering all possible values of $k$, we may have to $\operatorname{try} T 2=\sum_{k=0}^{n_{0}} S(n, k) x S\left(n^{\prime}, k\right) x k$ ! such mappings, where $n_{0}=$ minimum $\left(n, n^{\prime}\right)$ before we are assured that no resolution of the step $e \rightarrow e^{\prime}$ is possible. Table 7.2 shows some Stirling numbers of the second kind, to indicate how steeply T2 grows with $n$ and $n^{\prime}$.

The above formulation assumes a partitioning in which no class is empty. But this fails to account for the case of implicit substeps as is found in say $\sin ^{2} \theta+(\tan \theta-\sin \theta / \cos \theta) \rightarrow\left(1-\cos ^{2} \theta\right)$. Here

| $n \sqrt[k]{ }$ | 1 | 2 | 3 | - 4 | 5 | 6 | 7 | 8 | 9 | 10 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 1 | 1 |  |  |  |  |  |  |  |  |  |
| 2 | 1 | 1 |  |  |  |  |  |  |  |  |
| 3 | 1 | 3 | 1 |  |  |  |  |  |  |  |
| 4 | 1 | 7 | 6 | 1 |  |  |  |  |  |  |
| 5 | 1 | 15 | 25 | 10 | 1 |  |  |  |  |  |
| 6 | 1 | 31 | 90 | 65 | 15 | 1 |  |  |  |  |
| 7 | 1 | 63 | 301 | 350 | 140 | 21 | 1 |  |  |  |
| 8 | 1 | 127 | 966 | 1701 | 1050 | 266 | 28 | 1 |  |  |
| 9 | 1 | 255 | 3025 | 7770 | 6951 | 2646 | 462 | 36 | 1 |  |
| 10 | 1 | 511 | 9330 | 34105 | 42525 | 22827 | 5880 | 750 | 45 | 1 |

Table 7.2 Some Values of $S(n, k)$
$(\tan \theta-\sin 0 / \cos \theta) \rightarrow 0$ is a substep although the 0 is present only implicitly in the right expression. (In multiplicative resolution we have an implicit match with $\pm 1$ ). The number of k-partitions of n distinct objects, permitting empty classes, is $\sum_{i=1}^{k} S(n, i)$, this being also the number of ways of distributing $n$ distinct objects into $k$ non-distinct cells, with empty cells allowed (see Liu [39]). The effect of this revision is to greatly increase the size of T2 derived above.

The aim of our brief combinatorial exercise has not been so much to derive specific formulae as to show that to carry out a substep resolution, a very large number of trial-and-error operations might be required, this number growing dramatically (exponentially) with the number of components obtained from the step expressions. There is therefore a need for a very efficient method for deciding expression equivalence, and this is one application in which our
numeric approach has a big edge over a purely symbolic one. The choice of data structures used in the implementation also becomes very important; we shall discuss this topic later.

## Primary and Secondary Resolution

Substep resolution based on primary components of the step expressions will be called a primary resolution; similarly a secondary resolution is based on secondary components only. Our ad hoc approach is to perform a primary resolution first. If this fails, then a secondary resolution is attempted. If a secondary resolution fails, then another (based on a further secondary decomposition of the expressions) is attempted, unless this is not possible.

The rationalé for this approach is that a primary resolution involves fewer components than a secondary one, and therefore is much faster to carry out, since the effort required to perform a resolution increases exponentially with the number of components. Besides, by the way subexpressions occur, a primary resolution has a relatively high chance of succeeding. It would be inefficient therefore to attempt a secondary one straight away.

Non-uniqueness
The resolution of a step is not always unique, but where all possible resolutions lead to the same conclusion regarding step-size, then we have no problem. However a small step may give rise to a resolution which causes it to be regarded as large. One such case is the following: $a+b \rightarrow c+d+d$ ' being resolved into $a \rightarrow c+d$ ' and $b \rightarrow d$ with both substeps small, and into $a \rightarrow c+d$ and $b \rightarrow d$ ' in which $b \rightarrow d$ ' is large.

In practice the proportion of cases incorrectly analysed in consequence of non-uniqueness is so small that we can ignore it without serious consequence. There are ways in which this problem can be handled, but we shall not consider any of them here. We merely wish to point out the existence of the problem.

Sequential Resolution Procedure
So far our formulation has more or less assumed simultaneous resolution. But there is no need for deriving all the substeps of a resolution at once. Instead we can obtain the same results sequentially, and this approach is simpler to implement. In sequential resolution, we remove a substep from the step as it is detected, continuing in like manner with the remaining step. This is in fact the approach used in Super-2.

Sequential resolution may be described briefly as follows. Let the components of the step expressions be, as usual, $\varepsilon=\left\{e_{1}, e_{2} \ldots e_{n}\right\}$ and $E^{\prime}=\left\{e_{1}^{\prime}, e_{2}^{\prime}, \ldots e_{n}^{\prime}\right\}$. We attempt to detect substeps by a sequence of schedules $1-1,1-2,2-1,2-2,1-3, \ldots$. A schedule $r-s$ is a program for seeking out a substep involving $r$ components of $E$ and $s$ components of $E^{\prime}$. The $\binom{n}{r}$ classes of $r$ components of $\varepsilon$ are matched against the $\binom{n}{s}$ classes of $s$ components of $\varepsilon^{\prime}$ in turn until there is a successful match or until all attempts fail. A successful match indicates a substep and this is removed. The matching comparison is done numerically, using maximum consistency (q.v.) values. When a substep is removed, $n-x$ components of $E$ and $n^{\prime \prime}-s$ components of $E$ ' remain. The search for another substep under the same schedule continues with these remaining components provided there are enough of them, i.e.
$n-r \geqslant r$ and $n^{\prime}-s \geqslant s$. If this schedule no longer applies, the next one is tried until no further schedules are applicable, by reason of insufficient number of components. When a given class of $r$ components is initiated, a test for an implicit test is also made by testing it against 0 .

In Super-2 only the 9 schedules $1-1,1-2,2-1,2-2,1-3,3-1,2-3,3-2$ and 3-3 are used, in that order. In analysing the 207 sample steps, it was found that the removal of the last five schedules did not affect the result of the analysis. This is because the number of components involved in the expressions are small, (Super-2 does not perform secondary resolution) and the substeps themselves involve relatively few components. If the first four schedules prove adequate, then a significant improvement to the resolution algorithmn is achieved, man:
since the last five schedules often involve mon more tests than the first four.

## Data Structures

How efficiently and elegantly we can implement a program will depend to a large extent on our choice of the underlying data structures. In TPS this consideration is vital if we are to expect the full advantages of our largely numeric approach. There are several important factors to bear in mind.

Our approach involves a large number of computations for deriving expression values at various selected points. A standard approach for evaluating an expression is to convert it first into a Polish form and then to carry out the computation interpretively. There are
several forms of the Polish notation (see Hamblin (301) (h, it wow used. In Super-2 we choose the early prefix Polish.

Expressions under investigation should be carried in the Polish form to avoid repeating the costly process of converting an expression into this form every time it is to be evaluated. Polish expressions should be maintained internally as a simple doubly-linked list to expedite the insertion and deletion of subexpressions. The latter operations occur during sequential substep resolution.

A doubly-linked list consists of a sequence of cells, each linked to its left and right neighbours; the first and the last cells have only one link each. The diagram below shows $\sin \theta+\cos \theta *\left(1-\tan ^{2} \theta\right)-\tan \theta$ maintained in its Polish form as a doubly-linked list ('\&"' represents a double link).
$[-] \leftrightarrow[+] \leftrightarrow[\sin \theta] \leftrightarrow[*] \leftrightarrow[\cos \theta] \leftrightarrow[-] \leftrightarrow[1] \leftrightarrow[\uparrow] \leftrightarrow[\tan \theta] \leftrightarrow[2] \leftrightarrow[\tan \theta]$

TPS requires the values of expressions and subexpressions at various representative points. Of these the most important are the maximum consistency (MXC) values computed at the $R P$ of $C 97$ and the minimum consistency (MNC) values computed at the $R P$ of $C O$. Since the MXC and MNC values are used very frequently they are carried permanently with the Polish list in Super-2. The diagram below shows how the fictitious MNC values of the last expression (assuming $\sin \theta=1, \cos \theta=2$ and $\tan (\theta=3)$ may be stored with the list. Note that each cell carries
 the value of the subexpression it initiates. In particular the values of all the components are now known and this is a great advantage
since these values are required again and again during substep resolution. The dramatic improvement derived by this saving of the MXC and MNC values will be shown in our discussion on Super-2.

For the same reason as for the MXC and MNC values, we should also derive the component counts of the various elements and subexpressions only once and save them in the list, ready for use when required.

Two basic formula manipulation operations in resolution are the locating of components and the detaching of matched components. In both we want to find the initial and terminal cells of a desired component so that we can read off its MXC or MNC value, or compute its value as some $R P$ or to remove it from the parent list. To ensure efficiency, we should perform our formula manipulations in the Polish form only so that we do not need to operate at the usual infix form as well. Unfortunately, a Polish expression, maintained as a simple doubly-linked list is highly unstructured. It does not reveal easily the location of desired components.

Furthermore, during component detachment, and attachment, certain of the values and component counts in the resultant list become incorrect and must be recomputed. To avoid unnecessary corrections, we should recompute only those affected quantities. There is then the problem of locating the affected cells.

In the following section, we develop a simple numbering scheme which imposes a useful structure on the list by assigning an index to each cell. The indices enable us to develop very simple algorithms
for the various formula manipulation operations. The indices are carried with the list, in the same way, and for much the same reasons, as for the other appended quantities.

## Index Theory

We shall define an index scheme for prefix Polish and study some of its properties. We shall then show the relevance of these properties in our formula manipulation operations.

## Basic Definitions

D. 1 A symbol is a member of a set $\left\{s_{1}, s_{2}, s_{3}, \ldots\right\}$ of primitive operands. e.g. A,ZR,12,5
D. 2 An operator is a member of a set $\left\{\varnothing_{1}, \varnothing_{1}, \varnothing_{2}, \ldots\right\}$ of operators. e.g. +,-,*, $\uparrow, \sim, \sin , s e c . \quad(\sim$ is the unary minus)
D. 3 An element is a symbol or an operator.
D. 4 A string is a sequence of elements.
D. 5 The degree $D(e)$ of an element $e$ is given by: (1) $D(e)=0$ if $e$ is a symbol and (2) $D(e)=m$ if $e$ is an $m$-ary operator. e.g. $D(\mathrm{sec})=D(\sim)=1, D(A)=D(5)=0$ and $D(*)=D(+)=2$.
D. 6 The rank $R(e)$ of an element $e$ is $D(e)-1$.
D. 7 The rank of a string $S$ is the sum of the ranks of its elements.
D. 8 Well-Formed Formula (wff)
(a) a single symbol is a wff;
(b) if $\varnothing$ is an m-ary operator and $F_{1}, F_{2}, \ldots F_{m}$ are wffs then $\not \mathrm{F}_{1} \mathrm{~F}_{2} \ldots \mathrm{~F}_{\mathrm{m}}$ is a wff;
(c) a string is a wff if and only if it is so by virtue of (a) and (b).

Note: D. 8 defines a well-formed expression in the prefix Polish
form. Note that the rightmost element of a wff is always a symbol.
D. 9 A substring of a wff which is also a wff is called its wellformed subformula (wfsf).
e.g. 'a' and '-bc' are wfsfs of the wff '+a/-bcd'

Notation: We will usually denote a wff $F$ by $e_{1} e_{2} e_{3} \ldots e_{n}$ where

$$
e_{1}, e_{2}, \ldots e_{n} \text { are elements. }
$$

D. $10 W\left(e_{i}\right)$ or $W(i)$ denotes the wfsf of $e_{1} e_{2} \ldots e_{n}$ beginning with $e_{i} \cdot$ e.g. If $e_{1} e_{2} \ldots e_{7}$ is ' $+a /-b c d^{\prime}$ then $W(2)$ is 'a'. $W(4)$ is '-bc' and $W(9)$ is undefined.

The problem of locating $W(i)$ is to find its rightmost element. One way of locating this element is to use the Rank Theorem (see Nelson [50], p.45) which states: The rank of a well-formed formula is -1 . Since $W(i)$ is unique all we have to do then is to add the ranks of the string elements beginning with $e_{i}$ and proceeding to the right until the sum is -l. However we shall use an alternative approach based on indices (q.v.).

## D. 11 Definition of Index

The index of the element $e_{i}$ in the string $e_{1} e_{2} \ldots e_{n}$, denoted by $I\left(e_{j}\right)$ or $I(i)$ is given by:
(a) $I(i)=I(i+1)-R\left(e_{i}\right)$
(b) $\quad I(n+1)=N$
$N$, the index base, is an arbitrary integer value to be set. The standard index has the base $N=0$. Unless otherwise specified, all indices will be assumed to be standard, as in Super-2. e.g. The Polish string and its associated indices for the expression
$A+(B-C) /(2 * A-P /(Q+R))$ is as follows. The indices are computed from the right.

I (i): $\begin{array}{llllllllllllllll}1 & 2 & 1 & 2 & 3 & 2 & 1 & 2 & 3 & 2 & 1 & 2 & 1 & 2 & 1\end{array}$
$e_{i}: \quad+A /-B C-* 2 / P / Q R$
D. 12 The rightmost and the leftmost elements $e_{n}$ and $e_{1}$ of the string $S: e_{1} e_{2} \ldots e_{n}$ are denoted by $\underline{R m(S)}$ and $\operatorname{Lm}(S)$ respectively. If $S$ is an element then $\mathrm{Rm}(S)$ and $\mathrm{Lm}(S)$ are the same element. We shall now derive a number of simple index-theoretic results which are useful for our numeric heuristics. These results will be called observations or Obsns for short. They pertain to expressions and subexpressions which are well-formed. It would be helpful to the reader to consult the last example when reading the observations.

The Indices of Well-formed Expressions
Obsn 1: Let $F_{i} F_{i+1}$, where $F_{i}, F_{i+1}$ are wffs, be a substring of a wff. Then $I\left(\operatorname{Lm}\left(F_{i+1}\right)\right)=I\left(\operatorname{Rm}\left(F_{i}\right)\right)-1$.

Proof: As noted earlier the rightmost element of a wff is always a symbol and therefore has the rank -1. It follows from the definition of index, that $I\left(\operatorname{Rm}\left(F_{i}\right)\right)=I\left(\operatorname{Lm}\left(F_{i+1}\right)\right)-R\left(R m\left(F_{i}\right)\right)=I\left(\operatorname{Lm}\left(F_{i+1}\right)\right)+1$. Hence the observation. QED.

Obsn 2: If $F$ is a wff then $I(R m(F))=I(\operatorname{Lm}(F))$.
Proof: We prove this observation by induction on the length of $F$. If $F$ is of length $l$, then result is obviously true since $\operatorname{Lm}(F)$ and $R m(F)$ are the same element (true for $n=1$ ).

Suppose observation holds for all F's of length $<\mathrm{n}$. Let F be of length $n+1$. Since $F$ has at least two elements it has the form
$\emptyset F_{1} F_{2} \ldots F_{m}$ where $\varnothing$ is an $m$-ary operator and $F_{1}, F_{2} \ldots F_{m}$ are all wellformed. Since each $F_{i}$ is of length $\leqslant n, I\left(\operatorname{Rm}\left(F_{i}\right)\right)=I\left(\operatorname{Lm}\left(F_{i}\right)\right)(i=1,2, \ldots m)$, by the induction hypothesis. Let $I\left(\operatorname{Lm}\left(F_{m}\right)\right)=k$. Then by Obsn 1 , $I\left(\operatorname{Lm}\left(F_{m-1}\right)\right)=k+1, I\left(\operatorname{Lm}\left(F_{m-2}\right)\right)=k+2, \ldots, I\left(\operatorname{Lm}\left(F_{I}\right)\right)=k+(m-1)$. By definition, $I(\operatorname{Lm}(F))=I(\phi)=I\left(\operatorname{Lm}\left(F_{1}\right)\right)+R(\varnothing)=k+(m-1)-(m-l)=k=I\left(\operatorname{Lm}\left(F_{m}\right)\right)=I\left(R m\left(F_{m}\right)\right)=$ I(Rm(F)). QED.

Obsn 2 states that the extremal elements of a•wf have equal indices. This motivates the next definition.
D. 13 The index of a wff is the common index of its extremal elements. Thus if $F$ is a wff, then $I(F)=I(R m(F))=I(\operatorname{Lm}(F))$.

Obsn 3: Let $\varnothing$ be an m-ary operator and $F_{1}, F_{2}, \ldots F_{m}$ wffs. Then the indices of $\varnothing, F_{1}, F_{2} \ldots F_{m}$ in the wff $\varnothing F_{1} F_{2} \ldots F_{m}$ are respectively $1, m, m-1, m-2, \ldots 3,2,1$ 。

Proof: See proof for Obsn 2.
Note that all standard indices are positive and the index of a wff, not treated as a wfsf of another wff, is 1. Obsn 4: Let $F \equiv e_{1} e_{2} \ldots e_{n}$ be a wff. Then $I(i) \geqslant 1$ ( $i=1,2, \ldots n$ ) Proof: Follows from Obsn 3 and induction.

Obsn 4 states that no standard index in a wff can be less than 1. In fact in any wfsf of a wff, the indices are no less than those of the extremal elements of the wfsf.

Obsn 5: Let $F \equiv e_{1} e_{2} \ldots e_{n}$ be a wff. Then $\operatorname{Rm}(W(i))$ is the first element $e_{j}$ to the right of $e_{i}$ satisfying $I(j+1)<I(i)$ or if this $e_{j}$ does not exist, it is $e_{n}$.

Proof: Either (1) $W$ (i) has a right-hand neighbour in $F$ or (2) it does
not. In the case (2), $W(i)$ is $e_{n}$.
In the case (1), since $W(i)$ has a right neighbour it must have a wfsf as a right neighbour. By Obsn 1 , the index of the right neighbour must be $k-1$ if the index of $W(i)$ is $k$. By Obsn 4 , every element in $W(i)$ has an index $\geqslant k$. Therefore the right neighbour of $W(i)$ is the first element on its right with a smaller index than its own. QED.

This Observation enables us to locate the right extremity of a component in a Polish expression very easily. There is no need to apply the Rank Theorem.
D. 14 Let $\emptyset F_{1} F_{2} \ldots F_{m}$ be a wff in which operator $\varnothing$ is m-ary and $F_{1}, F_{2}, \ldots F_{m}$ are well-formed. Then $\varnothing$ is called the governing operator of $F_{1}, F_{2}, \ldots F_{m}$, which in turn are the operands of $\phi$. $\phi \mathrm{F}_{1} \mathrm{~F}_{2} \ldots \mathrm{~F}_{\mathrm{m}}$ will be called the governing wff of $\varnothing_{1} \mathrm{~F}_{1}, \mathrm{~F}_{2} \ldots \mathrm{~F}_{\mathrm{m}}$.
D. 15 The operator Op maps a wff on its governing operator. Thus (cf D.14) $O p\left(F_{1}\right)=O p\left(F_{2}\right)=\ldots=O p\left(F_{m}\right)=\varnothing . \quad O p^{i+1}(F)$ denotes Op(Op $\left.{ }^{i}(F)\right)$. A wff of length 1 has no governing operator. Obsn 6: If $\emptyset \mathrm{F}_{1} \mathrm{~F}_{2} \ldots \mathrm{~F}_{\mathrm{m}}$ is a wff, then $\mathrm{F}_{1}, \mathrm{~F}_{2} \ldots \mathrm{~F}_{\mathrm{m}}$ are respectively $W\left(i_{1}\right), W\left(i_{2}\right), \ldots W\left(i_{m}\right)$ where $e_{i_{j}}(j=1,2, \ldots m)$ is the first element to the right of $\varnothing$ whose index is $m-j+1$.

Proof: Very similar to proof for Obsn 7 below.
This observation gives us a simple index-directed method for locating the operands of an operator in a Polish string. Obsn 7: The governing operator of $a$ wfsf $F_{i}$ of a wff is the first element on its left with an index not greater than its own.

Proof: $F_{i}$ must be in the context ... $\varnothing F_{1} F_{2} \ldots F_{m} \ldots$ as one of $F_{1}, F_{2}, \ldots, F_{m}$.

Let $I(\varnothing)=k$. Then $F_{1}, F_{2}, \ldots F_{m}$ have the indices $k+(m-1), k+(m-2), \ldots$ $\ldots k+2, k+1, k\left(c f\right.$ Obsn 3). By Obsn 4, all the elements in $F_{1}, F_{2}, \ldots F_{m-1}$ have indices greater than $k$. Hence the observation. QED.

Obsn 8: If we replace any wfsf in a wff with a wff, then the resultant string is a wff.

Proof: Definition of well-formed formula.

## Using Indices in our Data Structures

In TPS the operators encountered are the arithmetic ones,,$+- *$, /,,$\sim$ and $V$ (reciprocal). Since we are treating $\sin \theta, \cos \theta, \ldots \cot \theta$ as the special variables $\operatorname{SIN}, \operatorname{COS}, \ldots \operatorname{COT}$ (i.e. $x_{1}, x_{2}, \ldots x_{6}$ ) we do not concern ourselves with trigonometric operators. Our operators are all of degree 1 or 2 and although our index theory applies to general $m$-ary operators, $m \leqslant 2$ is adequate for TPS.

We maintain an expression internally as a prefix Polish string $e_{1} e_{\eta} \ldots e_{n}$ To each element $e_{i}$ we append its MXC and MNC values, its index $I(i)$ and its component count $N(i)$. To simplify description we represent the $M X C$ and $M N C$ values by a single one $V(i)$ which can be regarded as being derived for some given substitution.

We shall refer to a string $e_{1} e_{2} \ldots e_{n}$ in which $e_{i}$ is associated with $I(i), V(i)$ and $N(i)$ as a structure. If the string is a wff and $I(i), V(i)$ and $N(i)(i=l, \ldots n)$ are all correct and consistent then we shall call the structure well-formed.

Let $e_{1} e_{2} \ldots e_{n}$ be a wff. Then $V(i)$ the value of element $e_{i}$ under some given substitution is given by the following.

If (l) $e_{i}$ is a numeric constant, $V(i)$ is that number;
(2) $e_{i}$ is a variable, $V(i)$ is the substituted, value of $e_{i}$;
(3) $e_{i}$ is an operator, $V(i)$ is the value obtained by applying the operator to the values of its operands. (If $e_{i}$ is + , then addition is implied, etc.)

The component count $N(i)$ of $e_{i}$ is defined as follows :
(1) $e_{i}$ is a variable or constant then $N(i)=0$;
(2) $e_{i}$ is $\uparrow$ and its left operand is $\operatorname{SIN}, \operatorname{COS}, \ldots$ or $\operatorname{COT}$, and the right operand is 0,1 or 2 , then $N(i)=0$.
(3) $e_{i}$ is $\uparrow$ and the operands are not of the type in (2), then $N(i)$ is the component count of its left operand plus 1 , i.e. $N(i+1)+1$.
(4) $e_{i}$ is +, -, * or / then if $e_{i+l}$ is of the same hierarchy* then $N(i)$ is the sum of the component count of its 2 operands plus l;
(5) $e_{i}$ is,,$+- *$ or / but does not satisfy condition (4), then $N(i)$ is the sum of the component count of its two operands plus 2.

Figure 7.2 below shows the structure of $\S \equiv A-B+(C-D)+P /(C-P * Q)$, assuming the substitution $A=2, B=4, C=6, D=5, P=5$ and $Q=4$.

Remark: The indices carried in a string are relative to the base $N$. The following diagram shows three valid assignments for the string of $A^{*}(B / C+D)$.


[^17]| i : | 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 | 9 | 10 | 11 | 12 | 13 | 14 | 15 |
| :---: | ---: | ---: | ---: | ---: | ---: | ---: | ---: | ---: | ---: | ---: | ---: | ---: | ---: | ---: | ---: |
| $I(i):$ | 1 | 2 | 3 | 4 | 3 | 2 | 3 | 2 | 1 | 2 | 1 | 2 | 1 | 2 | 1 |
| $\mathrm{e}_{\mathrm{i}}:$ | + | + | - | A | B | - | C | D | $/$ | P | - | C | $*$ | P | Q |
| $\mathrm{V}(\mathrm{i}):$ | $-\frac{19}{14}$ | -1 | -2 | 2 | 4 | 1 | 6 | 5 | $\frac{-5}{14}$ | 5 | -14 | 6 | 20 | 5 | 4 |
| $\mathrm{~N}(\mathrm{i}):$ | 12 | 5 | 2 | 0 | 0 | 2 | 0 | 0 | 6 | 0 | 4 | 0 | 2 | 0 | 0 |

Figure 7.2 A Structured List

The subexpression $B / C$ in the first assignment has the indices 2 $\quad \begin{array}{lll}3 & 2 \\ \text { / and this can be regarded as being relative to a base of } 1 \text {. }\end{array}$ Applying Index Theory to Formula Manipulation in Prefix Polish

We shall now consider several important applications of our index-theoretic results to subexpression manipulation.

## Expression Decomposition

In Super-2 an expression is decomposed only implicitly. The components are located and their positions in the string noted in a component table. Obsn 5 and Obsn 6 enable us to locate the operands of an operator.

If the operator is unary then its only operand begins immediately on its right, the right extremity of this operand being easily found by using Obsn 5. If the operator is binary, of index $k$ say, then it has a left and a right operand. The left operand is located in the same way as the operand of a unary operator. The right operand begins with the element which is the first to the right of the operator to have the index $k+1$. Its right extremity can again be found by using Obsn 5.
e.g. In Figure 7.2 the operands of $e_{2}$ are $W(3):-A B$ and $W(6):-C D$,
and the left and right operands of $e_{1}$ are $W(2)$ and $W(9)$.

When an expression is in the additive or multiplicative form, several components are often involved. The operands of any one operator do not yield directly the desired components. To illustrate, the primary components of $\S$ are $A,-B,(C-D)$ and $P /(C-P * Q)$ but the operands of say $e_{1}$ (cf Polish string of §) are $W(2)$ and $W(9)$ but not the components. We shall now present an algorithm for dexiving the primary components using indices. We shall treat only the additive case as the multiplicative one is similar.

To locate the primary additive components, scan the string $e_{1} e_{2} \ldots e_{n}$ from the left for the leading chain $e_{1} e_{2} \ldots e_{r}$ of additive operators. If there is no such chain, then the expression is its only component. Otherwise, the primary components are $W\left(i_{0}\right), W\left(i_{1}\right), \ldots W\left(i_{r}\right)$ where $i_{0}$ is $r+1$ and $e_{i_{j}}(j=1,2, \ldots . r)$ is the first element to the right of $e_{r}$ for which $I\left(i_{j}\right)=I(j)$. This follows from a repeated application of Obsn 6.

An expression such as $-(A+B-P / Q)$ is not in the additive form strictly speaking. However by taking care of the signs separately, we can derive the components by bypassing the unary minus. At the Polish level this means applying our algorithm to $e_{2} e_{3} \ldots e_{n}$.

Applied to $\S$ the primary components are, ignoring signs, $W(4), W(9), W(6)$ and $W(5)$, i.e. $A, / P-C * P Q,-C D$ and $B$. Note that $V(4), V(9), V(6)$ and $V(5)$ are the values of these components. When taking into account the signs, a component should be negated only if it is the right operand of a '-'. In our example only $B$ should be negated.

Our method does not strictly yield the primary components in all cases. It gives the same components as for $\S$ when applied to $(A-B)+(C-D)+P /\left(C-P^{*} Q\right)$, which has only three primary components. The anomaly is due to the first primary component being itself an additive form. We shall however ignore this unimportant anomaly.

If we apply our algorithm a second time to $\S$, we derive the secondary components $A,-B, C,-D$ and $P /(C-P * Q)$. Note that only ( $C-D$ ) of the primary components is decomposed in this secondary resolution. Subexpression Detachment

When a substep is detected during sequential resolution, the components forming the substep are detached from the parent string. A substep expression may involve several components. We shall now examine the process of detaching a component from a wff.

Let the parent string be of the form $F \equiv \ldots \stackrel{. k}{\phi}_{\mathcal{F}_{1}+1}^{F_{2}} \ldots$ where $\phi$. is a binary operator, and $F_{1}$ and $F_{2}$ are wfsfs. To detach $F_{2}$ from $F$ we must replace $\phi F_{1} F_{2}$ (a wfsf) by $F_{1}$ (another wfsf) in the string of $F$. This involves the delinking of $F_{2}$ and $\varnothing$. If $F_{1}$ is to be detached, then we must replace $\emptyset F_{1} F_{2}$ by $F_{2}$ if $\varnothing$ is + or *, by $\sim E_{2}$ if $\varnothing$ is - and by $\nabla F_{2}$ if $\varnothing$ is /. These actions are summarised in Table 7.3.

When we have taken the above actions to detach a component, the resultant string reflects correctly the resultant expression. However the resultant structure is no longer well-formed, because some of the appended quantities (the $V(i), N(i)$ and $N(i)$ ) are no longer correct. To rectify these affected values, we do not have to recompute
completely the appended quantities since normally not many of them are incorrect.

If it is $F_{1}$ which is detached, then no index correction is required since $\emptyset F_{1} F_{2}$ is replaced by a wfsf of the same index. If $F_{2}$ is the component detached, then only the indices of the elements of $\mathrm{F}_{1}$ which replaces $\not \mathrm{F}_{1} \mathrm{~F}_{2}$ need be corrected. This is done by reducing each incorrect index by 1 , to make the new index of $F_{1}$ the same as that of the wfsf it replaces.

The only "V(i)" and "N(i)" that are incorrect are those of the governing operators of the affected wfsf in the resultant string. Thus if $F_{2}$ has been detached, then the affected operators are $O p\left(F_{1}\right)$, $O p^{2}\left(F_{j}\right), O p^{3}\left(F_{1}\right) \ldots(t i l l$ there are no more). These operators can be easily located using Obsn 7. The correction for the "V(ị)" and " $\mathrm{N}(\mathrm{i})$ " should be made in the order of the governing operators shown.

Figure 7.3 illustrates the detachment of (C-D) from the expression 5. in three stages. The first shows the well-formed structure prior to the detachment. The second shows the effect of delinking '-CD' and its governing '+'. The affected appended quantities are shown in italics and they are rectified in stage three.

Table 7.3 summarises the actions necessary to effect the detachment of a subexpression under various conditions. Note that the ' $k$ ' and ' $\mathrm{k}+\mathrm{l}$ ' on the expressions are indices.

So far we have considered only the detachment of a single component. When several components are involved it would not be a good approach to handle the detachment by detaching each component independently.


Figure 7.3 Component Detachment

This is because the "V(i)" and "N(i)" of affected operators may be corrected more than once. Affected indices may, as before, be corrected after each component is detached. However the correction of affected "V(i)" and "N(i)" should be deferred until all detachable components have been removed.

As an illustration consider the detachment* of $D$ and of $P$ (the first one) from $\xi^{5}$. We detach $D$ first say, and then $P$ flagging affected operators in each case. Affected "V(i)" and "N(i)" are then corrected. Figure 7.4 shows what happens in three stages.

* In TPS, we detach on ly components at the outermost level; so this cxample is more general than we need in TPS.

| Expression | $\begin{gathered} \text { To } \\ \text { Detach } \end{gathered}$ | Delinking Action | Besultant Expression | Correction |  |
| :---: | :---: | :---: | :---: | :---: | :---: |
|  |  |  |  | Indices | V(i) and N(i) |
| $\ldots{ }^{k} \sum_{F_{1}}^{F_{1} F_{2}}$ | $\mathrm{F}_{1}$ | Delink $+\& \mathrm{~F}_{1}$ | $\ldots \stackrel{K}{F}_{2} \ldots$ | none | $\underline{O L} \mathrm{Op}\left(\mathrm{F}_{2}\right), \mathrm{Op}^{2}\left(\mathrm{~F}_{2}\right), \ldots$ |
| $\ldots{ }^{k} \ln _{1} \frac{k}{F_{2}}$ | $\mathrm{F}_{2}$ | Delink $+\& \mathrm{~F}_{2}$ | $\ldots F_{1} \ldots$ | Reduce all <br> indices in $\mathrm{F}_{1}$ by 1 | $i=0 p\left(F_{1}\right), \mathrm{op}^{2}\left(\mathrm{~F}_{1}\right), \ldots$ |
| $\ldots \operatorname{lam}_{1}^{k} F_{2} \ldots$ | $\mathrm{F}_{1}$ | Delink $\mathrm{F}_{1}$ <br> Change - to : | $\ldots k_{2} . .$ | none | $i=0 p\left({ }_{x} \mathrm{~F}_{2}\right), \mathrm{Op}^{2}\left({ }_{\sim} \mathrm{F}_{2}\right) \ldots$ |
|  | $\mathrm{F}_{2}$ | Delink - \& F2 | $.{ }_{-\quad k+1}^{\mathrm{F}_{1}} .$ | Reduce all <br> indices in $\mathrm{F}_{1}$ by 1 | $i=0 p\left(F_{1}\right), o p^{2}\left(F_{1}\right), \ldots$ |
| $\ldots{ }_{*_{1} F_{1} F_{2}^{k} \ldots}$ | $F_{1}$ | Delink * \& $\mathrm{F}_{1}$ | $\ldots \stackrel{K}{F}_{2} \ldots$ | none | $i=O p\left(F_{2}\right), o p^{2}\left(F_{2}\right) \ldots$ |
| $\ldots{ }^{k \times F_{1} F_{1} F_{2} \ldots}$ | $\mathrm{F}_{2}$ | Delink * \& F2 | $\stackrel{k+1}{F_{1}} \ldots$ | Reduce all indices in $F_{1}$ by 1 | $i=0 p\left(F_{1}\right), \mathrm{Op}^{2}\left(F_{1}\right), \ldots$ |
| $.{ }^{k} / F_{1} k_{2} F_{2}$ | $\mathrm{F}_{1}$ | $\begin{aligned} & \text { Delink } \mathrm{F}_{1} \\ & \text { Change / to } \nabla \end{aligned}$ | $\ldots{ }^{k k}$ | none | $i=O p\left(\nabla F_{2}\right), O p^{2}\left(\nabla F_{2}\right), \ldots$ |
| $. o^{k k+F_{1} F_{2}}$ | $\mathrm{F}_{2}$ | Delink / \& $\mathrm{F}_{2}$ | $\ldots{ }_{2+1}^{F_{1}} \ldots$ | Reduce all indices in $F_{1}$ by 1 | $i=0 p\left(F_{1}\right), o p^{2}\left(F_{1}\right), \ldots$ |

Table 7.3 Subexpression Detachment

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(I): $A-B+(C-D)+P /(C-P * Q)$

(II): $A-B+C+P /(C-P * Q)$
(III): $\mathrm{A}-\mathrm{B}+\mathrm{C}+(\nabla(\mathrm{C}-\mathrm{P} * \mathrm{Q}))$

Figure 7.4 Multiple Component Detachment

The first shows § as a tree prior to the removal of $D$. The second shows the effect of D's removal, the affected operators being flagged with an 'X'. The situation after $P$ is removed is given in the third stage, affected operators are again flagged. Note that the uppermost '+' (node 1) is flagged twice showing that by deferring correction, we have avoided one correction of its value and component count.

The affected values and component counts can now be recomputed by traversing down the final tree. Thus $V^{\prime}(1)=V^{\prime}(2)+V^{\prime}(5)$, $V^{\prime}(2)=V(3)+V(C)$ and $V^{\prime}(5)=1 / V(6)$, where $V^{\prime}(i)$ is the corrected value of $V(i)$. Note that $V^{\prime}(1)$ cannot be evaluated until $V^{\prime}(2)$ and $V^{\prime}(5)$ have been computed. The component counts can be recomputed in a similar way.

## Super-2

Super-2 is a FORTRAN program written to implement the step-size model Model-0, a precursor to Model-A. It runs on a CDC 6400 in about 35K (octal) of central memory although this requirement can be reduced to about 25 K by removing the many diagnostic and debugging codes and revising the program. A listing of Super-2, together with its data of sixteen proofs, are given in Appendix $D$.

The main aims of Super-2 have been the following.
(1) To check out an actual step-size model, in fact one which has many features in common with Model-A and Model-B.
(2) To verify the effectiveness of the various ideas we have proposed. These include C-sets, our representative point technique and substep resolution.
(3) To give us some idea of the programming efforts required to implement TPS fully and an appreciation of the practical problems that may be expected.
(4) To provide us with some data on the likely performance of TPS, at least in its proof-checking aspects. We are anxious to confirm that it will be efficient enough to meet our real-time objectives.

## The Program

Super-2 reads in a proof ' $e_{1}=e_{2}=\ldots-e_{n}$ ' and generates the $\binom{n}{2}$ steps $e_{i} \not{ }^{\gamma}{ }_{j}(l \leqslant i<j \leqslant n)$. The proof expressions are checked for correctness of syntax. Each step is analysed for step-size in turn.

When a step is analysed its expressions are first converted into early prefix Polish and maintained as a doubly-linked list. The conversion is done by scanning an expression backwards, using an operator stack and a table of operator hierarchies. The Polish string is thus generated in reverse. As each element of the string is produced, its index and its MXC and MNC values are computed and appended.

Figure 7.5 below shows one cell of a list made up of four words $A C, B C, I C$ and $K C$. $A C$ and $B C$ hold the $M X C$ and MNC values while $K C$ holds the index.* IC contains the left and right links as well as identifying information for this element of the Polish string. Super-2 does not use any component count although this can be easily packed into IC if required. For the computation of the index, MXC and MNC values three stacks are used.

[^18]

Figure 7.5 A List Cell

$$
\begin{aligned}
\text { RL } & \text { right link (9 bits) } \\
\text { LL - } & \text { left link ( } 9 \text { bits) } \\
\mathrm{X} & \text { - identifier for number } \\
& \text { constant, operator and } \\
& \text { trig. function. }
\end{aligned}
$$

When the expressions of a step are converted into their Polish lists, their MNC values are compared. If they are equal (subject to a tolerance factor of $10^{-8}$, then the step is algebraic and it is not analysed any further. If the MNC values are unequal, then the MXC values are compared; non-equality implies that the step is incorrect.

Super-2 performs only the additive, multiplicative and exponential resolutions, and these are done at the primary level only. The sequential resolution method is used. Super-2 employs the schedules $1-1,1-2,2-1, \ldots .2-3,3-2$ and 3-3. In the analysis of the 207 sample steps, the last five schedules were found to be redundant.

Super-2 decomposes a step as far as possible into its substeps before testing for primitiveness. A-steps, being regarded as small, are not tested for primitiveness. To be primitive, the c-set of a step must be singleton. Furthermore it must satisfy one of the discrepancy tests explained below.

Let $F \rightarrow G$ be a permitted variant of the reference identity Ii (or $J_{j}$ ) and let $\underset{\sim}{U}$ be an arbitrary point from $\mathbb{R}^{6}$ that is not from an $S$-set (apart from $U^{n}$ ). Define the difference discrepancy DD as $\left|F^{\circ}(\underset{\sim}{U})-G^{\circ}(\underset{\sim}{U})\right|$ and the ratio discrepancy RR as $\left|F^{\circ}(\underset{\sim}{U}) / G^{\circ}(\underset{\sim}{U})\right|$ (provided $\left.G^{\circ}(U) \neq 0\right)$. DD would in general be nonzero and $R R$ not equal
to 1. Let $f \rightarrow g$ be a step whose $C$-set is $\{I i\}$. Then we have the following criteria of primitiveness.
(I) $\mathrm{f} \rightarrow \mathrm{g}$ is primitive if and only if $\left|\mathrm{f}^{\circ}(\underset{\sim}{\mathrm{U}})-\mathrm{g}^{\circ}(\underset{\sim}{\mathrm{U}})\right|=\mathrm{DD}$ (difference criterion).
(2) $f \rightarrow g$ is primitive if and only if $\left|f^{\circ}(\underset{\sim}{U}) / g^{\circ}(\underset{\sim}{U})\right|=R R$ or $\left|g^{\circ}(\mathrm{U}) / \mathrm{f}^{\circ}(\underset{\sim}{\mathrm{U}})\right|=R \mathrm{R}$ (ratio criterion).
(3) $f \rightarrow g$ is primitive if it is so by (1) or (2) (mixed criterion). These criteria roughly cover the specifications in Model-A for primitive $T$-steps together with the step composition rule $W_{5}$, without rigorously implementing the model.

Since standard FORTRAN has no list-processing facility, Super-2 has provided its own. It maintains an available cells list (ACL) which is initialised to 511 cells of four words each. Idle cells are returned to the bottom of ACL while cells requested are released from the top. Various subroutines and functions perform the list-processing functions such as the linking and delinking of cells. In our experiment on the 207 steps, it was found that not more than 160 cells were in use at any one time. This shows that we can easily reduce the size of our ACL if desired.

Experiments With Super-2
Super-2 was used to analyse the steps generated from the sixteen proofs shown in Table C.3. The analysis was carried out under the three different criteria for primitive $T$-steps listed above. The results under each criterion are shown in the table under the headings RUN-1, RUN-2 and RUN-3. These correspond to the mixed, the difference
and the ratio criteria respectively.

RUN-1 was performed under the two different conditions:
(1) the MXC and MNC values are recomputed whenever required;
(2) the MXC and MNC are computed only once and saved.

The aim of this experiment is to assess the gain in speed derived from saving the MXC and MNC values. The times taken to check each step are shown in the table, TIME-A for condition (1) and TIME-B for condition (2). $N$-COMP in the table gives approximately the number of numeric tests involved in the analysis of each step under RUN-1.

Ignoring the algebraic steps, it can be seen that TIME-A is about $2 \frac{1}{2}$ to 3 times as large as TIME-B and that this ratio tends to be higher as the value of $N$-COMP gets larger. This experiment has demonstrated a significant gain in speed in saving the MXC and MNC values. It also shows that most of the steps can be checked in less than 0.1 second and often much less.

Super-2 has also been modified to perform the latent structure analysis shown in Table C. 4.

## Chapter VIII

## CONCLUDING REMARKS AND RECOMMENDATIONS

We have described our work in computer-assisted instruction and our investigation into the problem of supervising trigonometric proofs in CAI.

Chapter II described UACAIS, our experimental CAI system and offered some suggestions for its modification and extension. In Chapter III the author language ALFIE was described. Chapter IV introduced the problem of supervising trigonometric proofs and discussed its context and scope. It also examined the problem of expression equivalence and developed the theory of consistency sets. Chapter $V$ was devoted to the step-size problem. It described a schema for defining small step models. Chapter VI considered the problem of assisting the student in his proof and described an approach for developing an automatic proof constructor. Chapter VII dealt with some of the important practical problems in the implementation of our proposed proof supervisor.

Although we have spent far more time developing our CAI system than investigating proof supervision, it is the latter that is more important and original. The following points summarize the main significance of our work.
(1) UACAIS is the first major effort in CAI in Australia.
(2) ALFIE is a cue-oriented author language. This special feature makes it especially suitable for programming
the test-first-inform-later instructional paradigm. TFIL can be used as a vehicle for guided discovery teaching and for course revision. It is also a very cheap way of preparing adaptive, branching programs. The full potential of TFIL has yet to be explored.

We have been able to relate our theory of consistency sets and the associated numeric test to algebraic geometry. In particular the application of Hilbert's Nullstellensatz is interesting.
(6) We have developed a schema for defining small steps and we were able to derive good empirical models for
step-size from it. In particular we have derived Model-A and Model-B, the latter being much easier to implement than the former since it has a simpler definition for primitive $T-s t e p s$.

We have proposed an approach for generating trigonometric proofs which we believe to be effective and feasible. It utilises several numeric-oriented heuristics including C-set determination and latent structure probing.
(8) Latent structure is itself an interesting concept and it is very useful because it can be detected by simple numeric tests. It provides the identity prover with an additional measure of look-ahead.
(9) Our indexing scheme is a novel technique for imposing relevant structures on the polish string of an expression, thereby expediting the various subexpression manipulation tasks encountered in TPS. Such an indexing scheme could well find new applications in the area of formula manipulation.
(10) The most significant contribution of our work in proofsupervision is perhaps in its indirect; long term implications. We have adopted a largely numeric approach for solving problems that are essentially symbolic. The numeric approach should be used for detecting subexpression equivalence in program compilation where the potential benefits have to be traded-off against the cost of deriving them. More importantly however
it is hoped that our work here will stimulate others to look into the possibility of using numeric techniques for solving symbolic problems.

## Suggestions for Further Work

In this research we have not been able to carry out fully the various experiments and investigations. Also our efforts so far have opened up new areas to explore. We would like to suggest follow-up studies in the following:
(1) In the area of CAI, to investigate the test-first-inform-later instructional technique using ALFIE. Experiments should be conducted to assess the comparative effectiveness of TFIL. Other areas of potential application of TFIL should also be examined.
(2) TPS should be implemented. Initially this may be done off-line to check out the proof-checking and proofgenerating components first. Eventually however it should be integrated into UACAIS so that its performance in a CAI environment may be studied. In particular we wish to ensure its real-time capability. Many of the essential ideas of TPS have already been successfully implemented in super-2. Several others have also been tested separately. We therefore foresee no feasibility problem in the implementation of TPS. For step-size analysis, we would urge the adoption of Model-B.
(3) We should investigate the effectiveness of TPS as an
aid in the teaching of trigonometry. How does TPSassisted teaching compare with the traditional method of teaching the subject? Is the effectiveness of TPS adversely affected by its communication interface? Is the keyboard a serious impediment to the usefulness of TPS?

Extend our numeric approach for proof supervision to the multi-argument trigonometric problems, in which the addition, product and multiple argument formulae are permitted. Here we are no longer working with only twelve reference identities. An indefinite number of reference identities may have to be considered since the number of arguments may vary. We have already looked into the problem partially and have found the idea of independence and interdependence of classes of arguments relevant. This is to detect classes of relevant reference identities.
(5) Attempt extending our numeric approach to other areas of mathematics. The most immediate area the hyperbolic functions since these in many ways resemble the trigonometric functions. However it would be interesting if we could devise cheap numeric techniques to aid in symbolic (i.e. formal) differentiation and integration, in contrast to the approach of slagle [66].
(6) Attempt to extend our numeric approach philosophy to traditionally symbolic problems with the aim of
finding better and cheaper methods of solution. One target area is the field of formula manipulation [lo].

## APPENDIX A

## A

MANUAL AND AUTHOR GUIDE

FOR

ALFIE

ADELAIDE LANGUAGE FOR INSTRUCTION AND EDUCATION (VERSION 1.0)

FEBRUARY 1969

2ND REVISION - OCTOBER 1970

## LEE KIM CHENG

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## A-1

## INTRODUCTION

ALFIE, the Adelaide Language for Instruction and Education is the language for writing teaching programs for the University of Adelaide Computer-Assisted Instruction System (UACAIS). The version being described is designated ALFIE 1.0 and represents the latest development in the language as of October 1970.

This manual is intended to be both an author guide and a description of ALFIE. Course preparation will be described in the context of the card medium only; paper tape and on-line keyboard entry facilities are not yet available.

An author language is an integral part of a CAI system. It is designed to give the author convenient access to the various CAI facilities in a system. These facilities usually include those for presenting stimulus material (e.g. typewriter text, CRT display, etc.), analysing student responses, sequencing course material, branching, and recording student responses and performance data.

In designing CAI languages, a popular objective has been to make them easy to learn and convenient to use. Thus users are not required to be familiar with computers. As far as possible, subject to the limitations imposed by available hardware, ALFIE has been designed with this in mind.

## OVERVIEW OF UACAIS

UACAIS is a dedicated CAI system based on the computing centre's CDC 6400 machine. Thus when under CAI operation, it may not process non-CAI jobs. The system has been designed to drive up to 512 remote student consoles - of which four are implemented at present. Each console consists of an IBM Selectric typewriter, but other pieces of terminal equipment may be added in future.

Courses are prepared off-1ine on cards and are then assembled by the ALFIE course compiler onto magnetic tape for subsequent use under JACAIS. During CAI operation, required courses are loaded from magnetic tape onto the disc, ready for use.
A-2

Students sitting at the remote consoles receive their lessons on the typewriter and communicate with the system via the keyboard. Different students may be receiving different segments of a course simultaneously and independently. More than one course may be conducted by the system at any one time.

## TYPEWRITER CHARACTERS \& CONTROL FUNCTIONS

The characters available on the typewriters are :-
(1) Alphabetic $A B C \ldots X Y Z$ a b c.... $x$ y $z$
(2) Numeric
$123 \ldots 7890$
(3) Special
$+-* /() \$=b l a n k$, . [ ] \# : ' 。 \& " \% @ \& ? ! ;

Available control functions are: carriage return, index, tab, backspace and black and red ribbon select.

Textual material must be composed from this set of characters and functions only. Since not all these are available on a standard card punch, a card code for representing them is required. Table A. 1 gives the list of all available typewriter characters and functions and their card codes, based on the IBM 029 punch, as well as other codes, as explained below :-

| Table Column <br> 1 |  | Description <br> 2 |
| :---: | :--- | :--- |
|  | Kellerith Punch key combination on IBM 029 which <br> gives this Hollerith punch |  |
| 3 | corresponding CDC 6400 display code |  |
| 4 | corresponding line-printer character |  |
| 5 | corresponding 7-bit typewriter code |  |


| HOLLERITH | 029 | KEY | DC | DC CHAR | TW CODE | TW CHAR | REMARK |
| :--- | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| $12-1$ | A | 01 | A | $x 16$ | A/a | $x=0$ for upper and |  |
| $12-2$ | B | 02 | B | $\times 01$ | B/b | $x=1$ for lower cases |  |
| $12-3$ | C | 03 | C | $x 15$ | C/C |  |  |
| $12-4$ | D | 04 | D | $x 55$ | D/d |  |  |
| $12-5$ | E | 05 | E | $\times 51$ | E/e |  |  |


| HOLLERITH | 029 KEY | DC | DC CHAR | TW CODE | TW CHAR | REMARK |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 12-6 | F | 06 | F | $\times 34$ | F/f |  |
| 12-7 | G | 07 | G | $\times 74$ | G/g |  |
| 12-8 | H | 10 | H | $\times 41$ | H/h |  |
| 12-9 | I | 11 | I | $\times 12$ | I/i |  |
| 11-1 | $\checkmark$ | 12 | J | $\times 70$ | J/j |  |
| 11-2 | K | 13 | K | $\times 11$ | K/k |  |
| 11-3 | L | 14 | L | $\times 45$ | L/1 |  |
| 11-4 | M | 15 | M | $\times 76$ | M/m |  |
| 11-5 | N | 16 | N | $\times 31$ | $\mathrm{N} / \mathrm{n}$ |  |
| 11-6 | 0 | 17 | 0 | $\times 46$ | 0/0 |  |
| 11-7 | P | 20 | P | $\times 50$ | $\mathrm{P} / \mathrm{p}$ |  |
| 11-8 | Q | 21 | Q | $\times 10$ | Q/q |  |
| 11-9 | R | 22 | R | $\times 56$ | $\mathrm{R} / \mathrm{r}$ |  |
| 0-2 | S | 23 | S | $\times 42$ | S/s |  |
| 0-3 | T | 24 | T | $\times 71$ | T/t |  |
| 0-4 | U | 25 | U | $\times 35$ | U/u |  |
| 0-5 | $V$ | 26 | V | $\times 36$ | V/v |  |
| 0-6 | W | 27 | W | $\times 02$ | W/w |  |
| 0-7 | $x$ | 30 | $\chi$ | $\times 75$ | $x / \mathrm{x}$ |  |
| 0-8 | Y | 31 | Y | $\times 40$ | Y/y |  |
| 0-9 | Z | 32 | Z | $\times 73$ | Z/z |  |
| 0 | 0 | 33 | 0 | 143 | 0 |  |
| 1 | 1 | 34 | 1 | 177 | 1 |  |
| 2 | 2 | 35 | 2 | 133 | 2 |  |
| 3 | 3 | 36 | 3 | 137 | 3 |  |
| 4 | 4 | 37 | 4 | 147 | 4 |  |
| 5 | 5 | 40 | 5 | 153 | 5 |  |
| 6 | 6 | 41 | 6 | 113 | 6 |  |
| 7 | 7 | 42 | 7 | 157 | 7 |  |
| 8 | 8 | 43 | 8 | 117 | 8 |  |
| 9 | 9 | 44 | 9 | 103 | 9 |  |
| 12 | + | 45 | + | 030 | + | - |
| 11 | - | 46 | - | 100 | - |  |
| 11-8-4 | * | 47 | * | 017 | * |  |
| 0-1 | 1 | 50 | 1 | 144 | 1 |  |
| 0-8-4 | $($ | 51 | ( | 003 | $($ |  |
| 12-8-4 | ) | 52 | ) | 043 | ) |  |
| 11-8-3 | \$ | 53 | \$ | 047 | \$ |  |
| 8-3 | $=$ | 54 | $=$ | 130 | $=$ |  |
| no punch | blank | 55 | blank | 020 | blank |  |
| 0-8-3 | , | 56 | , | 014 | , |  |
| 12-8-3 |  | 57 | 。 | 032 | - |  |
| 0-8-6 | S | 60 |  |  |  | lower case flag |
| 8-7 | C | 61 |  | 077 | [ |  |
| 0-8-2 | $\dagger$ | 62 | 三 | 037 | \# |  |
| 8-2 | D | 63 | : | 054 | , |  |
| 8-4 | $\bar{T}$ | 64 | $\neq$ | 152 | ' | single quote |
| 0-8-5 | W | 65 | $\rightarrow$ | 072 | ${ }^{\circ} \mathrm{O} \mathrm{r}^{\frac{3}{4}}$ | single quote |

## A-4

| HOLLERITH | 029 KEY | DC | DC CHAR | TW CODE | TW CHAR | REMARK |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 11-0 | B | 66 |  | 057 | \& |  |
| 11-8-5 | E | 70 | $\uparrow$ |  |  | upper case flag |
| 11-8-6 | F | 71 | $\downarrow$ | 052 | " | double quote |
| 12-0 | R | 72 |  |  |  | null character |
| 11-8-7 | G | 73 | > | 053 | \% |  |
| 8-5 | A | 74 | $\leqslant$ | 013 | \$ |  |
| 12-8-5 | N | 75 | $\geqslant$ | 044 | ? |  |
| 12-8-6 | 0 | 76 | $\rightarrow$ | 172 | tor $\frac{1}{2}$ |  |
| 12-8-7 | P | 77 | ; | 154 | ; |  |
|  | 8 A |  |  | 033 | @ |  |
|  | 8 C |  |  | 024 |  | carriage return |
|  | XI |  |  | 023 |  | index |
| - | XR |  |  | 026 |  | red ribbon |
|  | XB |  |  | 027 |  | black ribbon |
|  | XT |  |  | 025 |  |  |
|  | 8- |  |  | 000 | - | underscore end-of-card |
|  | 又 |  |  | 021 |  | a backspace |

The specification Rny or Xnny where $n$ is any digit $0,1, \ldots, 9$ and $y$ is any of $C, A, I, R, B, T$, - and blank means $n$ or $n n \bar{X} y$ ' $s$ where the meaning of $X y$ for various $y$ is as given above. Any $\bar{X} v$ not corresponding to any of the above combinations will be treated as $\bar{X} \bar{X}$ - the end-of-card code.

## TABLE A. 1 CARD CODES

The ' $x$ ' used in column 5 takes the value 0 or 1, depending on whether the letter is in the upper or the lower case. In column 2, D (d-bar) refers to the upper case of the D key on the IBM 029; similarly for S, E, R, etc. ${ }^{\bar{T}}$ refers to the lower case of the ' $=$ ' key.

There are two case flags: the upper, $E$, and the lower $\bar{S}$. The presence of an $E$ in a text stream (see below) indicates that all subsequent letters are in the upper case until an $\bar{S}$ is encountered. Similarly when an $S$ occurs the lower case prevails until an $E$ appears.

The R punch is for the null character - and is used to suppress a space. It is useful for card correction. For instance, if we have 'SPEED' on a card, but discover that it should have been 'SPED' instead,

## A-5

we can effect the necessary correction by duplicating the card, but replacing one of the E's with an R as in 'SPERD'.

XR selects the red ribbon and $\bar{X} B$ the black. $\bar{X} T$ sends a tab function. It is assumed that the tab spacing has been set at columns $11,21,31,41, \ldots$ etc. $\bar{X} C$, the carriage return, positions the typewriter carriage to the left margin of the next line. $\bar{X} \bar{X}$ is the end-ofcard code, and indicates that subsequent punches on the card are to be ignored.

Whether we get a $\frac{1}{4}$ or $\circ$ for the code 072 depends on the typeball; some carry ${ }^{\circ}$ while others carry the $\frac{1}{4}$. Similar remarks apply to the T/W code 172.

The remaining codes in the table should be now self-explanatory.

## THE TEXT STREAM

A text stream is a string of typewriter (T/W) codes to be output on the typewriter. It is punched as a set of successive textbody cards (TBCs), bounded by two keyword cards (KWCs). A line or a paragraph of text may be coded on one or more TBCs. The following example illustrates the coding of text in ALFIE. We assume all punches begin on column 2 of the cards here.
e.g. 1 Intended T/W output:
"The vowels of the alphabet are a, e, i, o and u." This may be coded as:

ETS̄HE VOWELS OF THE ALPHABET ARE A, E, I, 0 AND U. $\bar{\chi} \bar{X}$
The same output may be more wastefully coded on two cards as
HABET ARE A, E, I, 0 AND U. $\bar{X} \bar{X} \quad$ card 2
ETS̄HE VOWELS OF THE ALP玟 card 1
The 1st punch E calls for capital letters, but this affects only the 1st letter ' $T$ ' since an $\bar{S}$ is immediately encountered, setting all subsequent letters to the lower case. Note the use of $\bar{X} \bar{X}$.
e.g. 2 To output the following tabular text:

| Country | $\frac{\text { Capital }}{\text { Australia }}$ |
| :--- | :--- |
| China | Peking |
| Canada | Ottawa |
| U.A.R. | Cairo |

with the two columns set at 11 and 31 . This table may be coded as :-

## 


(Note the use of $\bar{X}, \bar{X} T, \bar{X} C$ and $\bar{X}$ - for backspace, tab, $c / r$ and underscore.)
e.g. 3 To output $\sin (\phi+\theta)=0.1624^{\prime \prime}$ we need punch only:
SSIN(EOX /+0X -)=0.1624X又

A basic problem in the off-line preparation of text concerns the line limit and justification. It is indeed a tedious job for the author to keep track of his text, making sure that each line does not exceed the limit set; line-justification is even more involved. With an on-line keyboard entry facility, a larger part of this problem would simply be non-existent. As an aid for the ALFIE author, we have included a simple text-editing facility through the EDIT card.

## $=\operatorname{EDIT}(\mathrm{n}, \mathrm{m})$

$n$, which takes a value between 40 and 80 inclusive, specifies the width over which a line of text is to be truncated and justified. If justified, the text will be dispersed randomly over columns 1 through $n$ subject to mode $m$, where $m$ can be one of the following:
$\mathrm{m}=0$ - break string and resume on the next line when current word extends beyond column n. Do not distribute the words.
$\mathrm{m}=1$ - truncate current line and continue on the next line when current word exceeds column n. Distribute words over the field (columns 1 to $n$ ) overriding any $c / r$ which occurs after column n-7.

## A-7

$m=2$ - as for $m=1$, but do not override any $c / r$.
Each EDIT specification holds at a new text stream, and applies to all subsequent text until a new EDIT is encountered. The default EDIT specification is ${ }^{\prime}=\operatorname{EDIT}(80,1)$ '.

The following listings (Figures A. 1 and A.2) illustrate the use of the EDIT card. They also show the two listings produced by ALFIE .. one, Figure A.1, by the course preprocessor, and this is the source deck 1lsting; the other, Figure $A .2$, is produced by the compiler proper. Note that in the source deck listing $X$ is shown as $\wedge, E$ as $\uparrow$, and so on, as shown in Table A. 1.

## COMPILATION OF ALFIE PROGRAMS

In preparing a course, we must first of all code it in detail. This course is then punched on cards, and the course deck is set up as a job deck (computer program) to be read by the card reader. Before it can be used, it must be checked and if satisfactory, converted into its object code form and output on magnetic tape. The course in its object code form, may then be loaded during a CAI run, to be executed interpretively by a resident central program.

The process of converting a course on deck into its object code form is called an assembly or a compilation, and the computer program which actually carries this out is called an assembler or a compiler.

A course is assembled in two stages. The first stage is performed by LKC, a preprocessor program for translating the course in its card format into a common intermediate code called CONCODE. The actual assembler ALF then carries out the second stage by accepting a course in CONCODE and producing the object codes. It can be seen that we have made provisions for a course to be prepared in other media; all that would be required for a new medium is a corresponding preprocessor for converting a course in that medium into the CONCODE. Figure A. 3 illustrates the approach just discussed.

## A－8

| SCOURSE，DEMON |  |  |  |  |  |  |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| SCHAPTER，ONE． |  |  |  |  |  |  |  |  |  |  |  |  |  |
| SPAGE，R55． |  |  |  |  |  |  |  |  |  |  |  |  |  |
| －IEN＊OEMEGA／55＋FORTRAN EYOU CAN HAVE A MAXIMUM OF FIFTEEN＋DO－ELOOPS WITHIN O |  |  |  |  |  |  |  |  |  |  |  |  |  |
| NE NEST，ALTHOUGH PROBLEMS SELDOM ARISE THAT REQUIRE MORE THAN TWO OR THREE LOO |  |  |  |  |  |  |  |  |  |  |  |  |  |
| PS WIT＜＜HIN LOOPS，$\uparrow$ UEUITE OFTEN YOU WILL WANT TO USE TDO\＃E゙LOOPS END TO END INSI |  |  |  |  |  |  |  |  |  |  |  |  |  |
| DE ANOTHER $\uparrow$ DO－ELOOP，AA |  |  |  |  |  |  |  |  |  |  |  |  |  |
| $=\operatorname{EDIT}(45.1)$ |  |  |  |  |  |  |  |  |  |  |  |  |  |
| STEXT． |  |  |  |  |  |  |  |  |  |  |  |  |  |
| ศIEN $\uparrow$ OEMEGA／55 ศFORTRAN EYOU CAN HAVE A MAXIMUM OF FIFTEEN PDO～ELOOPS WITHIN O NE NEST．ALTHOUGH PROBLEMS SELDOM ARISE THAT REQUIRE MORE THAN TWO OR THREE LOO |  |  |  |  |  |  |  |  |  |  |  |  |  |
|  |  |  |  |  |  |  |  |  |  |  |  |  |  |
| PS WIT＜＜HIN LOOPS．qGEUITE OFTEN YOU WILL WANT TO USE ¢DO＝ELOOPS END TO END INSI |  |  |  |  |  |  |  |  |  |  |  |  |  |
| DE ANOTHER ¢DO－ELOOP＊AA |  |  |  |  |  |  |  |  |  |  |  |  |  |
| $=E D I T(70,2)$ |  |  |  |  |  |  |  |  |  |  |  |  |  |
| ＋ |  |  |  |  |  |  |  |  |  |  |  |  |  |
|  <br> （J） 12 C <br> EWILL CAUSE STATEMENT 10 TO 日E EXECUTED ONE HUNORED TIMESOAA |  |  |  |  |  |  |  |  |  |  |  |  |  |
|  |  |  |  |  |  |  |  |  |  |  |  |  |  |
| ＝EDIT（65．1） |  |  |  |  |  |  |  |  |  |  |  |  |  |
| \＄TEXT． |  |  |  |  |  |  |  |  |  |  |  |  |  |
| ＾TEHE ¢FORTRAN ERULE OF HIERARCHY CONSISTS，THEN，OF THREE PARTS：A2C |  |  |  |  |  |  |  |  |  |  |  |  |  |
| EXPONENTIATION（IF ANY）IS DONE FIRST．AC 2．＾AELL MULTIPLICATION AND／OR DIVISI |  |  |  |  |  |  |  |  |  |  |  |  |  |
| ON（IF ANY）IS DONE SECOND．AC 3．AABLL ADOITION AND／OR AA |  |  |  |  |  |  |  |  |  |  |  |  |  |
| SUHTRACTION（IF ANY）IS＜＜＜＜DONE LASY．AA |  |  |  |  |  |  |  |  |  |  |  |  |  |
| ＝ED）T（40，1） |  |  |  |  |  |  |  |  |  |  |  |  |  |
| STEXT． |  |  |  |  |  |  |  |  |  |  |  |  |  |
| ＾TEHE＾FORTRAN ERULE OF HIERARCHY CONSISTS，THEN，OF THREE PARTS：＾2C 1．＾A |  |  |  |  |  |  |  |  |  |  |  |  |  |
| EXPONENTIATION（IF ANY）IS DONE FIRST．AC Z：AAELL MULTIPLICATION ANO／OR DIVISI |  |  |  |  |  |  |  |  |  |  |  |  |  |
|  |  |  |  |  |  |  |  |  |  |  |  |  |  |
| SUBTRACTION（IF ANY）IS＜＜＜＜DONE LAST$=$ EOIT 60.1$)$ |  |  |  |  |  |  |  |  |  |  |  |  |  |
|  |  |  |  |  |  |  |  |  |  |  |  |  |  |
| \＄TEXT． |  |  |  |  |  |  |  |  |  |  |  |  |  |
| ＾I三N EVERYUAY PRACTICE，THIS PROBLEM IS AGGRAVATED GY THEACFACT THAT SOME O |  |  |  |  |  |  |  |  |  |  |  |  |  |
| F THE TCAI 三LANGUAGES WHICH THE INSTRUCTORACMUST USE TO SPECIFY HIS REQUIREMENT |  |  |  |  |  |  |  |  |  |  |  |  |  |
| S FOR ACCEPTABLEACRESPONSES DO NOT ALLOW EVEN THE PRIMITIVE LEVEL OF ANALYSISAC |  |  |  |  |  |  |  |  |  |  |  |  |  |
| REPRESENTED BY SUCH PROCEDURES AS SCANNING FOR KEYWORDS，ACEDITING OUT PUNCTUATI |  |  |  |  |  |  |  |  |  |  |  |  |  |
| ON，ALLOWING CERTAIN FLEXIBILITY IN ACSPELLING，ETC．AA |  |  |  |  |  |  |  |  |  |  |  |  |  |
| ＝EDIT（60，2） |  |  |  |  |  |  |  |  |  |  |  |  |  |
| STEXT． |  |  |  |  |  |  |  |  |  |  |  |  |  |
| TI三N EVERYDAY PRACTICE，THIS PROBLEM IS AGGRAVATED BY THEACFACT THAT SOME O |  |  |  |  |  |  |  |  |  |  |  |  |  |
| $F$ THE ¢CAI 三languages which the instructoracmust use to specify his requirement |  |  |  |  |  |  |  |  |  |  |  |  |  |
| S FOR ACCEPTABLEACRESPONSES DO NOT ALLOW EVEN THE PRIMITIVE LEVEL OF ANALYSISAC |  |  |  |  |  |  |  |  |  |  |  |  |  |
| REPRESENTED BY SUCH PROCEDURES AS SCANNING FOR KEYWORDS•ACEDITING OUT PUNCTUATI |  |  |  |  |  |  |  |  |  |  |  |  |  |
| ON，ALLOWING CERTAIN FLEXIEILITY IN ACSPELLING，ETC．AA |  |  |  |  |  |  |  |  |  |  |  |  |  |
| \＄E | END |  |  |  |  |  |  |  |  |  |  |  |  |


| CARD | 0001 |
| :---: | :---: |
| CARD | 0002 |
| CARD | 0003 |
| CARD | 0004 |
| CARD | 0005 |
| CARD | 0006 |
| CARD | 0007 |
| CARD | 0008 |
| CARD | 0009 |
| CAHD | 0010 |
| CARO | 0011 |
| CARD | 0012 |
| CARD | 0013 |
| CARD | 0014 |
| CARD | 0015 |
| CARD | 0016 |
| CARD | 0017 |
| CARD | 0018 |
| CARD | 0019 |
| CARD | 0020 |
| CARD | 0021 |
| CARD | 0022 |
| CARD | 0023 |
| CARD | 0024 |
| CARD | 0025 |
| CARD | 0026 |
| CARD | 0027 |
| CARD | 0028 |
| CARO | 0029 |
| CARD | 0030 |
| CARD | 0031 |
| CARD | 0032 |
| CARD | 0033 |
| CARD | 0034 |
| CARD | 0035 |
| CARI） | 00.36 |
| CARD | 00.37 |
| CARD | 0038 |
| CARD | 0039 |
| CARD | 0040 |
| CARD | 0041 |
| CARD | 0042 |
| CARD | 0043 |
| CARD | 0044 |

Figure A． 1 Source Card Listing of a Course

| PAGE. 1555. | PAGE OL - CHAPTER ONE | 0550001 |
| :---: | :---: | :---: |
|  | IN OMEGA/55 FORTRAN YOU CAN HAVE A MAXIMUM OF FIFTEEN DO-LOOPS WITHIN ONE NEST | 8550002 |
|  | ALTHOUGH PROELEMS SELDOM ARISE THAT REQUIRE MORE THAN TWO OR THREE LOOPS WITHI | $R 550003$ |
|  | LOOPS, QUITE OFTEN YOU WILL WANT TO USE DO-LOOPS END TO END INSIDE ANOTHE | 8550004 |
|  | DO-LOOP. | 8550005 |
| TEXT. |  | 8550006 |
|  | IN OMEGA/55 FURTRAN YOU CAN HAVE A MAXIMUM OF | R55 0007 |
|  | FIFTELN DO-LOOPS WITHIN ONE NEST, ALTHOUGH | R55 0008 |
|  | PROBLEMS SELDOM ARISE THAT REQUIRE MORE THAN | R55 0009 |
|  | TWO OR THREE LOOPS WITHIN LOOPS. QUIYE OFTEN | R55 0010 |
|  | YOU WILL WANT TO USE DO~LOOPS END TO END | $R 550011$ |
|  | INSIDE ANOTHER DO-LOOP. | H55 0012 |
| p |  | R55 0013 |
|  |  | R55 0014 |
|  |  | R55 0015 |
|  | the sequence | $R 550016$ |
|  | $0010 \quad 1=1010$ | RS5 0017 |
|  | DO 10 Jmal 10 | R55 0018 |
|  |  | R55 0019 |
|  |  | R55 0020 |
| TEXT. | WILL CAUSE STATEMENT 10 TO EE EXECUTED ONE HUNDRED TIMES. | R55 0021 |
|  | THE FORTRAN RULE OF HIERARCHY CONSISTS, THEN. OF THREE PARTSI | R55 0022 |
|  | THE FORIRAN RULE OF HIERARCHY CONSISTS. THEN. OF THREE PARTSI | R55 0023 |
|  | 1. ALL EXPONENTIATION IIF ANY) IS DONE FIRST. | $R 55$ $R 56$ |
|  | 2. ALL MULTIPLICATION ANDIOR DIVISION (IF ANY) IS DONE SECOND. | RS: 0026 |
|  | 3. ALL ADDITION AND/OR SUBTRACTION IIF ANY) IS DONE LAST: | H5: 0027 |
| TEXT. |  | 2550028 |
|  | THE FORTRAN RULE OF HIERARCHY CONSISTS, | R55 0029 |
|  | THEN OF THREE PARTSI | RS5 0030 |
|  |  | R55 00031 |
|  | 1. ALL EXPONENTIATION (IF ANY) IS DONE | 2550032 |
|  | FIRST. | -2550033 |
|  | (IF. ALL MULTIPLICATION ANDIOR DIVISION | 2550034 |
|  | (IF ANY) IS DONE SECOND. | N5 0035 |
|  | 3. ALL ADDITION AND/OR SUBTRACTION (IF | R5¢ 003 n |
|  | ANY) IS DONE LAST. | H55 10017 |
| TEXt. |  | N55 003 |
|  | IN EVERYDAY PRACTICE, THIS PROBLEM IS AGGRAVATED EY THE | W55 0039 |
|  | FACT THAT SOME OF THE CAI LANGUAGES WHICH THE INSTRUCTOR | 255 0040 |
|  | MUST USE TO SPECIFY HIS REQUIREMENTS FOR ACCEPTAQLE | 2550041 |
|  | RESPONSES DO NOT ALLOW EVEN THE PRIMITIVE LEVEL OF ANALYSIS | 255 UU4? |
|  | REPRESENTED BY SUCH PROCEDURES AS SCANNING FOR KEYWORDS, | H5S, 0043 |
|  | EDITING OUT PUNCTUATION, ALLOWING CERTAIN FLEXIBILITY IN | R55 0044 |
|  | SPELLING, ETC. | H55 0045 |
| TEXT. |  | R55 0046 |
|  | IN EVERYUAY PRACTICE, THIS PROBLEM 15 agghavated by the | RS5 0047 |
|  | FACT THAT SOME OF THE CAI LANGUAGES WHICH THE INSTRUCTOR | R55 004 H |
|  | MUST USE TO SPECIFY HIS REQUIREMENTS FOR ACCEPTABLE | 2550044 |
|  | HESPONSES DO NOT ALLOW EVEN THE PRIMITIVE LEVEL OF ANALYSIS | 2550050 |
|  | REPRESENTED BY SUCH PROCEDURES AS SCANNING FOH KEYWORDS, | 8550051 |
|  | EDIYING OUT PUIVCTUATION, ALLOWING CERTAIN FLEXIBILITY IN | 2550052 |
|  | SPELLING, ETC. | W55 0053 |
| END |  | 8550054 |

## A-10



Figure A. 3 Compiling an ALFIE Course

Two kinds of listings are produced when a course is compiled. One is the course card listing produced by LKC as illustrated in Figure A.1. The source card listing can be produced or suppressed by the listing control card (see below). When no LCC is present, the listing status is assumed to be 'on'. The other listing is the assembly listing, produced by ALF as shown in Figure A.2. It will be seen that this listing of the text simulates as closely as the line-printer will permit, its appearance on the typewriter. Thus while spacing, backspace and tab etc. are reflected exactly, this listing is unable to show alphabetic case changes, ribbon changes and certain special typewriter characters like ' \&' and '?'. The assembly listing can be suppressed and reinstated at will by the LIST and NOLIST cards. The initial setting is for listing to be produced.

The assembler listing is an important debugging aid for ALFIE programs and greatly compensates for the very ungainly card codes for text.

LKC distinguishes five kinds of course cards, by examining the first column of the cards. These five kinds are :-
(1) Listing Control Card (LCC): This has a 2-8 (D on IBM 029) punch on column 1. The LCC acts as a source listing switch, turning the listing status to 'on' if it is 'off' and vice versa. It does not produce any object code.
(2) Comment Card (CC): A comment card is characterised by a * on column 1 and is used for passing comments on the source and assembly listings. The whole 80 columns of a CC is listed, if the listing status is 'on'. No object code is produced for the CC.
(3) Edft Card (EC): Has ' $=$ ' on column 1 and 'EDIT' on the next four columns. Its use has been explained above.
(4) Keyword Card (KWC): A card with a '\$' or ' $\rightarrow$ ' ( $(\mathbb{1}$ on 029) on column , and a 'C' if it is a continuation KWC. KWCs are used for specifying course directives. . In a KWC, blanks are ignored except in an answer string.
(5) Textbody Card (TBC): A TBC is a card which is not an LCC, CC, EC or KWC and usually with column 1 blank. If column 1 is not blank, then a warning 'TBC' is tagged alongside its source listing. If column 1 of a TBC is blank, then its contents are assumed to begin on column 2 and end on the first end-of-card code $\bar{X} \bar{X}$, or on column 80 in the absence of the 双.

## ALFIE THE LANGUAGE

A course in ALFIE is a sequence of directives and texts. Directives are KWCs while texts are made up of TBCs, as explained earlier. 'A course is organised into an arbitrary number of named chapters, each of which comprise of from one to sixty-four named pages.

A KWC begins with a '\$' or a ' $\rightarrow$ ' ( $W$ on the IBM 029) on column 1, and any continuation KWC must bear a 'C' on column 1. Except in answer specifications, all blanks in a KWC are ignored.

Each directive is associated with a keyword and belongs to one of the three categories :-
(1) listing control
(2) course organisational
(3) command.

We shall now describe the various KWCs in ALFIE and their syntax. Some BNF Definitions:

```
<alphabetic> :}:=A|B|C|D|....|X|Y|Z
<digit> ::= 0|1|2|.... 7|8|9
<alphanumeric> ::= <alphabetic>|<digit>
```



```
<display code> ::= <alphabetic>|<digit>|<special>
<identifier> ::= <alphanumeric>|<identifier><alphanumeric>
```

'<', '>', '::=' and '/|' above are called metalinguistic symbols and
<alphabetic> and <identifier> etc., are metalinguistic variables.
<alphabetic> ::= A|B|C|....|X|Y|Z simply means that the variable
'<alphabetic>' may take the letter 'A' or 'B' or 'C' or ..... or 'Z'.
Similarly the variable identifier represents any non-null alphanumeric
string. Note that the latter variable is defined recursively - i.e. in
terms of itself.
e.g. of '<identifier>' : 'A', '232', 'PX24' and 'FREDERICI'.

We shall also define <name> to be any <identifier> not exceeding 6 characters long. A <name> is used for a label, chapter name or page name. Thus we take <pagename> and <chapter name> to be <name>.

In ALFIE command KWC's may be labelled. A label is any <name> followed by a colon, preceding a keyword.
e.g. $\$$ LX2:PROBLEM,Q02. A label may also appear by itself as in $\$$ TGX: and serves to define a page location. Apart from the implicit label ' $\rightarrow$ ' which appears on column 1 of a KWC, all labels in a given page must be unique. The use of the implicit label will become clear later.

We shall now describe each keyword and the form of its associated command. Before doing so, we explain the 'metalanguage' used. The metalinguistic variable <--> has been explained earlier. The brace pair \{--\} means that one of its contained options must occur. [x] means that the $x$ may, but need not, occur. Other characters shown must occur
literally. Blanks not in answer specifications, will be ignored in a KWC. The column 1 characters of the KWC (viz. '\$', ' $\rightarrow$ ' or 'C') will not be shown, but is taken as understood.
e.g.: GOTO,CHAPTER(\{*|<chaptername>\})[,PAGE(\{*|<pagename>\})]
means that the string 'GOTO,CHAPTER(' must occur, to be followed by either a '*' or a <chaptername>, and then ')', to be further followed optionally by: ',PAGE(', an '*' or a <pagename>, and then a ')'.

Examples of this command are:-
GOTO,CHAPTER(S7),PAGE(X02)
GOTO,CHAPTER(PT2)
GOT0,CHAPTER(*), PAGE(12)
But the following are invalid:-
GOTOCHAPTER(PT2) (no comma)
GOTO,CHAPTER(VERY LONG) (chapter name too long)
Any command not terminated by a ')' may be terminated, but only if desired, by any special character, usually the period. Thus 'LIST', 'LIST.' and 'LIST*' are all equivalent.

The listing control keywords are LIST and NOLIST. These control only the assembler listing and should not be confused with the LCC which affects only the source card listing. We shall refer to non-listing control KWCs as proper.

LIST
e.g。 \$LIST

This is a request to the assembler to produce the assembler listing of all subsequent sectionsof the course, until a NOLIST is encountered. NOLIST
e.g. \$NOLIST

This directive is a request to suppress assembler listing of all subsequent course material unti1 a LIST is encountered.

The course organisational keywords are COURSE, CHAPTER, PAGE and END.

## A-14

## COURSE, <coursename>

e.g. \$COURSE,ALGEBRA
\$COURSE,BOOLEAN
This card begins and names a course. The <coursename> is any <identifier> not exceeding 10 characters. The COURSE must be the first KWC of a course. Following a course KWC, the next KWC, other than listing control, must be the CHAPTER. In a given CAI run, all course names must be distinct.

CHAPTER, <chaptername>
e.g. \$CHAPTER,PDOO3.

This KWC begins and names a new chapter and ends the previous chapter (if any). In a given course, chapter names must be unique. If a chapter name is not acceptable, for reason of syntax or multiplicity, the system generates a name of the form ${ }_{\wedge}$ SYSCHn where $n=1$ for the first system-given chapter name in a course, $n=2$ for the second and so on. The proper KWC which immediately succeeds a CHAPTER must be a PAGE. A course is allowed any number of chapters.

PAGE, <pagename>
e.g. \$PAGE(RR22)

This KWC begins and names a new page of a course, and terminates the previous page (if any). Each chapter may contain as many as 64 pages, but at least one. Page names within a chapter must be unique. If the author-supplied pagename is unacceptable for some reason, then a systemdefined name of the form SYSxxx is substituted. The first such page in a chapter is SYSOO1, the next SYSOO2 and so on.

A page is a unit of a course which can be assembled into a block of central memory words less than or equal to the limit PGSIZE (currently PGSIZE $=464$ ). A page constitutes a segment of a course that may reside in core at any one time during CAI operation. It is also the unit of course which is swapped between disc and core. The first word of a page contains its name, i.e. <pagename>, in display code, left justified zero filled.

If the author attempts to assemble more than PGSIZE words of code into a page, the assembler will try to split in into two (or more) pages, if possible. It does this by accommodating as much into the current page as possible, and attempts to place the remaining codes in a new system-defined page. In splitting a page, a problem block (see later) must not be split between pages. A page which cannot be split without violating this requirement will be abandoned.

The assembler automatically assembles at the end of each page an exit to the next page, unless this is the last page, or its last KWC is COMPLETE or END. The next page above includes the first page of the next chapter, if the current page is the last in a chapter. In the assembler listing of a page, the location at which each command in the page is assembled is also shown. The listing ends with the number of unused central memory words in the page (see Figure A.2).

## END

This keyword ends the current course - this means also that the current page and chapter are also terminated.

As a further illustration of the organisational KWCs, the course listed in Figure A. 1 consists of only one chapter, and one page.

The remaining keywords are mainly command keywords. Each is assembled into one or more central words, the first of which must bear a 6-bit opcode, to the far left. Succeeding cards in a page are assembled into succeeding locations, in their order of appearance. All KWCs assemble into one central memory word unless stated otherwise.

SIGNOFF opcode: 00
e.g. \$L2:SIGNOFF。

This commands the CAI system to sign-off the student. When a student is signed off he cannot resume his lesson until he signs on again.

TEXT[T=<delay>] opcode: 01
e.g. $\$ \operatorname{TEXT}(\mathrm{~T}=24)$
$\rightarrow \operatorname{TEXT}(T=*)$

This modifies the immediately following text stream. If the next card is not a TBC, i.e. no such text stream follows, then the KWC is ignored. However a text stream need not be preceded by a TEXT card, in which case '\$TEXT.' is assumed to occur. <delay> is a number taking an integer value from 0 through 999, and represents the time the system must wait on presenting the text stream, before resuming the execution (interpretation) of the course. If no T-parameter is specified, $T=1$ is assumed; i.e. '\$TEXT' is equivalent to '\$TEXT $(T=1)$ '. The special form $T=\star$ implies an infinite delay. The system will resume execution of the course prior to the expiry of the delay, if the student types in '\#GO'.

A 'TEXT' without an accompanying text stream causes no object code to be produced. With its text stream, it is assembled as follows. The typewriter codes of the text stream are assembled into as many text groups as required. Each text group contains two header words followed by up to 16 central memory words in which the T/W codes are packed 5 per word. Thus eac ${ }^{h}$ text group can accommodate up to $80 \mathrm{~T} / \mathrm{W}$ codes and a text stream with $n \mathrm{~T} / \mathrm{W}$ codes occupies N central memory words where:
$N=18 \times[n / 80]+\left[\frac{1}{5}(n-1-80 \times[n / 80])\right]+1$.
$[x]$ stands for the largest integer not exceeding $x_{0}$ e.g. $97 \mathrm{~T} / \mathrm{W}$ codes will take up $18+\left[\frac{1}{5} \times 16\right]+1=22$ words.

The CUE, ANSWER, ENDANS, WAITCUE and GIVECUE commands must be used only in a problem environment - a loose concept to be explained later. \{CUE|EXPLAIN|EXP\} [, <n>] [(T=<delay>)] opcode: 02 e.g. $\$ \operatorname{LX}: \operatorname{CUE}(T=15)$
\$CUE, 4( $\mathrm{T}=10$ )
\$EXP.
This instruction will be referred to as a cue. The keywords CUE, EXPLAIN and EXP are treated as equivalent. <n> takes any integer from 1 to 99. <delay is as for TEXT; if the T-parameter is not specified, $T=$ * is assumed. The $<n>$ is a repetition factor and indicates the number of 'single' cues intended. Thus '\$CUE,4(T=12)' is equivalent to four
successive '\$CUE, $(T=12)$ ' cards saving three cards. Each single cue assembles into 1 word; thus '\$CUE,3.' takes three words.

A cue must be part of a problem block (q.v.). When it is executed, a red question mark is typed out on the left margin of a new line, indicating to the student to respond with an answer. The student must then respond within the delay time of the cue or else he forfeits his chance to answer; in this latter case the course execution will resume from immediately after the cue. When an answer is received, the system next executes the first answer command in the associated answer sequence ( $q . v_{0}$ ). This then in effect triggers off (see execution of answer command) a comparison of the student's answer against the author answers, one after another in the answer sequence, until either (a) a match is made or (b) there is no more author answer to compare. In the case (a) the course will continue from immediately after the matching answer command. In the case (b), no match has been achieved and the system types out the message "Incorrect" and then resumes execution from the cue just executed. What follows the cue would usually be a piece of explanatory or prompting text - whence the keywords CUE and EXPLAIN.

The following is a simple example of the use of cues in the context of a problem block. This is followed by two hypothetical student interactions. The italicised texts within square brackets are comments for the reader.

## COURSE SEGMENT

\$TEXT.
Kuala Lumpur is the capital of $\qquad$ ?
\$CUE.
M $\qquad$ - Please try again.
$\$ \operatorname{CUE}(\mathrm{~T}=10)$
MAL $\qquad$ . Try again.
\$EXPLAIN ( $\mathrm{T}=10$ )
The answer is MALAYSIA.
\$GOTO,L20.
\$ANSWER(M=3)*MALAYA*

Not quite. Malaya is now part of another country. \$GIVECUE.
\$ENS (M=3) \$MALAYSIA\$
Very good.
\$L20:TEXT.
In what year

## Interaction 1

SYSTEM: Kuala Lumpur is the capital of ?
STUDENT: ?BURMA [The '?' from the system is in red; student ends answer with a Carriage return.J
SYSTEM: Incorrect.
M $\qquad$ - Please try again.
? [Student fails to respond within 10 seconds.]
SYSTEM: MAL $\qquad$ - Try again.

STUDENT: ?MALAYA
SYSTEM: Not quite. Malaya is now part of another country. The answer is MALAYSIA.
In what year .....

## Interaction 2

SYSTEM: Kuala Lumpur is the capital of $\qquad$ ?
STUDENT: ?SINGAPORE
SYSTEM: Incorrect.
M $\qquad$ . Please try again.
STUDENT: ?MALAYA
SYSTEM: Not quite. Malaya is now part of another country. MAL $\qquad$ . Try again.
STUDENT: ?MALAYSIA
SYSTEM: Very good.
In what year .....
\{ANSWER|ANS|ENDANS |ENS $\}\{[<t>] \mid([M=<m o d e>][, C=<$ category $>])\}<$ answer specn>
e.g. \$ANS ( $\mathrm{M}=2, \mathrm{C}=3$ ) *PERMUTATION*
opcode: 03
\$ANSWER(C=4)*WARM*FRIENDLY*GENIAL*
\$ENS. =BIG=LARGE=
\$ANSWER (M=6)\$123565\$2434\$

The keywords ANSWER and ANS are equivalent; so are ENDANS and ENS. The instruction forms are only approximately represented by the above specification; so further explanation is in order。 <t> is either ',' or '.'. <mode> is an integer, at present taking one of the values $0,1,2$, ...9,10,11,12,13. Other modes have not been yet implemented. <category> may take any of the integer values $0,1,2, \ldots 63$. When not specified, the default values for $M$ is 3 and $C$ is 0 . The $C$-parameter and $M$-parameter may appear in any order.

An <answer specn> consists of one or more answer strings bounded and separated by a common delimitter character. An answer string is made up of any CDC 6400 display code characters. Imbedded blanks are significant. A delimitter can be any display code character not used in the answer strings. An answer specification has the form: \$<answer string $1>\$<a n s w e r$ string $2>\$ . \ldots . . \$<$ answer string $n>\$$ where $\$$ is the delimitter character. The second and subsequent answer strings, if present, may not begin with a blank - if one does, then it, and all subsequent strings in the specification will be ignored. Thus \$ANS ( $M=2$ )*AA* AB*AC* will be treated as $\$$ ANS $(M=2) * A A^{*}$ only. An answer instruction with $n$ answer strings is equivalent to $n$ separate answer instructions, containing only one of the $n$ answer strings each, and with the same $M$ and $C$ parameters. Thus \$ANS $(M=2, C=5) * A 01 * A 02 * A 03 *$ is equivalent to the three successive instructions: $\$$ ANS $(M=2, C=5) * A 07 *$, \$ANS $(M=2, C=5) * A 02 *$, and $\$ \operatorname{ANS}(M=2, C=5) * A 03 *$. But note that \$ENS(--)*JACK* JILL* is equivalent to \$ANS(--)*JACK* and \$ENS(--)*JILL* in that order.

The C-parameter is included in any recording of a response match against an answer. It is useful for classifying answers in a course. For instance, the author may designate the categories $0,1,2$ and 3 for incorrect, partially correct, acceptable and best-match answers respectively.

When an answer command (ANSWER or ENDANS) is executed, the student's input string will be compared with the author's answer string (or strings), under the prescribed mode. The outcome is either a match or a mismatch.

A match is always obtained when an answer command is executed in the absence of a student answer. If a match is made, the next command to be executed is the one immediately following the answer command. If there is a mismatch then the next action depends on whether or not this is the last answer command in the problem block. If it is, then the message "Incorrect" is output and the course resumes immediately after the last cue executed. We have not discussed answer recording here to avoid complicating the above explanations.

To understand the execution of an answer command in the absence of a student answer, consider the answer sequence :
\$ANS $(M=3) * A *$
Message-1
\$ANS (M=3)*B*
Message-2
\$ENS (M=3)*C*
Message-3.
If the student's answer is 'A', and the first answer command is executed, a match is obtained. The next command to be executed is the one immediately following this first answer command, and this is the text "Message-1"; this text is typed out. The next command is then executed - this is the second answer, and since there is now no student answer (his answer ' $A$ ' has been successfully matched with the first answer command and is no longer active), a match is assumed, and therefore "Message-2" is next typed out, followed thereafter by "Message-3", since a match is again assumed with the last answer command (ENS).

Currently we have only the answer processing modes $M=0,1,2 \ldots$ 12,13,14 to meet the immediate needs of an experimental system. These modes have the functions described below :-

| Mode |  |
| :--- | :--- |
| 0 | Permitted only in an ENDANS. In Mode 0, there is no answer |
| string associated with the instruction. Any response will |  |
| match a mode 0 answer - i.e. it is a catch-all.e.g. $\$ \operatorname{ENS}(M=0)$. |  |

## A－21

1 Perform an exact string match of the student＇s response， without prior editfing，against the author answers，e．g． \＄ANS（M＝1）＊NEIN＊will match＇NEIN＇but not＇NE IN＇nor＇MEIT＇．

As for $M=7$ ，but remove blanks from student response prior to string matching，e．g．\＄ANS（M＝2）＊ALPHA＊will match any of ＇ALPHA＇，＇AL PH A＇and＇ALP HA＇but not＇BETA＇or＇GAMMA＇．

This is the default mode－i．e．if no mode is specified by the author，$M=3$ is assumed．As for $M=2$ ，but in addition，any ，；：？＂＇and 。are removed from the student string before it is matched．e．g．\＄ANS（M＝3）ZALPHAZ will match＇AL，．PHA＇ and＇ALPHA．＇．

4 Remove from student＇s answer any non－alphanumeric before comparison．Clearly then \＄ANS（M＝4）＊F44．6＊will never match any student response as any＇．＇present in it will be removed． As for $M=4$ ，alphanumerics only．But student responses may be truncated on the right before matching．Thus the response ＇PROGRAMME＇will match＇\＄ANS（M＝5）＊PROGRAM＊．

All non－numeric characters to be removed prior to matching． Thus an author answer string containing a non－numeric will fail to match all student answers．

Remove any blank，＇，＇，＇；＇and＇：＇before matching．Thus ＇TWO；THREE＇but not＇TWO．THREE＇will match $\$$ ENS（M＝7）个TWOTHREE个．

Remove blanks and if necessary truncate trailing zeroes，before matching．Thus＇46．2300＇but not＇46．23243＇will match \＄ANS（M＝8）＊46．23＊。

This mode is for the recognition of a list of answer items， which may be separated by blanks，＇，＇，＇；＇or＇：＇，and in which the items are allowed to occur in any order．In the author list，the items are separated by $\mp$（T－bar on IBM－029）．
e.g. (1) \$ANS(M=9)BLUETREDTGREEN* matches 'BLUE,GREEN,RED' and 'RED; BLUE:,GREEN'.
 to \$ANS(M=9)*ALPTGAMT̄BET* and \$ANS(M=9)*PPT̄QT=TRT̄TSS* in succession.

This is for keyword match; author strings and keywords, whose occurrence are searched for in the student string; if search is successful, a match is said to be made. e.g. \$ANS(M=10)*HAPPY* matches 'I AM HAPPY'.

This is for matching a number; the student's number must be less than the author answer. e.g. '14.64' and '7' match \$ANS ( $M=11$ )*15.0* but not '15.01' nor '20'.

Same as for $M=11$, except that the student answer must be greater than the author's number.

In this mode, each answer string is two numbers separated by a semi-colon. Student answers match if they are between these two numbers in value. The author does not have to place the number pair in numerical order. Thus \$ANS $(M=13) * 12 ; 13^{*}$ and $\$ \operatorname{ANS}(M=13) * 13 ; 12^{*}$ are equivalent and will match '12.23' but not '13.4'.

This is for algebraic expression match. The author string is an algebraic expression. A student answer matches if it is algebraically equivalent to it. e.g. \$ANS $(M=14) *(A+B) \uparrow 2^{*}$ matches ${ }^{\prime}(B+A) \uparrow 2^{\prime}, ~ ' A \uparrow 2+B \uparrow 2+2 * A * B '$ and ' $(2 * B+(A-B)) *(B+A)$ ' but not ' $2 *(A+B)^{\prime}$.

In an answer sequence (q.v.), the last answer instruction must be an ENDANS. Thus an answer sequence with only one answer instruction consists of only an ENDANS.

The number of words taken to assemble an answer instruction depends on the number of answer strings and the lengths of these strings. Each
string is assembled as a separate answer block, made up of one header word, and one or more words to accommodate the actual answer string, packed 10 per word, with a zero byte (6-bits) to terminate it. Thus *ANSWER(M=3)*SHORT* takes 2 words, \$ANS(M=2)*BELLYLONGSTLING* requires 3 full words and $\$ \operatorname{ENS}(M=0) 1$ word.

Unconditional Branch:
There are three unconditional branch instructions, facilitating (a) intra-page,
(b) inter-page, but intra-chapter, and
(c) inter-chapter transfers.

GOTO $\{$ name $>1,|\rightarrow| \rightarrow\} \quad$ opcode: 04
e.g. (1) \$GOTO,L4 (2) \$GOTO $\rightarrow$

This instruction effects a branch to another instruction within a page. <name> refers to a label in the page. When executed, the system continues the course at the instruction bearing the label. $\rightarrow$ is an implicit label. ' $\$$ GOTO $\rightarrow$ ' or ' $\$$ GOTO, $\rightarrow$ ' causes the execution of the course to be transferred to the first instruction below in the same page which bears $a \rightarrow$ on column 1. If no $\rightarrow$ exists, then the branch will be to the last instruction assembled in the course - this is normally a system-supplied transfer to the next page.

GOTO,PAGE (\{<pagename>|*\}) opcode: 05
e.g. (1) \$GOTO,PAGE(T004) (2) $\rightarrow$ GOTO,PAGE (*)

Here <pagename> refers to another page in the same chapter; the execution of this instruction causes a transfer to be made to the beginning of that new page. $\$ G O T 0, \operatorname{PAGE}(*)$ is a transfer to the next page in the chapter.

GOT0, $\operatorname{CHAPTER}(\{<$ chaptername $>\mid *\})[, \operatorname{PAGE}(\{<$ pagename $>\mid *\})]$ opcode: 06 or 15
e.g. (1) \$GOTO,CHAPTER(FIVE), PAGE(14)
(2) \$GOTO,CHAPTER(T664)
(3) \$GOTO,CHAPTER(*), PAGE(SIX)

This instruction causes a transfer to the named page of the named
chapter．＇${ }^{* \prime}$ refers to the next chapter or page as the case may be． When no page is mentioned（as in the 2nd example above）the first page of the chapter is intended．Assembles in one or two words depending on the instruction．

## WAITCUE opcode： 07

This is a command to re－execute the last cue executed in the problem block－in effect giving the student another chance to answer．

This is not the same as an explicit branch to a cue（see example on right）as in ：－
since this involves a particular cue，whereas WAITCUE＂transfers＂to the last＇active＇cue．

This commands the system to continue from immediately after the last cue executed．What follows is usually a line or two of cueing text－hence the keyword GIVECUE．

TIME，＜name＞opcode： 13
e．g．（1）$\rightarrow$ TIME，XX2
（2）\＄TIME，LOC4．

This instructs the system to record on the student performance tape， the current time，using the specified name to identify the location in the course．This facilitates an investigation by researchers into various routes taken by the different students，and their＇arrival＇time at the various sections．
\｛DELAY｜DEL\}( $\mathrm{T}=<$ delay $>$ ）opcode： 04
e．g．$\$ \operatorname{DELAY}(T=200)$
This instructs the system not to continue executing the course until the specified delay（in seconds）has elapsed，unless the student interrupts during this time，with an input requiring processing，e．g。\＃GO。

WAIT opcode： 14
This instruction is equivalent to the three successive instructions：－ \＄TEXT．

RRW又。 $8 又$
\＄CUE．

This conmand causes a 'W' in red to be output on a new line, which acts as a signal to the student to press the carriage return key (or any input followed by the $c / r$ ) to indicate his readiness to continue. This instruction may be used to wait on the student until he is ready to continue. The WAIT may not be used in a problem environment.
\{COMPLETED|FINISHED\} opcode: 17
This command indicates that the student's course terminates here. There may be more than one 'COMPLETED' in a course, since a course may terminate at several different points. The system also automatically assembles a COMPLETED instruction on encountering \$END, as a precaution. The system action is to sign-off the student and to flag the end-of-course status.
\{PROBLEM|PRB|BLOCK|BLK $\}[<$ name $>[(R=<$ recording mode>) $]]$ opcode: 12
e.g. (1) \$PROBLEM, Q002 ( $R=8$ )
(2) \$PRB.

This command allows the author to name a problem block and to specify the recording mode for the students' responses to it. In the CAI system, there is a location in the student area, called the blockname location - for saving a blockname and the recording mode. The effect of executing a PRB is to reset this location with a new name and R-value. When a student answer is received, the system examines this location. If it is zero in value, no recording of his response is made. Otherwise a recording of the response with this blockname and under the recording mode indicated is made.

When a new page is assembled, a flag F=PRB is set to zero. When a PRB command is encountered, this flag is set, and when a problem block is encountered, this flag is cleared; but before being cleared, the system ensures that it is set. If not, the system assembles a '\$PRB.' so that no recording for this block is made.

The PRB command must be used with care - $\quad \$ \operatorname{PRB}, Q 1(R=2)$ being executable. Thus if the example (see opposite) shown, is executed, responses to the problem block could be recorded under the name Q1 and mode 2, instead of the presumablyintended name Q7 and mode 8.
\$GOTO,L2.
\$PRB,Q7(R=8)
\$L2:TEXT.
What is ...?
\$CUE.

The command '\$PRB.' is treated as having no name and 0 mode.
The recording mode, $R$, may assume any of the values $0,1,2 \ldots 30,31$ (decimal). $R$ is in fact a 5-bit status flag; thus $R=13$ is '01110'. Each of the five bits has the significance indicated below:- If student response matches, record the match number. If non-matching, record his whole response.
00100 Record whole answer if catch-all (i.e. $\operatorname{SENS}(M=0)$ ).
01000 Record student response unconditionally.
10000 Make a record of only the first response to this question. e.g. (1) $R=3 \quad\left(3=00011_{2}\right)$ means same as $R=2$, i.e. record match number if match; else record the non-matching response.
(2) $R=8 \quad\left(8=01000_{2}\right)$ Record all responses to this problem. Recording Details

At present, no standard programs exist, for processing the recorded data of student responses. Users will have to develop their own programs to extract the information they want. To assist in this, the recording format is described in some detail here. (See figure opposite) The figure shows a record of recorded data. Record size $=$ number of CM words in the record. Current time recorded in the form: '^*HH.MM.SS.ss' where $H H=$ hour, $M M=$ minute, SS.ss = time in seconds to 2 decimal places. Latency of Response - given in seconds.

| Record Size |
| :--- |
| Current Time |
| Student Code |
| Course Name |
| Problem Name \& R-mode |
| Reserved |
| Latency of Response |
| Match Number |
| STUDENT'S <br> RESPONSE |
|  |

The student's response is recorded in the $\mathrm{T} / \mathrm{W}$ code (7-bit T/W code), packed to the left, 8 codes per word; first 4 bits of each word here $=$ code count. Unused bits are zeroed.

## Register Arithmetic

The author is provided with 15 registers $A, B, C, \ldots . M, N, O$, for holding working values. Each register is a 60 -bit word and is used to hold a (floating point) number. At the beginning of a course, these registers are initialised to zero. Registers can be used to keep track of student performance. For instance, register $A$, can be used to hold the total number of tries at a given set of questions and $B$ to hold the corresponding number of successful ones.

Simple arithmetic on register values may be performed using register statements. The forms that a register statement may take are given by the BNF grammar below. Arithmetic is performed in floating point. Each register can hold a number $n$, where $|n| 1$ ies between 10-294 and $10^{322}$. Division by zero gives zero as the answer, e.g. $3 / 0=0$.

The kinds of permitted expressions are those involving constants, registers and + , *, / and - only. These last four symbols, +, *, / and - are respectively the operators for addition, multiplication, division and subtraction. Rather complex arithmetic expressions are possible, but it is envisaged that the more usual ones would be sufficient to meet most author needs.

Examples:-
(1) $\$ A=B=3.64$ (set registers $A$ and $B$ to the value 3.64)
(2) $\$ D=-3$ (set register $D$ to -3)
(3) $\$ A=12 * B /(C-D)$ (set $A$ to the value of the expression $12 * B /(C-D)$ )
(4) $\$ A=B=G *(M=13.2 /(4 * K))-(E=F / G)$
(4) is equivalent to the three separate statements:
$\$ E=F / G$
$\$ M=13.2 /(4 * K)$
$\$ A=B=G * M-E$

BNF Grammar for Register Statement

```
<digit> ::= 0|l|2|...7|8|9
<register> :}:=A|B|C|\ldotsM|N|
<aop> ::= +|-
<mop> ::= *|/
<unsigned int> ::= <digit>|<unsigned int><digit>
 ::= <unsigned int>
<unsigned no> ::= <unsigned int>||<unsigned int>.|
    <unsigned int>
<factor> ::= <register>|(<expression>)|(<register statement>)
<term> ::= <factor>|<term><mop><factor>
<expression> ::= <term>|<expression><aop><term>|<aop><term>
<register statement> ::= <register>=<expression>|<register>=<register>
    statement>
<rel op> ::= EQ|NE|GT|LT|LE|GE
<sign op> ::= PS|NG|NZ|ZR|NP|NN
<constant> ::= <unsigned no>|+<unsigned no>|-<unsigned no>
```


## Conditional Branching

The conditional branch statement has the general form :-

$$
\text { IF(<relational expression>) } \mathrm{Br}
$$

Here ' Br ' stands for an unconditional branch statement. The relational expression has either TRUE or FALSE as value; if TRUE, the branch ' $\mathrm{Br}^{\prime}$ is taken; otherwise the next instruction below is executed. The relational expression has one of the three forms below :-
(1) <register>.<re1 op>.<register>
e.g. A.LE.F
(2) <register>.<rel op>.<constant>
e.g. B.NE. 12.6
(3) <register>, <sign op>
e.g. M,NG

The relational operators have the meanings:- EQ (equal), NE (not equal), GT (greater than), GE (greater than or equal to), LT (less than), LE (less than or equal to); PS (is positive), NG (negative), NZ (non-zero), ZR (zero), NP (non-positive) and NN (non-negative).

## Examples of Conditional Branch

(1) \$IF(A.LE.F)GOTO,L6.
(2) \$IF(B.GT. -6.4)GOTO,PAGE(TWO)
(3) $\$ \mathrm{IF}(\mathrm{D}, \mathrm{NZ})$ GOTO, CHAPTER(XA7)

In example (1), if the value of $A$ is 7 and if $F$ is 13 , then 'GOTO,L6' will be executed.

The Problem Block
The rather loose concept of a problem block is now discussed. A "cue" refers to a CUE, EXP or EXPLAIN instruction; an "answer" refers to ANSWER, ANS, ENDANS or ENS instruction while "endanswer" refers to ENS or ENDANS. Because the cue, answer, WAITCUE, GIVECUE (and even WAIT) instructions cannot be used as freely as the other instructions, they are said to be critical.

A cue sequence is a set of one or more cues, possibly interspersed with non-critical instructions. It has the form

e.g. \$CUE,2(T=10)

It begins with a 'C'
\$CUE ( $\mathrm{T}=15$ )
\$TIME,ABB
Try again.
\$EXP.
The answer is 'crisis'.
The following is not a cue sequence :-
\$CUE.
\$ANS (M=4)*PQR* (because it imbeds an answer)
\$CUE,2.
Try again.
\$EXP.

An answer sequence is either an end answer or a set of answers (which are not end answers) terminated by an end answer. An answer sequence may be interspersed by other instructions, excluding cues and WAIT.
e.g. (1) \$ENS (M=2).ALPHA. BETA.
(2) $\$$ ANS $(M=2) *$ COMMON*

Not quite - try again.
\$WAITCUE.
\$ENS(M=2)*ORDINARY*
Very good - correct.
(3) \$ANS (M=2)*PORT*
\$ENS $(M=5) * G O R T *$ (is not an answer sequence)
\$ENS (M=2)*WORT*

A cue sequence followed by an answer sequence constitutes a problem block. The problem block is a means for posing a question to the student and for accepting and analysing his responses against author answers. The cue sequence and the answer sequence have no independent standing. Every cue sequence must be followed by an answer sequence. This answer sequence is said to be associated with the cue sequence.

A problem block may not be split over two or more pages; it must be fully accommodated in one page. When an author-defined page is too long, the compiler will try to split into two or more pages without splitting a problem block.

It is normal for an answer sequence to be immediately preceded by an unconditional branch, to lead the student out of the problem block. If such a branch statement is absent, then a '\$GOTO, $\rightarrow$ ' is automatically inserted just above the first answer.
e.g. \$CUE.....

XXXXXXX
\$ANS..... is equivalent to
\$CUE.....
XXXXXXX
\$GOTO $\rightarrow$
\$ANS.....

## Programming Examples

(1) Specification: Present student with a question 'Q...' and give him one chance to answer. There is only one current answer ' $X X X$ '; if the answer given is correct, reinforce student, else if incorrect inform him so. No time limit for answering. 2 possible codes are :-
(a) Q....
\$CUE
\$GOTO,L4
\$ENS (M=2)*XXX*
Good. Correct.
\$L4:TEXT.
(2) Specification: Give student question; three attempts, with a time limit of 10 seconds each; no prompting material. Two possible codes are :-
(a) ...question...
$\$ \operatorname{CUE}(\mathrm{~T}=10)$
\$CUE ( $\mathrm{T}=10$ )
\$CUE ( $\mathrm{T}=10$ )
The answer is
\$ANS ( ) ....
\$ENS ( ) ....
(3) Specification: Let student try a question again and again; if incorrect answer, tell student to 'try again'. No cueing text. No time limit for attempts. Two ways to do this are :-
(a) ...question...
\$CUE.
Try again.
\$WAITCUE.
$\begin{array}{ll}\$ \operatorname{ANS}( & ) \ldots . \\ \vdots \\ \$ \operatorname{ENS}( & \\ \end{array}$
(b) ...question... \$CUE. \$ANS ( ) .... : \$ENS ( $M=0$ ) . No. Try again. \$WAITCUE.
(4) Specification: Let student try a question the number of times specified in register $G$ - but at least once. No time limit for each attempt.

```
...question...
$A=0
$LOOP:CUE.
$A=A+1
$IF(A.LT.G)GOTO,LOOP
$ANS( )....
    \ENS( )....
```

(5) Specification: 6 attempts, without time limit. If correct in first attempt, type out 'Very Good'; if correct on 2nd or 3rd attempt output 'Good', and if correct only after three or more incorrect attempts, type out 'Correct'. No cueing material. As usual, output 'Incorrect' for each wrong answer received.
...question...
\$I=0
\$CUE.
\$I $=\mathrm{I}+1$
\$IF(I.GT.5)GOTO,4.

\$IF(I.GT.1)GOTO,2.
Very Good.
\$GOTO, $\rightarrow$
\$2:IF(I.GT.3)GOTO,3.
Good.
\$GOTO,4.
\$3:TEXT
Correct.
$\rightarrow 4$.

## Structure of a Course

An ALFIE course has the deck structure shown below. The card indentation is intended to emphasise the division of a course into chapters and pages. The vertical dots indicate intervening cards which are assumed not to be '\$COURSE' or '\$END'.
\$COURSE,
\$CHAPTER, $\qquad$
\$PAGE, $\qquad$ \$ ${ }^{\text {PAGE }}$ $\qquad$ :
\$PAGE, $\qquad$

$\qquad$
$\vdots$
\$CHAPTER,
$\qquad$ ! \$CHAPTER, $\qquad$
\$PAGE, $\qquad$
:
\$PAGE, :
\$END

## A-34

SCOPE 3 job card. (beginning card of job deck)
RFL, 100 .
REQUEST,XAOLR. K55 READ ONLY
RFL, 30000.
REWIND (XAOLR)
COPYBF (XAOLR,LKC) (copy off program LKC)
COPYBF (XAOLR,ALF) (copy off program ALF)
LKC.
(pre-process course)
REQUEST,XAOBJ. K40 WITH RING
ALF.
(assemble course onto K40)
End-of-Record Card
(your course deck)
End-of-File Card.

It is possible to compile more than one course in one run. This is done simply by placing the several courses to be compiled, one after another, and placing them in the job-deck (see above) where the single course deck is. The object codes of each course will be output on the course object tape, and treated as a file (i.e. terminated with an EOF mark) - with the last course having a double EOF terminator.

NOTE:
The version of ALF on K55 does not permit answer processing modes 10, 11, 12, 13, 14.


Figure A. 4 Schematic of a Course

Job Deck Structure For Course Compilation
To compile a course onto a magnetic tape, the course deck must be organised with other cards to form a job - for running under the SCOPE operating system of the CDC 6400. The object code is output on the file XAOBJ, which is a tape file if a tape is assigned to it.

A typical job deck for compiling an ALFIE course has the structure shown below. The tape K55, contains the preprocessor LKC, and assembler program ALF in their binary form, as the first and second tape files. Tape K 40 is assigned to XAOBJ.

## B-1

## APPENDIX B

THEORETICAL DEVELOPMENT

## Résumé of Algebraic Geometry

This section reviews some of the main ideas and results from the theory of rings and algebraic geometry which are especially relevant to the derivation of our Thm 1, Thm 2 and Thm 3. The main sources of reference are $[3,26,37,46]$.

## Commutative Ring

Let R be a non-empty set of elements $\mathrm{a}, \mathrm{b}, \mathrm{c}, \ldots$ in which the sum $a+b$ and the product $a \cdot b$ of any two elements $a$ and $b$ of $R$ are defined. Then $R$ is a commutative ring with unity if the following axioms hold.
(1) $\forall a, b \in R \quad a+b \in R$ and $a \cdot b \in R \quad$ [closure]
(2) $\forall a, a^{\prime}, b, b^{\prime} \varepsilon R$ where $a=a^{\prime}$ and $b=b^{\prime}, a+b=a^{\prime}+b^{\prime}$ and $a \cdot b=a^{\prime} \cdot b^{\prime}$ [uniqueness]
(3) $\forall a, b \in R \quad a+b=b+a$ and $a \cdot b=b \cdot a \quad$ [commutativity]
(4) $\forall a, b, c \in R \quad a+(b+c)=(a+b)+c$ and $a \cdot(b \cdot c)=(a \circ b) \cdot c \quad[a s s o c i a t i v i t y]$
(5) $\forall a, b, c \in R \quad a \cdot(b+c)=a \cdot b+a \cdot c$ [distributivity]
(6) $3 \quad 0 \in R$ such that $\forall a \in R \quad a+0=a \quad$ [zero]
(7) $\exists l_{E} R, \quad \neq 0$ such that $\forall a \in R \quad a \cdot 1=a$ [unit]
(8) $\forall a \in R \quad \exists x \in R$ such that $a+x=0$ [additive inverse].

The following are examples of commutative rings with unity :-
(1) the set $\mathbb{Z}$ of all integers
(2) the field $\mathbb{R}$ of real numbers
(3) the complex field $\mathbb{C}$ and
(4) the ring $\mathbb{R}[\underset{\sim}{X}]$ of all polynomials in $\underset{\sim}{X}$ with real coefficients.

Henceforth all our rings will be assumed to be commutative rings with unity.

Defn. B. 1 A non-empty subset I of a ring $R$ is an ideal if and only if for every $a, b \in I$ and $r \in R, a-b \in I$ and $a \cdot r \varepsilon I$ 。
e.g. The set of all even integers is an ideal of the ring $\mathbb{Z}_{\text {。 }}$

$$
B-Z
$$

Every ideal contains 0 (since $0=a-a$ ) and the additive inverse of every of its elements (since $-\mathrm{a}=0-\mathrm{a}$ )。 Every ring $R$ contains at least two ideals, viz. the trivial ideals $\{0\}$ and R. $\{0\}$ which contains only the zero element is also called the zero ideal. An ideal that is non-trivial is said to be a proper ideal.

Defn. Bo2 Let $S=\left\{s_{1}, s_{2}, \ldots s_{k}\right\}$ be a set of elements of $R$. Then the set $\left\{{ }_{j} \sum_{=1}^{K} a_{i} \cdot S_{i} \mid a l l a_{i} \in R, s_{j} \in S\right\}$ of all "linear combinations" of the elements of $S$ is an ideal, called the ideal generated by $S$. $S$ is called a basis of the ideal. The ideal is denoted by $\left(s_{1}, s_{2}, \ldots s_{k}\right)$. An ideal like this, with a finite basis is said to be finitely generated.
e.g. The ideal (2) of all even integers is generated by \{2\}.

Defn. B. 3 A Noetherian ring is one in which every ideal is finitely generated. While not all rings are Noetherian, all our rings of interest are.

Notation: Let $R$ be a ring. Then $R\left[X_{N}\right] \equiv R\left[x_{1}, x_{2}, \ldots x_{n}\right]$ denotes the ring of all polynomials in $x_{1}, x_{2}, \ldots x_{n}$ over the ring $R-$ i.e. the set of all polynomials in $x_{1}, x_{2}, \ldots x_{n}$ with coefficients from R. Commonly used rings are the integer, the real and the complex rings $\mathbb{Z}, \mathbb{R}$ and $\mathbb{C}$.

Defn. B.4 'a' is a root of $F_{\varepsilon} R[x]$ if $F \equiv(x-a) \cdot G$ for some $G \varepsilon R[x]$. A field $K$ is algebraically closed if any non-constant $F_{E} K[x]$ has a root. Thus $\mathbb{C}$ is closed but not $\mathbb{R}$. A point ${\underset{\sim}{X}}_{0} \varepsilon \mathbb{R}^{n}$ is a zero of the polynomial $F_{\in} R\left[X_{\sim}\right]$ if $F(\underset{\sim}{X} 0)=0$. If $F$ is not a constant then the set of all zeroes of $F$, denoted $H_{F}$ is called the hypersurface of $F$.

More generally a set $S=\left\{F_{1}, F_{2}, \ldots F_{k}\right\}$ of polynomials from $R\left[X_{\sim}^{X}\right]$ defines the set $M(S) \xlongequal{\text { defn }}\left\{\underset{\sim}{X} \in R^{n} \mid F_{i}(\underset{\sim}{X})=0\right.$ for $\left.i=1,2, \ldots k\right\}$ of all the common zeroes of the polynomials $F_{1}, F_{2}, \ldots F_{k}$. We note that $M(S)=\bigcap_{i=1}^{k} M\left(F_{i}\right)$. We also write $M(S) \equiv M\left(\left\{F_{1}, F_{2}, \ldots F_{k}\right\}\right)$ as $M\left(F_{1}, F_{2}, \ldots F_{k}\right)$.

Defn. B. 5 A subset $A$ of $R^{n}$ is called an algebraic manifold (or simply a manifold) if $A=M(S)$ for some set $S$ of polynomials in R[X].

The set of all common zeroes of a set of polynomial is a manifold. A hypersurface in particular is a manifold.
Notation: If I is an ideal then $\left.M(I) \xrightarrow{\text { defn }} \underset{\sim}{X_{\varepsilon}} R^{n} \mid F(\underset{\sim}{X})=0 \forall F E I\right\}$.
We now present some well-known results of algebraic geometry.
Res-1: If I is the ideal generated by $S$ then $M(I)=M(S)$. Thus every manifold is equal to $M(I)$ for some ideal I.
Res-2: If $\left\{I_{1}, I_{2}, \ldots I_{k}\right\}$ is any set of ideals of $R[\underset{\sim}{X}]$ then $M\left(\underset{j}{{\underset{U}{U}}_{1}^{k}} I_{i}\right)$
$=\bigcap_{i=1}^{k} M\left(I_{i}\right)$. So the intersection of any collection of manifolds is
a manifold.
Res-3: If $I \subset J$ then $M(I) \supset M(J)$.
Res-4: $M(F \cdot G)=M(F) u M(G)$ for any potynomials $F$ and $G$ 。 $M(I): M(J)$ $=M(\{F \cdot G \mid F \in I, G \varepsilon J\})$. Thus any finite union of manifolds is a manifold.
Res-5: $M(0)=R^{n}$ and $M(1)=\emptyset . \quad M\left(x_{1}-a_{1}, x_{2}-a_{2}, \ldots x_{n}-a_{n}\right)=\left\{\left(a_{1}, a_{2}, \ldots a_{n}\right)\right\}$ for $a_{i} \in R$. So any finite subset of $R^{n}$ is an algebraic manifold.
Defn. B-6: Let $A \subset R^{n}$. The set $I(A)$ of all polynomials in $R\left[X_{\sim}\right]$ which vanish on $A$ form an ideal called the ideal of $A$.
Res-6: If $A c B$, then $I(A) \sqsupset I(B)$.
Res-7: $I(\rho)=R[X]$ and $I\left(R^{n}\right)=(0)$ if $R$ is an infinite field. $I\left(\left\{\left(a_{1}, a_{2}, \ldots a_{n}\right)\right\}\right)=\left(x_{1}-a_{1}, x_{2}-a_{2}, \ldots x_{n}-a_{n}\right)$ for $a_{i} \in R$.
Res-8: $I(M(S)) S$ for every set $S$ of polynomials. $M(I(A))$ for every set $A \subset R^{n}$.

Res-9: $M(I(M(S)))=M(S)$ for every set $S$ of polynomials and $I(M(I(A)))$ $=I(A)$ for every subset $A$ of $R^{n}$. So if $M^{\prime}$ is a manifold then $M\left(I^{\prime}\left(M^{\prime}\right)\right)=M^{\prime}$ and if $I^{\prime}$ is the ideal of a manifold, then $I\left(M\left(I^{\prime}\right)\right)=I^{\prime}$.

## B-4

Defn. B.7: A manifold $M$ is irreducible if it is not possible to express it as the union of two proper submanifolds - i.e. $M=M_{1} \cup M_{2}$ where $M_{1}, M_{2} \neq M, M_{1}, M_{2} \in M$ and $M_{1}$ and $M_{2}$ are manifolds.

Defn. B.8: An ideal I is prime if for every $a \cdot b \in I$, either $a \in I$ or $b \in I$.

Res-10: A manifold $M$ is reducible if and only if there exists two polynomials $f$ and $g$ such that neither one vanishes all over $M$, but such that f.g does.

Res-11: Every manifold is uniquely expressible as the union of irreducible manifolds $M_{1}, M_{2}, \ldots M_{k}$; i.e. $M=M_{1} \cup M_{2} \cup \ldots \cup M_{k}$ and $M_{i} \nsubseteq M_{j}$ for every $i \neq j$.

The $M_{i}$ 's are called the irreducible components of $M$ and $M=\bigcup_{j=1} M_{i}$ is said to be the decomposition of $M$ into its components. If $M$ is itself irreducible then it is its only component.

Res-12: If $V \subset W$ and $V, W$ are two manifolds of $R^{n}$ then each irreducible component of $V$ is contained in some irreducible component of $W$.

Defn. B.9: Let I be an ideal of $R$. The radical of $I, \operatorname{rad}(I)$ is defined as the set $\left\{a_{\in} R \mid a^{2} r_{\varepsilon}\right.$ for some integer $\left.r>0\right\}$.

It can be shown easily that $\operatorname{rad}(\mathrm{I})$ is itself an ideal. An ideal which coincides with its radical is called a radical ideal.
Res-13: Let $V$ be an irreducible manifold of dimension $r$ in $\mathbb{C}^{n}$. Let $F \in \mathbb{C}[X]$ be such that $V \cap H_{F} \neq \emptyset$ and $V \notin H_{F}$. Then all the components of $\mathrm{V} \cap \mathrm{H}_{\mathrm{F}}$ have dimension $\mathrm{r}-1$.

Res-14: Hilbert's Nullstellensatz: Let I' be an ideal of K[X] where $K$ is algebraically closed. Then $\operatorname{Rad}\left(I^{\prime}\right)=I\left(M\left(I^{\prime}\right)\right)$.

This is a central result in algebraic geometry and is also vital to our work. This zero-theorem says that if $G \varepsilon K[X]$ vanishes where $F_{1}, F_{2}, \ldots F_{k} \in K[X]$ vanish jointly, then $G^{m}=\sum_{i=1}^{k} f_{i} \cdot F_{i}$ (Hilbert's Formula) for some positive interger $m$ and $f_{i} \varepsilon K[X]$. Note that K must be a closed field.

## B-5

This theorem gives the form of the set of all polynomials which vanish on the set of common zeroes of a set of polynomials. Corollaries
(a) If $I^{\prime}$ is a radical ideal in $K[\underset{\sim}{X}]$ then $I\left(M\left(I^{\prime}\right)\right)=I^{\prime}$. So there is a 1-1 correspondence between radical ideals and manifolds. Also if ( $F_{1}, F_{2}, \ldots . F_{k}$ ) is a prime ideal, then $m=1$ in Hilbert's formula.
(b) If I' is prime then $M\left(I^{\prime}\right)$ is irreducible. Thus there is a $1-1$ correspondence between prime ideals and irreducible manifolds.
(c) Let $F \in R\left[X_{\sim}\right]$ where $F=F_{1}^{n_{1}} \cdot F_{2}^{n_{2}} \ldots . . F_{k}^{n k}$ is the decomposition of $F$ into its irreducible factors $F_{1}, F_{2}, \ldots, F_{k}$. Then $M(F)=$ $\bigcup_{j=1} M\left(F_{i}\right)$ is the decomposition of $M(F)$ and $\left.I(M(F))=F_{1} \cdot F_{2} \cdot \ldots \cdot F_{k}\right)$. There exists thus a 1-1 correspondence between irreducible polynomials in $R[\underset{\sim}{X}]$ (up to a nonzero constant) and irreducible hypersurfaces in $\mathrm{R}^{\mathrm{n}}$.

## Results Derived

In this section we derive Thm 1, Thm 2 and Thm 3, the last of which concerns the relationship between an arbitrary rational function and a set of reference rationals on whose common zeroes it vanishes. But first we establish two lemmas.
Lemma 1: Let $A, B_{1}, B_{2}, \ldots B_{k}$ be distinct irreducible manifolds and let $C$ be any manifold such that $C \supset A-\left({\underset{i}{k}}_{k}^{u_{i}} B_{i}\right)$. Then $C \supset A$.
Proof: If $A-\left(\bigcup_{i=1} B_{i}\right)=A$ then the lemma is trivially true. Therefore assume otherwise, i.e. $A \cap\left({ }_{i=1}^{k} B_{i}\right) \neq \varnothing$ 。 Let $D=A \cup\left({ }_{i} \underline{\underline{I}}_{1} B_{i}\right)$. Then by Res-11, the unique decomposition theorem, $A \cup B_{1} \cup B_{2} \cup \ldots \cup B_{k}$ is the unique decomposition of $D$. Suppose the lemma is false, i.e. $C \neq A$. But $C \supset A-{\underset{j}{j}}_{k}^{k} B_{i} \quad$ (hypothesis)
Therefore $A \cap C \supset A \cap\left[A-{\underset{j}{=}}_{\substack{k}} B_{i}\right]=A-{ }_{i=1}^{k} B_{i}$ 。
Therefore $(A \cap C) \cup\left[{ }_{k}^{k}{ }_{j}^{k} B_{i}\right] \sqsupset(A-\underbrace{k}_{i=1} B_{i}) \cup\left[\bigcup_{i=1}^{k} B_{i}\right]$
ie. $(A \cap C) \cup\left[{ }_{i=1}^{k} B_{i}\right] \supset A \cup\left[{ }_{i=1}^{k} B_{i}\right]$

But $(A \cap C) \cup\left[\stackrel{U}{i}_{i=1}^{k} B_{i}\right] \subset A \cup\left[{ }_{i=1}^{k} B_{i}\right]$ since $A \cap C \in A$ ．
Therefore $(A \cap C) \cup\left[{ }_{i=1}^{k} B_{i}\right]=A \cup\left[{ }_{i=1}^{k} B_{i}\right]=D$ since $A \subset B$ and $A \sim B \rightarrow$ $A=B$ ．
Now by assumption A $\cap C \neq A[c f . C \neq A]$ and whether $A \cap C$ is irreducible or not，we have displayed two distinct decompositions of $D-a$ contradiction of Res－11．Therefore CDA．QED

Lemma 2：Let $A$ and $B$ be any two manifolds with no irreducible components in common．Then for any manifold for which CゝA－B，CコA． Proof：Let $A={ }_{j}^{k} A_{i}$ and $B={ }_{j=1}^{l} B_{j}$ be the unique decompositions of $A$ and $B$ ．Then by the hypothesis $A_{i} \neq B_{j}$ for all $1<i<k$ and $1<j<l$ ．

$$
\begin{array}{lll} 
& C \supset U_{i} A_{i}-U_{j} B_{j} & (\text { hypothesis) } \\
\therefore & C \supset A_{i}-U_{j} B_{j} & (\text { for } i=1,2, \ldots k) \\
\therefore & C \supset A_{i} & (i=1,2, \ldots k) \text { by Lemma } 1 . \\
\therefore & C \supset{ }_{j=1}^{k} A_{i} & \text { QED. }
\end{array}
$$

Thm 1：Let $r(\underset{\sim}{X}) \equiv p(\underset{\sim}{x}) / q(\underset{\sim}{X})$ where $p$ and $q$ are relatively prime poly－ nomials．Then if any polynomial $p^{\prime}$ vanishes on $M(r) *$ it also vanishes on $M(p)$ ．
Proof：Let the unique factorisation of $p$ and $q$ be respectively ${ }_{i=1}^{n_{1}} p_{i}^{\sigma} i$
 $M\left(p_{j}\right) \neq M\left(q_{j}\right)$ ．Furthermore $M\left(p^{\prime}\right) \sqsupset M(r)=M(p)-M(q)$ 。 Therefore by lemma 2 $M\left(p^{\prime}\right) \supset M(p)$ ；i．e．$p^{\prime}$ vanishes on $M(p)$ ．QED。 Thm 2：Let $r_{1}, r_{2}, \ldots r_{k}$ be rational expressions in which $r_{i}=p_{j} / q_{i}$ （ $i=1,2, \ldots k$ ），$p_{i}$ and $q_{i}$ being relatively prime polynomials．The $p_{i}$ and $q_{j}(1<i, j<k)$ have no common factors．Then any polynomial $p$ which vanishes on $\bigcap_{j=1}^{k} M\left(r_{j}\right)$ also vanishes on $\sum_{j=1}^{k} M\left(p_{j}\right)$ 。

[^19]Proof: $\bigcap_{i} M\left(r_{i}\right)=\bigcap_{i}\left[M\left(p_{i}\right)-M\left(q_{i}\right)\right]$

$$
\begin{align*}
& =\bigcap_{i}\left[M\left(p_{i}\right) \cap M^{\prime}\left(q_{i}\right)\right] \\
& =\bigcap_{i} M\left(p_{i}\right) \cap\left[\bigcap_{i}^{\prime} M^{\prime}\left(q_{i}\right)\right] \\
& \left.=\bigcap_{i} M\left(p_{i}\right) \cap \prod_{i}^{i} M\left(q_{i}\right)\right]^{\prime}  \tag{*}\\
& =\bigcap_{i=7}^{K} M\left(p_{i}\right)-\underbrace{k}_{i=1} M\left(q_{i}\right) \ldots
\end{align*}
$$

Let the distinct prime factors of $p_{1}, p_{2}, \ldots, p_{k}$ and of $q_{1}, q_{2}, \ldots q_{k}$ be $p_{1}^{\prime}, p_{1}^{\prime}, \ldots . p_{m}^{\prime}$ and $q_{1}^{\prime}, q_{2}^{\prime} \ldots q_{n}^{\prime}$ respectively. By hypothesis, these two groups of factors are distinct and therefore $M\left(p_{j}^{\prime}\right) \neq M\left(q_{j}^{\prime}\right)$ for $a_{l l} i$ and $j$. Therefore $M\left(q_{1}^{\prime}\right), M\left(q_{2}^{\prime}\right), \ldots M\left(q_{n}^{\prime}\right)$ and the components of $\bigcap_{i=1}^{m} M\left(p_{i}^{\prime}\right)$ are distinct. This is because if $m=1$, then it is already true while if $m>1$, the components of $\left.{ }_{j}^{m}=1 . p_{j}^{\prime}\right)$ are of lower dimension (cf Res-13) than $M\left(q_{j}^{\prime}\right)(j=1,2, \ldots n)$ and they are therefore
 Noting (*) and applying lemma 2, $\bigcap_{i=1}^{k} M\left(r_{i}\right) \frown \bigcap_{i=1}^{m} M\left(p_{i}^{\prime}\right)=\bigcap_{i=1}^{k} M\left(p_{i}\right)$. But by hypothesis $M(p) \supset \bigcap_{i=1}^{k} M\left(r_{i}\right)$. Therefore $M(p) \supset \bigcap_{i=1}^{k} M\left(p_{i}\right)$, i.e. $p$ vanishes on ${ }_{i=1}^{k} M\left(p_{i}\right)$, QED.

Thm 3: Let $r_{1}, r_{2}, \ldots r_{k}$ be rational expressions where $r_{i}=p_{j} / q_{i}$ $(i=1,2, \ldots k)$, the $p_{i}$ and $q_{j}$ being relatively prime polynomials. The $p_{i}$ and $q_{j}(1 \leqslant i, j \leqslant k)$ have no common factors. If $r$ is any rational expression which vanishes on $\sum_{i=1}^{k} M\left(r_{i}\right)(p w d)$, then $r^{m}=\sum_{i=1}^{k} s_{i} \cdot r_{i}$ where $m$ is a positive integer and each $s_{i}$ is a rational expression which is not ill-defined all over $M\left(r_{i}\right)$. (All polynomials are assumed to be from $\mathrm{C}_{\left[\mathrm{K}_{\mathrm{N}}\right]}$ ).
Proof: Let $r=p / q$. If $r$ vanishes on $M=\bigcap_{i=1}^{k} M\left(r_{i}\right)$ then it is $p$ which vanishes on $M$. By Thm 2, $p$ vanishes on ${ }_{i=1}^{k} M\left(p_{i}\right)$ 。By Hilbert's nullstellensatz, $p^{m}=\sum_{i=1}^{k} h_{i} \cdot p_{i}$ where $m$ is a positive integer ( $m=1$ if the ideal ( $p_{1}, p_{2}, \ldots p_{k}$ ) is prime) and $h_{i}(i=1,2, \ldots k)$ are polynomials. Therefore $p^{m} / q^{m}=\sum_{i=1}^{k}\left(h_{i} \cdot p_{i}\right) / q^{m}={ }_{i=1}^{k}\left(\left(h_{i} \cdot q_{j}\right) / q^{m}\right) \cdot\left(p_{i} / q_{j}\right)$. This is of form $r^{m}=\sum_{j=1}^{k} s_{j} \cdot r_{i}$ where $s_{i}=\left(h_{j} \cdot q_{j}\right) / q^{m}$ and is therefore not ill-defined except where $q$ vanishes. But $M(q) \not \supset M\left(r_{j}\right)$ for else it is not possible for $r$ to vanish on $M$. Therefore as required $s_{i}$ is not ill-defined all over $M\left(r_{i}\right)$. QED.

APPENDIX C
















AGREEMENT
count






"
C-2
STEP
MACHINE OPINION





















C-3



Table C. 2 C-set Search Table


Table C. 2 Continued

1．EXP＝（1）（SIN－COS）中2
EXP－（2）：SIN42－2＊SIN－COS＊COS\＆2
EXP－（3）：1－2＊SIN＊COS
COMPILATION TIME：． 021 SEC．

|  | STEP | $\mathrm{N} \cdot \mathrm{COMP}$ | TIME－A | TIME－B | RUN＝1 | RUN－2 | RUN－3 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 1 | $1 \rightarrow 2$ | 1 | ． 007 SEC． | ． 007 sEC． | ALGEE | ALGEB | ALGEb |
| 2 | $1 \rightarrow 3$ | 7 | ． 024 SEC． | ． 014 SEC． | SMALL | SMALL | LARGE |
| 3 | 2－3 | 26 | .060 SEC． | .021 SEC． | SMALL | SMALL | SMALL |

2．EXP－（1）：（1－SIN＋2）－（1＋TAN＋Z）
EXP－（2）｜COS＊2\＃SECヶ2
EXP＝（3）：1
COMPILATION TIME：． 019 SEC．

|  | STEP | N＝COMP | TIME－A | TiME－B | RUN－1 | RUN－2 | RUN－3 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 4 | 1 由 2 | 24 | ． 071 SEC． | .030 SEC． | SMALL | SMALL | SMALL |
| 5 | 1 － 3 | 10 | ． 024 SEC． | .007 SEC． | LARCE | LARGE | LaRGE |
| 6 | 2 ＊ 3 | 10 | .027 SEC． | ．014 SEC． | SMALL | SMALL | SMALL |

3．EXP－（1）： $\operatorname{COT}+4-\operatorname{CSC}+4$
EXP－（2）：（COT＋2－CSC＋2）（COTャ2＋CSC＋2）
EXP＝（3）：－1＊（COT＋2＊CSC＋2）
EXP－（4）：-1 （CSC $\uparrow 2-1+\operatorname{CSC}+2)$
EXP－（5）：1－2＊CSC $\uparrow 2$
COMPILATION TIME：． 048 SEC．

|  | STEP | N－COMP | T1ME－A |  | TIME－B |  | RUN－1 | RUN－2 | RUN－3 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 7 | 1 － 2 | 1 | ． 006 | SEC． | .006 | SEC． | ALGEB | ALGEE | ALGEB |
| 8 | 1 －3 | 29 | .099 | SEC． | ． 031 | SEC． | SMALL | LARGE | SMALL |
| 9 | $1 \rightarrow 4$ | 49 | ． 150 | SEC． | .039 | SEC． | LARGE | LARGE | LARGE |
| 10 | 1 ＊ 5 | 16 | .052 | SEC． | .019 | SEC． | LARGE | LARGE | LARGE |
| 11 | 2 －3 | 14 | ． 048 | sEC． | ． 023 | SEC． | SMALL | SMALL | SMALL |
| 12 | $2 \rightarrow 4$ | 34 | ． 104 | SEC． | ． 039 | SEC． | SMALL | SMALL | SMALL |
| 13 | 2 － 5 | 34 | ． 111 | SEC． | ． 038 | SEC． | SMALL | SMALL | LARGE |
| 14 | 3 － 4 | 23 | ． 063 | SEC． | ． 024 | SEC． | SMALL | SMALL | SMALL |
| 15 | $3-5$ | 27 | .087 | SEC． | ． 029 | SEC． | SMALL | SMALL | LARGE |
| 16 | 4 － 5 | 1 | ． 006 | SEC． | ． 006 | SEC． | ALGEB | ALGEB | AL．GEB |

4．EXP－（1）：（1－SIN＾2）＊CSC＋2
EXP－（2）： $\cos +2 * C S C+2$
EXP＝（3）：COS＾2／SIN＋Z
EXP＝（4）：COT＋2

## C-7



## C-8

7. EXP=(1): $(1-T A N) *(1-C O T)$

EXP=(2): 1-TAN-COT+TAN*COT
EXP-(3): 1-COT-TAN+1
EXP-(4): $2-C O S / S I N-S I N / C O S$
EXP-(5): $2-(\cos \uparrow 2+5 I N \uparrow 2) /(S I N * \operatorname{COS})$
EXP-(6): 2-1/(SIN*COS)
EXP-(7): 2-1/COS*1/SIN
EXP-(8): 2-SECHCSC
COMPILATION TIME: . 056 SEC.

|  | STEP | N-COMP | TIME-A |  | TIME-B |  | RUN-1 | RUN-2 | RUN-3 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 44 | 1 - 2 | 1 | . 007 | SEC. | . 007 | SEC. | ALGEB | ALGEB | ALGEB |
| 45 | 1 - 3 | 69 | . 103 | SEC. | . 034 | SEC. | SMALL | SMALL | LARGE |
| 46 | $1 \rightarrow 4$ | 30 | .080 | SEC. | . 031 | SEC. | LARGE | LARGE | LARGE |
| 47 | $1 \rightarrow 5$ | 15 | . 070 | SEC. | . 034 | SEC. | LARGE | LARGE | LARGE |
| 48 | $1 \rightarrow 6$ | 15 | . 047 | SEC. | . 024 | SEC. | LARGE | LARGE | LARGE |
| 49 | $1+7$ | 15 | . 051 | SEC. | . 026 | SEC. | LARGE | LARGE |  |
| 50 | 1 ¢ 8 | 15 | . 045 | SEC. | . 025 | SEC. | LARGE | LARGE | LARGE |
| 51 | 2 ค 3 | 19 | . 034 | SEC. | . 020 | SEC. | SMALL | SMALL | SMALL |
| 52 | $2 \rightarrow 4$ | 51 | . 086 | sEC. | . 037 | SEC. | SMALL | SMALL | LARGE |
| 53 | $2 \rightarrow 5$ | 66 | . 224 | SEC. | . 059 | SEC. | LARGE | LARGE | LARGE |
| 54 | $2 \rightarrow 6$ | 59 | . 132 | SEC. | . 045 | SEC. | LARGE | LARGE | LARGE |
| 55 | $2 \rightarrow 7$ | 69 | . 154 | SEC. | . 047 | SEC. | LARGE | LARGE | LARGE |
| 56 | 2 - 8 | 46 | . 099 | SEC. | .037 | SEC. | LARGE | LARGE | LARGE |
| 57 | 3 * 4 | 33 | . 059 | sEC. | . 027 | SEC. | SMALL | SMALL | SMALL |
| 58 | $3-5$ | 63 | . 201 | SEC. | . 053 | SEC. | LARGE | LARGE | LARGE |
| 59 | 3*6 | 56 | . 114 | SEC. | . 038 | SEC. | LARGE | LARGE | LARGE |
| 60 | $3 * 7$ | 66 | .134 | SEC. | . 041 | SEC. | LARGE | LARGE |  |
| 61 | $3 \rightarrow 8$ | 43 | .081 | SEC. | . 031 | SEC. | LARGE | LARGE | LARGE |
| 62 | $4-5$ | 1 | . 006 | SEC. | .006 | SEC. | ALGEB | ALGEB |  |
| 63 | $4-6$ | 39 | . 101 | SEC. | . 033 | SEC. | SMALL | LARGE | SMALL |
| 64 | $4 * 7$ | 49 | .118 | SEC. | . 034 | SEC. | SMALL | LARGE | SMALL |
| 65 | $4 * 8$ | 26 | . 067 | SEC. | . 025 | SEC. | LARGE | LARGE SMALL | LARGE SMALL |
| 66 | 5-6 | 17 | . 058 | SEC. | . 024 | SEC. | SMALL | SMALL | SMALL <br> SMALL |
| 67 | $5 \rightarrow 7$ | 17 | . 060 | SEC. | . 025 | SEC. | SMALL | SMALL | SMALL |
| 68 | $5 \rightarrow 8$ | 31 | . 082 | SEC. | . 036 | SEC. | SMALL |  |  |
| 69 | $6 \rightarrow 7$ | 1 | . 005 | SEC. | . 005 | SEC. | ALGEB | ALGEB | ALGEB |
| 70 | $6 \rightarrow 8$ | 26 | . 056 | SEC. | . 024 | SEC. | SMALL | SMALL | SMALL |
| 1 | 7 +8 | 24 | . 049 | SEC. | . 023 | SEC. | SMALL | SMALL | SMALL |

8. EXP-(1): $((1+T A N=S E C) /(S E C+T A N-1)) /((1+S E C-T A N) /(S E C+T A N+1))$

EXP-(2): $(1+$ TAN-SEC)*(SEC+TAN+1) $) /((S E C+T A N-1) *(1+S E C-T A N))$
EXP-(3): $((1+T A N) \uparrow 2-S E C \uparrow 2) /(S E C \uparrow 2-(T A N-1) \uparrow 2)$
EXP-(4): (1+2\#TAN+TAN+2-SEC+2)/(SEC+2-TAN+2+2*TAN-1)
EXP-(5): 2*TAN/(2\#TAN)
EXP-(6): 1
COMPILATION TIME: .086 SEC.

|  | STEP | $\mathrm{N}=$ COMP | TIME-A |  | TIME-B |  | RUN-1 | RUN-2 | RUN-3 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 72 | 1 +2 | 1 | .007 | SEC. | . 007 | SEC. | ALGEB | ALGEB | ALGEB |
| 73 | 1 - 3 | 1 | . 005 | SEC. | . 005 | SEC. | ALGEB | ALGEB | ALGEG |
| 74 | $1 \rightarrow 4$ | 1 | . 005 | SEC. | . 005 | SEC. | ALGEB | ALGEB | LLGEB |
| 75 | $1 \rightarrow 5$ | 82 | .275 | SEC. | . 053 | SEC. | LARGE | LARGE | LARGE |
| 76 | 1 - 6 | 26 | .116 | SEC. | . 032 | SEC. | LARGE | LARGE | LARGE <br> ALGEB |
| 77 | $2 \rightarrow 3$ | 1 | .006 | SEC. | . 006 | SEC. | ALGEB | ALGEB |  |



|  | COMPILATION TIME: |  | . 105 SEC. |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | STEP | N-COMP | TIM | -A | TIM | - | RUN=1 | RUN-2 | RUN-3 |
| 103 | 1 + 2 | 55 | . 146 | SEC. | . 060 | SEC. | SMALL | SMALL | SMALL |
| 104 | $1 \rightarrow 3$ | 62 | . 253 | SEC. | . 083 | SEC. | SMALL | SMALL LARGE | LARGE LARGE |
| 105 | 1 H 4 | 36 | . 254 | SEC. | . 071 | SEC. | LARGE |  |  |
| 106 | 1 - 5 | 36 | . 195 | SEC. | . 060 | SEC. | LARGE | LARGE | LARGE |
| 107 | 1 -6 | 16 | .116 | SEC. | . 051 | SEC. | LARGE | LARGE | LARGE |
| 108 | 1 -7 | 25 | . 098 | SEC. | . 035 | SEC. | LARGE | LARGE | LARGE |
| 109 | $2 \rightarrow 3$ | 1 | . 006 | SEC. | . 006 | SEC. | ALGEB | ALGEB | ALGEB |
| 110 | $2 \rightarrow 4$ | 1 | . 005 | SEC. | . 005 | SEC. | ALGEB | ALGEB | ALGEB |
| 111 | $2-5$ | 1 | .005 | SEC. | .005 | SEC. | ALGEB | ALGEB | ALGEB |
| 112 | $2 \rightarrow 6$ | 1 | .005 | SEC. | . 005 | SEC. | ALGEB | ALGEB | ALGEB |
| 113 | $2 \rightarrow 7$ | 25 | . 123 | SEC. | . 037 | SEC. | LARGE | LARGE | LARGE |
| 114 | $3+4$ |  | .007 | SEC. | .007 | SEC. | ALGEB | ALGEB | ALGEB |
| 115 | $3 \rightarrow 5$ | 1 | . 005 | SEC. | . 005 | SEC. | ALGEB | ALGEB | ALGEB |
| 116 | $3+6$ | 1 | . 005 | SEC. | . 005 | SEC. | ALGEB | ALGEB | ALGEB |
| 117 | $3 \rightarrow 7$ | 61 | .308 | SEC. | . 053 | SEC. | LARGE | LARGE | LARGE |
| 118 | $4 \sim 5$ | 1 | . 006 | SEC. | . 006 | SEC. | ALGEB | ALGEB | ALGEB |
| 119 | 4 -6 | 1 | . 006 | SEC. | .006 | SEC. | ALGEB | ALGEB | ALGEB |
| 120 | 4 -7 | 61 | . 308 | SEC. | . 054 | SEC. | LARGE | LARGE | LARGE |
| 121 | $5 \cdots 6$ | 1 | . 006 | SEC. | .006 | SEC. | ALGEB | ALGEB |  |
| 122 | $5 \rightarrow 7$ | 61 | .238 | SEC. | . 047 | SEC. | LARGE | LARGE | LARGE |
| 123 | $6 \rightarrow 7$ | 25 | .107 | SEC. | .033 | SEC. | LARGE | LARGE | LARGE |

12. EXP-(1): $\operatorname{CSC} /(\operatorname{CSC}-1)+\mathrm{CSC} /(\operatorname{CSC}+1)$

EXP-(2): $(1 / S I N) /(1 / S I N=1)+(1 / S I N) /(1 / S I N+1)$
EXP-(3): 1/(1-SIN)+1/(1+SIN)
EXP-(4): $(1+S I N+1-S I N) /(1-S I N+2)$
EXP-(5): $2 / \operatorname{COS} \uparrow 2$
EXP-(6): 2*SEC*2
COMPILATION TIME: . 052 SEC.

|  | STEP | $\mathrm{N}-\mathrm{COMP}$ | TIME-A |  | TIME-A |  | RUN=1 | RUN-2 | RUN-3 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 124 | 1 * 2 | 50 | . 138 | SEC. | .063 | SEC. | SMALL | SMALL | SMALL |
| 125 | 1 円 3 | 54 | . 124 | SEC. | . 047 | SEC. | LARGE | LARGE | LARGE |
| 126 | $1 \rightarrow 4$ | 15 | .068 | SEC. | . 027 | SEC. | LARGE | LARGE | LARGE |
| 127 | 1 + 5 | 15 | . 040 | SEC. | .011 | SEC. | LARGE | LARGE | LARGE |
| 128 | $1 \rightarrow 6$ | 15 | . 039 | SEC. | . 010 | SEC. | LARGE | LARGE | LARGE |
| 129 | 2 - 3 | 1 | . 006 | SEC. | . 006 | SEC. | ALGEB |  |  |
| 130 | $2 \rightarrow 4$ | 1 | . 005 | SEC. | . 005 | SEC. | ALGEB | $\begin{aligned} & \text { ALGEB } \\ & \hline \end{aligned}$ | ALGEB SMALL |
| 131 | $2-5$ | 15 | . 066 | SEC. | . 026 | SEC. | SMALL | Large | SARGE |
| 132 | $2-6$ | 15 | . 052 | SEC. | .012 | SEC. | LARGE | LARGE | LARGE |
| 133 | 3 - 4 | 1 | . 008 | SEC. | . 008 | SEC. | ALGEB |  |  |
| 134 | $3 \rightarrow 5$ | 15 | . 047 | SEC. | . 020 | SEC. | SMALL | LARGE | SMALL |
| 135 | $3 \rightarrow 6$ | 15 | .037 | SEC. | .010 | SEC. | LaRGE | LARGE | LARGE |
| 136 | $4 \rightarrow 5$ | 13 | . 043 | SEC. | . 018 | SEC. | SMALL | SMALL | SMALL |
| 137 | $4 \rightarrow 6$ | 5 | . 024 | SEC. | . 010 | SEC. | LARGE | LARGE | LARGE SMALL |
| 138 | $5+6$ | 5 | . 022 | SEC. | . 011 | SEC. | SMALL |  |  |

13. EXP=(1): $\operatorname{CSC} /(C O T+T A N)$

EXP-(2): (1/SIN)/(COS/SIN+SIN/COS)
EXP-(3): (1/SIN)/((COS\&2+SIN+2)/(SIN*COS))
EXP-(4): (1/SIN)*(SIN*COS)/(SIN*2*COS*2)

|  | EXP＝（5）： $\cos$ |  |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | COMPILATION TIME： |  |  | ． 048 SEC |  |  |  |  |  |
|  | STEP | N－COMP | TIM | －$A$ | TIM |  | RUN＝1 | RUN－2 | RUN－3 |
| 139 | 1 م 2 | 30 | ． 072 | sEC． | ． 032 | sEC． | SMALL | SMALL | SMALL |
| 140 | 1 －3 | 47 | － 134 | SEC． | ． 051 | SEC． | LARGE SMALL | LARGE SMALL | $\begin{aligned} & \text { LARGE } \\ & \text { SMALL } \end{aligned}$ |
| 141 | $1 \rightarrow 4$ | 21 | ． 069 | SEC． | ． 037 | SEC． | －SMALL |  |  |
| 142 | 1 ＋ 5 | 10 | ． 021 | SEC． | .012 | SEC． | LARGE | LARGE | LARGE ALGEB |
| 143 | $2 \rightarrow 3$ | 1 | ． 006 | SEC． | ． 006 | SEC． | ALGEB | ALGEB | ALGEB |
| 144 | $2 \rightarrow 4$ | 1 | ． 006 | SEC． | ． 006 | SEC． | ALGEB | ALGEB | SMALL |
| 145 | 2－5 | 28 | ． 070 | SEC． | ． 027 | SEC． | SMALL | LARGE | SMALL |
| 146 | $3 \rightarrow 4$ | 1 | ． 006 | SEC． | ． 006 | SEC． | ALGEB | ALGEB | ALGEB |
| 147 | $3 * 5$ | 28 | ． 095 | SEC． | ． 033 | SEC． | SMALL | LARGE | SMALL |
| 148 | 4 － 5 | 29 | ． 059 | SEC． | ． 026 | SEC． | SMALL | SMALL | SMALL |

14．EXP－（1）：（SEC－TAN）／（SEC＋TAN）
EXP－（2）：（SEC－TAN）\＃（SEC－TAN）／（（SEC＊TAN）＊（SEC－TAN）） EXP－（3）：（SEC个2－2\＃SEC＊TAN＋TAN＋2）／（SEC个2－TAN＊2）
$E X P-(4): S E C+2=2 * S E C \neq T A N+T A N+2$
EXP－（5）： $1-2 * S E C * T A N+2 \# T A N \uparrow 2$

|  | COMPILATION TIME： |  | ． 060 SEC． |  |  |  | RUN－1 | RUN－2 | RUN－3 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | STEP | N－COMP | TIME－A |  | TIME－B |  |  |  |  |
| 149 | 1 1 2 | 1 | ． 007 | SEC． | ． 007 | SEC． | ALGEB | ALGEB | ALGEB |
| 150 | 1 － 3 | O | ． 005 | SEC． | ． 005 | SEC． | ALGEB SMAL | ALGEB LARGE | ALGEB <br> SMALL |
| 151 | 1 － 4 | 30 | .103 | SEC． | ． 028 | SEC． | SMALL |  |  |
| 152 153 | 1 2 | 30 1 | .097 .006 | SEC． SEC． | ． 027 | SEC． SEC． | LARGE ALGE日 | LARGE <br> ALGEB | LARGE <br> ALGEB |
| 154 | 2 － 4 | 46 | .172 | SEC． | .033 | SEC． | SMALL | SMALL | SMALL |
| 155 | $2 \rightarrow 5$ | 74 | .252 | SEC． | ． 056 | SEC． | SMALL | SMALL |  |
| 156 | $3 \rightarrow 4$ | 25 | ． 117 | SEC． | ． 024 | SEC． | SMALL | SMALL | SMALL |
| 157 | 3 － 5 | 62 | ． 228 | SEC． | ． 054 | SEC． | SMALL | SMALL | Large |
| 158 | $4 \rightarrow 5$ | 39 | .115 | SEC． | .031 | SEC． | SMALL | SMALL | LARGE |

15．EXP－（1）：TAN／（1－COT）＋COT／（1－TAN）
EXP－（2）：（SIN／COS）／（1－COS／SIN）＋（COS／SIN）／（I－SIN／COS）
EXP－（3）：SIN＾2／（COS＊（SIN－COS））$+\operatorname{COS} \uparrow 2 /(S I N *(C O S-S I N))$
EXP－（4）：（SIN＋3－COS＊3）／（COS＊SIN＊（SIN－COS））
EXP＝（5）：（SIN－COS）＊（SINヶ2＋COSヶ2＋SIN＊COS）／（（SIN－COS）＊5IN＊COS）
EXP－（6）：（SIN＋2＋COS＾2）／（SIN＊COS）＋（SIN＊COS）／（SIN＊COS）
EXP＝（7）： $1 /(\operatorname{COS} \# S I N)+1$
EXP＝（8）：SEC＊CSC＋1
COMPILATION TIME： .109 SEC．

|  | STEP | $\mathrm{N}=$ COMP | TIME－A |  | TIME－B |  | RUN－1 | RUN－2 | RUN－3 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 159 | 1 H 2 | 70 | ． 152 | SEC． | ． 064 | SEC． | SMALL | SMALL | SMALL |
| 160 | 1 ＋ 3 | 36 | .157 | SEC． | ． 062 | SEC． | LARGE | LARGE | LARGE |
| 161 | $1 \rightarrow 4$ | 15 | ． 090 | SEC． | ． 041 | SEC． | LARGE | LARGE | LARGE |
| 162 | 1 － 5 | 30 | ． 188 | SEC． | ． 056 | SEC． | LARGE | LARGE <br> LARGE | LARG |


16. EXP-(1): $(1+\operatorname{COT}-\operatorname{CSC}) *(1+T A N+S E C)$

EXP-(2): $(1+\operatorname{COS} / S I N-1 / S I N)(1+\operatorname{SIN} / \operatorname{COS}+1 / \operatorname{COS})$
EXP-(3): ((SIN+COS-1)/SIN)*((COS*SIN+1)/COS)
EXP-(4): ((SIN+COS) $+2-1) /(S I N * C O S)$
EXP-(5): (SIN+2+COS+2+2*SIN*COS-1)/(SIN*COS)
EXP-(6): (1+2*SIN*COS=1)/(SIN*COS)
EXP-(7): 2
COMPILATION TIME: . 078 SEC.

|  | STEP | $\mathrm{N}-\mathrm{COMP}$ | TIME-A | TIME-B |  | RUN-1 | RUN-2 | RUN-3 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 187 | 1 * 2 | 44 | .116 5EC. | . 055 | sEC. | SMALL | SMALL | SMALL |
| 188 189 | 1 | 78 16 | .196 SEC. <br> .132 SEC. | . 068 | $\begin{aligned} & \text { SEC. } \\ & \text { SEC. } \end{aligned}$ | LARGE <br> LARGE | LARGE <br> LARGE | LARGE LARGE |
| 190 | 1 由 5 | 16 | .183 SEC. | .110 | SEC. | LARGE | LARGE | LARGE |
| 191 | 1 * 6 | 16 | . 135 SEC. | . 084 | SEC. | LARGE | LARGE | LARGE |
| 192 | $1 \rightarrow 7$ | 10 | . 038 SEC. | . 022 | SEC. | LARGE | LARGE | LARGE |
| 193 | 2 - 3 | 1 | . 006 SEC. | . 006 | SEC. | ALOEB | ALGEB | ALGEB |
| 194 | $2+4$ | 1 | . 005 SEC. | . 005 | SEC. | ALGEB | ALGEB | ALGEB |
| 195 | $2-5$ | 1 | .006 SEC. | . 006 | SEC. | ALGE日 | ALGEB | ALGEB |
| 196 | 2 -6 | 16 | .098 SEC. | .037 | SEC. | LARGE | LARGE | LARGE |
| 197 | 2 -7 | 10 | . 046 SEC. | .023 | SEC. | LARGE | LARGE | LARGE |
| 198 | $3 \rightarrow 4$ | 1 | .007 SEC. | .007 | SEC. | ALGEB | ALGEB | ALGEB |
| 199 | 3 - 5 | 1 | . 005 sEC. | .005 | SEC. | ALGEB | ALGEB | ALGEB |
| 200 | $3-6$ | 39 | .195 SEC. | . 042 | SEC. | LARGE | LARGE | LARGE |
| 201 | 3 - 7 | 26 | .080 SEC. | . 025 | SEC. | LARGE | LARGE | LARGE |
| 202 | 4 - 5 | 1 | .007 SEC. | . 007 | SEC. | ALGEB | ALGEB | ALGEB |
| 203 | 4 -6 | 26 | .081 SEC. | . 031 | SEC. | SMALL | SMALL | LARGE |
| 204 | $4 \rightarrow 7$ | 10 | . 033 SEC. | . 016 | SEC. | LARGE | LARGE | LARGE |
| 205 | $5 * 6$ | 45 | . 115 SEC. | .043 | SEC. | SMALL | SMALL | SMALL |
| 206 | $5 * 7$ | 10 | .051 SEC. | . 024 | SEC. | LARGE | LARGE | LARGE |
| 207 | $6 \rightarrow 7$ | 1 | . 007 SEC. | . 007 | SEC. | ALGEE | ALGEB | ALGEB |

Table C. 3 Continued

## C－13

```
INIT TIMEP R. R NOW= R. R FLAPSED TIME=*9309.7500 SE
1. EXP=(1): (SIN-COS)^?
    EXP=(2): SIN^2-2*SIN*COS*COS&2
    FXP-(3): 1-P#SIN*COS
llll
3 2-3 G(L) 由G(R): SIN2+\operatorname{Cos}2+1
2. FXP=(1): (1-SIN^2)*(1+TAN^2)
    EXP-(2): COS^2*SEC^?
    EXP=(3): 1
41*2 G(L) & G(R): 1-SIN2+COS2
5 & 3 NON-SINGLETON CSET
```



```
3. EXP=(1): COT^4-CSC44
    EXP-(2): (COT^2-CSC*2)*(COT&2+CSC^2)
    EXP=(3): -1*(COT^?+CSC^2)
    EXP-(4): -1#(CSC^?-1+CSC^2)
    EXP-(5): 1-2*CSC^?
\begin{tabular}{|c|c|c|c|c|}
\hline 7 & \(1 \rightarrow 2\) & ALGER & \multicolumn{2}{|l|}{} \\
\hline 8 & 1 ＋ 3 & \(F(X) * G(L)\)＊ & \(F(X) * G(R): ~ C S ~\) & －COT2¢1 \\
\hline 9 & 1 ＋ 4 & \(F(X)+G(L) \uparrow 2\) & \(\rightarrow F(x)+G(R) \uparrow 2!\) & CSC2－1ヵCOT2 \\
\hline 10 & \(1 \rightarrow 5\) & \(F(X)=G(L) \uparrow\) ？ & \(\rightarrow F(x)-G(R) \uparrow 2:\) & \multirow[t]{2}{*}{cscz－1mcote} \\
\hline 11 & 2 － 3 & \(G(L) * G(R):\) & CSC2－COT2円1 & \\
\hline \multirow[t]{2}{*}{12} & \(2 \rightarrow 4\) & \(G(L) * G(R):\) & CSC2－COT2ml & \\
\hline & & \(G(L) * G(R):\) & COT2ヵCsc2－1 & \\
\hline \multirow[t]{2}{*}{13} & \(2+5\) & \(G(L)+G(R):\) & \multicolumn{2}{|l|}{CSC2－COT2＋1} \\
\hline & & \(F(X)+G(L)\)＊ & \(F(X)+G(R): \quad C s\) & Csc2mCOT2＋1 \\
\hline 14 & \(3 \rightarrow 4\) & \(G(L) \rightarrow G(R):\) & COT \(2 \rightarrow\) cscer -1 & \\
\hline 15 & \(3 \rightarrow 5\) & \(F(X)+G(L)\) & \(F(x)+G(R): \quad C S\) & \(2 \rightarrow\) COTR +1 \\
\hline 16 & 4 － 5 & ALGER & & \\
\hline
\end{tabular}
4. EXP-(1): (1-5IN^2)*CSC\uparrow2
    F.XP-(2): cos^2#csc^?
    EXP-(3): cos+2/SIN+?
    FXP-(4): COT^2
\begin{tabular}{|c|c|c|c|c|c|c|c|c|}
\hline \multirow[t]{3}{*}{\[
\begin{aligned}
& 17 \\
& 18
\end{aligned}
\]} & \multirow{3}{*}{1} & \multirow[t]{3}{*}{} & \multicolumn{3}{|l|}{\multirow[t]{2}{*}{\[
\begin{aligned}
& G(L) \leftrightarrow G(R): \\
& G(L) \leftrightarrow G(R):
\end{aligned}
\]}} & \multicolumn{3}{|l|}{\multirow[t]{2}{*}{\[
\begin{aligned}
& 1-S I N 2 巾 \cos \\
& 1-S I N 2 \Pi \cos
\end{aligned}
\]}} \\
\hline & & & & & & & & \\
\hline & & & G（L） & ＊ & G（R）： & \(1 / 1\) & SC＋ & ャSIN \\
\hline 19 & 1 & － & NON－ & SIN & MGLETON & CSE & & \\
\hline 20 & 2 & － & G（L） & ＊ & \(G(R):\) & 1／C & 5C & \(\rightarrow\) SIN \\
\hline 21 & 2 & \(\rightarrow\) & G（L） & \(\uparrow\) ？ & －G（R） & ヶ2： & & COS＊C \\
\hline 22 & 3 & ＋ & \(G(L)\) & & ＋G（R） & ャ2： & & cos／5 \\
\hline
\end{tabular}
5. FXP=(1): (TAN^3-COT^3)/(TAN-COT)
    FXP-(2): ((TAN-COT)*(TAN^2+COT^2+TAN*COT))/(TAN-COT)
    EXP=(3):(TAN-COT)*(TAN*2+COT^2+1)/(TAN-COT)
    FXP=(4): TANAC+COT*?+1
```

Table C． 4 Latent Structure Analysis


## C-l5


8. $E X P-(1):((1+T A N-S E C) /(S E C+T A N-1)) /(1+S E C-T A N) /(S E C+T A N+1))$ EXP=(2): ( $(1+T A N-S E C) *(5 E C+T A N+1)) /((S E C+T A N-1) *(1+S E C-T A N))$
EXP=(3): $((1+$ TAN $) \uparrow 2-S E C \uparrow 2) /(S E C \uparrow 2-(T A N=1) \uparrow ?)$
EXP-(4): $(1+?$ \#TAN+TAN^2-SEC42)/(SEC^2-TAN^2+2*TAN-1)
EXP=(5): 2*TAN/(2*TAN)
FXP-(6): 1

| 72 | 1 | $\rightarrow 2$ | ALGER |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: |
| 73 | 1 | $\rightarrow 3$ | ALGER |  |  |
| 74 | 1 | + 4 | ALGER |  |  |
| 75 | 1 | $\rightarrow 5$ | UNCLASSIFIED |  |  |
| 76 | 1 | $\rightarrow 6$ | UNCLASSIFIED |  |  |
| 77 | 2 | $\rightarrow 3$ | ALGER |  |  |
| 78 | $?$ | - 4 | ALGER |  |  |
| 79 | 2 | - 5 | $\begin{array}{ll} F(X)+G(L) & \mapsto F(X)+G(R): \\ F(X)+G(L) & \mapsto F(X)+G(R): \end{array}$ |  | SEC2ヵTAN2+1 |
|  |  |  |  |  | TAN2+1 SEC? |
| 80 | 2 | + 6 | UNCLASSIFIED |  |  |
| 81 | 3 | - 4 | ALSER |  |  |
| 82 | 3 | $\rightarrow 5$ | $F(X)+G(L) * F$ | $F(X)+G(R):$ | SECZ-TAN2+1 |
|  |  |  | $F(X)+G(L) \rightarrow F$ | $F(X)+G(R):$ | TAN2+1巾SEC2 |
| 83 | 3 | +6 | UNCLASSIFIED |  |  |
| 84 | 4 | - 5 | $F(X) *(G)(L) \rightarrow$ | 0) 1 SEC? | $A N 2-1 \geqslant 0$ |
|  |  |  | $F(X) *$ (G) $L$ ) | 0): SEC2 | AN2=1 +0 |
| 85 | 4 | -6 | UNCLASSIFIED |  |  |
| 86 | 5 | $\rightarrow 6$ | ALGER |  |  |

9. $E X P-(1):(1+S I N+\operatorname{COS}) \uparrow$ ?

FXP-(3): 2+2*SIN+2*COS+2*SIN*COS
EXP-(4): 2*(1+SIN)*(1+COS)

> C-16


Table C. 4 Continued
12. $F X P=(1): C S C /(C S C-1)+C S C /(C S C+1)$

FXP=(2): $(1 / S I N) /(1 / S I N-)+(1 / S I N) /(1 / S I N+1)$
FXP=(3): $1 /(1-S I N)+1 /(1+S I N)$
EXP=(4): (1+SIN+1-SIN)/(1-SIN+2)
FXP-(5): 2/Cos+2
EXP=(6): 2*SEC个?


15. $E X P=(1): T A N /(1-C O T)+C O T /(1-T A N)$

EXP-(2): $(S I N / \operatorname{COS}) /(1-\operatorname{COS} / S I N)+(\operatorname{Cos} / 5 I N) /(1-S I N / \operatorname{COS})$
EXP=(3): SIN^2/(COS*(SIN-COS)) $+\operatorname{COS}+2 /(\operatorname{SIN}(\operatorname{COS}-5 I N))$
EXP=(4): (SIN^3-COS*3)/(COS*SIN*(SIN-COS))
EXP-(5): (SIN-COS)*(SIN\&2+COS+2+SIN*COS)/((SIN-COS)*SIN*COS)
EXP-(6): (SIN\& $+\cos \uparrow 2) /\left(S I N^{*} \operatorname{COS}\right)+\left(S I N^{*} \operatorname{COS}\right) /\left(S I N^{*} \operatorname{COS}\right)$
EXP-(7): 1/(cos*SIN)+1
EXP=(8): SEC\#CSC+1


Table C. 4 Continued

C-19


Note: RCP stands for 'reciprocal of'

Table C. 4 Continued

APPENDIX D

LISTING OF SUPER-2

```
    NOLIST SROGAM SUPERZ(INPUT,OUTPIIT,TAPEI=INPUT)
COMMON/LST/ICELL(511),ACELL(511),BCELL(511),KCELL(511),TPI,TPJ,
COMMONPOLE/IMP(100),ISTK(20),STK(20),RTK(20),IJ,IK,I1,I2,LAST,LNK
    COMMON/TAQ/H(14),TRGTAB(6),VTAB(26),TABA
    COMMON/BREG/IE(Z0):JE(20)
    COMMONTT/T1:TZ.T3.T4.T5.TS,V1,V2
    COMMONNXV/T(6),V(3),LQ(12),JFG(12),D(36),R(36)
    COMMON NA.JPAK,MONO.ISCH.EHR
    OUIVALENCE (U,TABB,
    EGUIVALENCE (U,TABB1)
    COMMON/FEB71/NT
    INTEGER TPI,TPJ:BPI,BPJ
    INTEGER H,TRGTAB
LOGICAL JPAK,MONO 
\ 535B,5058,560% ', 6.7,1,1,2,3,3,4,5,5,3RSIN,3RCOS,3RTAN
M,
8 3.982, 14.8542, 3.6603, 71,9726, 3.1212, 2.304, 8.9234,
```



```
E OAT, TABU, 2.7116, 4.92711, 7.00177, 15.33170, 11.03037,
*)
*)
H1,
```



```
M L.302,, 37.1232, 2.9674, 1.3374, 14.1046, 2.1628,
M 2.3032, 3.4042, -4.505P, 5.606, %.7072, 7.8082,
DATA JFG , 0102010444B, 0304051022日, 05061114118, %710152070B
| 11122124618, 13202530608, 21263134128, 27343540058,
```



```
0(7)=102300431068 & L'(5)=102030405138 & LO(6)=1415030405068
```




```
lol
\
V(1)=V(2)/V(1) S V(1)
\lll
V(20)=TAN(X2) & $ V(21)=1N(18) $ $ V V(22)=05(X2)
*)
N(26)=v(13)/v(1), V V(27)=V(2)/V(17), S V V(28)=V(2)*V(14
V(29)=1/v(28) S V(30)=v(13)/v(23) & V(31)=v(12)/v(2)
EKR=10E-G (f) ISCH=3312233113222112110
    jmitialise tablf of dicrepancy values
```



CALL TIME (1, r$)$
$1 H=2$
$I H=0$
$\mathrm{JH}=3$
$\mathrm{JH}=3$
$\mathrm{KH}=5$
....(*2)....











C $\quad S E C+2=T A N+2+1 \quad-T(1-1) \quad \$ \quad R(16)=1 / R(15)$

 $D(28)=A B S(1 /(T 5 * 2-T 3 * 2)-1)$
$R(18)=1 / R(17) \quad R(19)=A B S(T 5 * * 2 f(T 3 * * 2 * 11) \quad$ S $R(20)=1 / R(19)$

 $D(32)=A B S(1-1)(T 4 * * 2-T 6 * *))$
$R(24)=1 / R(23) \quad \$ \quad R(25)=A B S(T 4 * * 2 /(1 * T 6 * * 2)) \quad$ S $\quad R(26)=1 / R(25)$



 $T A N=S E C / C S C$
$D(35)=A B S(T 3-T S / T 4) \quad \Phi \quad R(35), R(33), R(34)$
$R(33)=A B S(T 3=T 4 / T 5) \quad$ S $R(34)=1 / R(33)$


- $T A 1=T \theta_{1}=T A 2=T A 2=0$

TAL $=T \mathrm{TH}_{1}$
NPRB $=0$
c fill table tabal, )
$\mathrm{DO}_{\mathrm{A}=\mathrm{I}}^{\mathrm{D}} \mathrm{I} \quad \mathrm{I}=1,10$
 $\operatorname{TABA}(4, I)=1 / T A B A(1, I)$
$T A B A(5, I)=1 / T A B A(2, I) \quad$, $T A B A(6, I)=1 / T A B A(3, I)$
$\underset{\substack{\text { INITIALISE } \\ \text { TPI } \\ \text { TPJ } \\ \text { IS }}}{\text { LIST AND POINTERS }}$

HPI $=511$
DO $12 I=1,510$
12
CCELL 11$)=1+1$
PRINT 15
NDO
15 FORMAT (1H1)
15 FORMAT(1H1),
c Get a new proof - initialise to beginning
20 CALL GINP(II)
.... (\#3)..


21 SPRA=NPRB +1

CALL TIME (0,Y)
147 FORMAT(/// /01H*,I3.*.*)
IEP=1
$\operatorname{LIST}(1)=10 \mathrm{HEXP}-10):$
$\operatorname{LIST}(1)=15 T(1)$

CALL GETEXP(II
CALL PRNTIO)
IF (IITNE.OGO TO 25
CALPOLISH
CALL POLISH
IE $I E P)=\angle A S T \quad \& \quad 1 E P=T E P * 1$


C ABOVE STATEMENTS ARE TEMPDRARY

- print out stuff
$40 \begin{gathered}J J=1 E P-1 \\ \text { CONTNUE } \\ \text { I } \\ \text { DO }\end{gathered}$

40 CONTINUE
CALL TIME
PRINT
PB
BB FORMAT $/ / 7 X$, *COMPILATION TIME: *,F9.3.* SEC.*)



NHTAEP-1 \& NSTTENST-1
IFINST.LT. 2) STOP 77
DO 1001 IMI $=1, N S T T$
DO 1000 JMJONSS.NST
$N=1+1 \quad N T=3$
$N=1+1$
$I H=J H=K H=L H=M H E N$
$\mathrm{A}_{1}=T \mathrm{~A}_{1}+T \times(1)$



- EVALUATE STFP TML $\rightarrow$ JMJ
It=IE(TMI) \$ JJ=IE(JMJ)

 IF(ABS(BCELLIII)-BCELL(JJ)).GT.ERR)GOTO 70
C STEP ALGE日RAIC

```
                                    ....(*4)....
```

    CALL TIME \((0, Y\)
    $T X(1)=T X(2)=T X(3)=T X(4)=Y \quad$ \& $\quad N Y(1)=N Y(2)=N Y(3)=N Y(4)=10$ HALGEBRA



C | 60 |
| :--- |
| 50 |
| c |



400 PRINT $67, N$, IMI, JMJ,NAT, TX (1), TX( 2 ), NY(1), NY(3), NY(4)



70 KS(1)=IITLSHFT(JJ,9) CALL COPY(II) s CALL COPY(JJ)
75 CAL IF (NH.EQ.1)NAT=NT IF (JT.EQ.O) GO TO AO
STEP LARG

 TF (ABS (BCELL(IS)-BCELL(JS)):OT,ERR) BOTO 75

822 FORMAT (10X; *AL GEERAIC*)
83 IF LGE:
$73 \mathrm{KE}, 0) 74,84$



GO TO 1000
$\mathrm{c}_{\mathrm{c}}{ }^{3}$
80 KP1NKP1+1 5 IF(KP1.LT.KP2)GO TO 75
CALL TIME $(0, Y)$
B4 CONTINEE


85
1000 c
c
001 CONTINELEASE(IE(IMI))
call release (IE (JMJ))
25 GO TO 20
26 PRINT 27
27 FORMAT $5 \times$.*SYNTAX LOUSY*)
27 FORMAT
GOTO
ENU
subroutine size(I, J)

XAPIIBPJINDEX
COMMOV/NOV/KS (25),JA(2,17),NSCH(2,3),K(2),JP(2),KP1,KPZ
COMMOV/XV/T (6),V(B)
COMMON/TT/T1,T2,G3:T4,T5,TG,V1,V2
CDMMON NX, JPAK:MONO. ISCH.ERR
COMMON/AFIH:JH KH,LHMHM, NH
NOTE ARAY K(2) INSEAD OF M(2) IN VIEW OF OTHER USE OF
 IIIII
GET STEP CONFIG
\&
JJJ=I2
at some later stage remove config test for comparison
$J=K F I G(11) 0 \cdot K F I G(12)$

IF((J.A.JFG(M)) NE:(JFG(M).A.77B))GO TO 10

10 If (ABS (V)
11 CALL RELEASE(III)
5 call release(juj)
REETURN
ASSUME
a NONZERO




TEST DIFFERENCE DISCREPANCIES
$11=L S H F T(J F G(M),-12), A, 77 \mathrm{~A}$
$I 2=L S F T(J F G),-6), A, 77 \mathrm{~A}$
20

IF(ABS (ABS (X1-x2)-D(II)).LT.ERR)GOTO 24

$\begin{array}{lll}\text { G0 TO } & 20 \\ \text { STEP } & \text { SMALL }\end{array}$
$24 \begin{aligned} & \text { Sot SMALL } \\ & \text { TRY RATIO DISCREPANCIES } \\ & \text { SO TO } 11\end{aligned}$
REMEMBER TO REMOVE IT SOME TIME FOR COMPARISON
26 IFINH.EQ, 3 )GOTO 11
F(ABS (V2).LT.10E-15)GOTO11
II=LSHFT(JFG(M),-24).4.778

IF(N.GT. 50 ) GOTO 29
IF (ABS ABS (X1/X2)-R(II)).LT.ERR)GOTO 2

GO TO
ENO
FUNCTION BCII
COMMON/LST/TCELL (511), ACFLL(511), 日CELL(511), KCELL(511), TPI,TPJ,
XEPIMPJ,INDEX
COMMON/POLE/IMP(100),ISTK(20),STK(20),RTK(20),IJ,IK,II,I2,LAST.LN

INTEGEH RL, $A$, FB, DF, FR

IF(NH.NE.1)RETURN


O FORMAT (5x, AFN BC
2 STK (I2) $=A C E L L(K)$
3 I $2=12+1$
4 IF(K.ER.I)GOTO 15 \& $K=L L(K)$ s IF(K.NE.OIGOTO 5

$$
\begin{aligned}
& \begin{array}{l}
\text { CONTINUE } \\
\text { BC=STK (1) \& RETURN }
\end{array} \\
& \text {....(\#6).... }
\end{aligned}
$$









FUNCTION AC(I) END
COMMON/LST/ICELL (511), ACELL(511), 日CELL(511),KCELL(511),TPI,TPJ,

COMMON/F/IH,JH,KH,LH,MH,N
IF (NHORE:I)RETURN


$12 \mathrm{STK}(12)=A C E L L(K)$

15 CONTINUE $\begin{aligned} & \text { AC=STK(1) S RETURN }\end{aligned}$





$c$





SUHROUTINE GNP(III)
COMMONPOLEIMP(10),ISTK(20),STK(20),RTK(20),IJ,IK,II,I2,LASTPLNK
COMMON/PRNTLISTI(10),

COMMON NX, JPAK, MONO
LOGICAL JPAK.MONO
LOGIEAL JP
 JPAK
II $=2$
2 READ 2 , KAD
IF (EOF. 1130 , 3

5 FORMAT: 5 IGNORED*2X,BORU
GO TO
10
$11=0$
$10 \quad 11=0$
MOPP(x) T TFINX.FQ.1RS)11,14

4 IK
RETURN
END
subroutine ietexpa
COMMON/LST/ICELL(511), ACFLL(511), 日CELL(511), KCELL(511). TPI,TPJ
COMMON/POLEFIMP (100),ISTK(20),STK(20),RTK(20),IJ,IK,I1,I2,LASTOLNK COMMON/TAB/H(14), TRGTAB(6),VTAB(26),TABA(6,10),TABE(6,10) COMMON NX,
INTEGER PP
INTEGER TPI,TPA,BPI, RPJ
c LOGICAL JPAK, MONO CURENT CHAR FOR LISting if Jpak is .t.


CCOCCCCCCC FOLLOWING 3 CARDS DFC 70 MODS


4. $\operatorname{IMP}_{\mathrm{IM}=P \mathrm{P}(\mathrm{IJ}(x)}$



1" $1 \mathrm{I}=1$ + RETURN
if JSAVENX \& KETKRNT=? \& IF(NX.GT.3EB)GO TO 35
C. 1, ALPHAHETIC


s KOUNT=KOUNT-
za IFECK IF A.h, ... X.Y.z one sin.cos. ...

c CHECK LEEAL TRIG FUNCTIO

22 CUNTINUE

NLERE: =JSAV
35 JSAV $=\mathrm{NX} X-2$
$36 \mathrm{NX}=\mathrm{PP}(x)$

c
IMP (IN) $=$ JSA ${ }^{\prime}+100$ 000 000
100 MILLION AS ADEND






 IF (NPAR.EG.O)RETURN
C 55 … $+\ldots$




NXPPP(X) ${ }^{5}$ GO TO 45
ANALYSING THE ARGUMENT SECTION OF A TRIG. FUNCTIO




70 IF (NX.GT: 32 B ) G0 TO 75
EXECTING
 MPAR=MPAR-1 $\quad{ }^{73}$ IMP(IJ) $=N X=P P(X) \quad$ s $\quad I J=1 J+1$
33 IF(INX.LT.45B).OR.(NX.GT. 508)) 10,64
75 NUMERIC STRING 1 IF(NX.GT.44BIGO To 10
$75 \mathrm{IF}(\mathrm{NX} \cdot \mathrm{GGT} .44$
$\mathrm{JSAV}=\mathrm{NX}-27$
$76 \mathrm{NX}=\mathrm{PP}(\mathrm{X})$
IFINX.GT.32B).A. (NX.LT,458)178:80
80 IF (JSAV.GT. 511 GO TO 10
So IT MAY PROVE TO BE A STONPID AND UNNECESSARY LIMIT -- 511 I MEAN
 IMP
60 TO
ENO
subroutine polis
COMMON/LST/ICELL(511),ACFLL(511),BCELL(511),KCELL(511), TPI,TPJ,

OMMON/POLE/IMP(1ח0),ISTK(20),STK(20),RTK(20),1J,IK,I1,12,LAST,LNK OMMOV/TAB/H(14), TRGTAB(G),VTAB(26), TARA (6,10), TABE (6.10)
OMMON/AUGZU/ARG(20), IRG
OMMON NX, JPAK, MONO
INTEGER H,TRGTAB
LOGICAL JPAK.MONO EXPRESSION (MODIFIED) IN IMP (1) ... IMP (IJJ-1


NDEX=0
$001001=1, J J$
$I T=I M P(I J-I)$
TEST IF NUMAER
IF (IT.LT. 1000000$)$ GO TO 10
RTK $(152)=5 T K(I 2)=I T-100000000$

c 10 CHECK FOR VARIABLE A.A..... X.Y.Z
RTK (L2) $=$ STK (Iz) $=V \operatorname{TAR}(I T)$
CALL
CALL ADLST(IT+100月) 60 TO 100
TEST FUR) OR
20 IFITT.GT. $72 H$ IGO TO 70


IF(IT-EQ.1R)IGO TO 10i)

IFII.EQ.JJ)
IF(IIR.EU.IRI).UR.(IR.EQ.IRA)IGO TO 100
IHE7 FOR IS 7
COOL FOR I
$35 \begin{gathered}\text { IF (11).EG. } 11 G 0 \\ \text { JK=1STK(11-1) }\end{gathered}$
IF (JK.EQ.1R))GO TO 37
COMPARE HIERACHIES
IF(HIIR).GE.H(JKI)GO TO 77



IR=IMP(IJ-I-1)

IFIR-HE-1RA)GO
IMP(IJ-I-1)=1Rゅ


55 IFiIT:NE...iR/IGO TO 60

$14=13$ $60 \quad 1035$

IR $=14$
H** SHOULD NDT GO TO
GE NECESSARY IN A MORKING VERSION
67 PRINT 68 FORMAT $/$... impossible at polish $68 \ldots$..
68 RETURN
SIN.COS,TAN, ...
70 CONTINUE $\quad$....(\#10)... IF (MONOIGO TO 73 \& $12=12-1$ STK(I2) =SINISTK(I2)
72 CALL ADLST(201B)
73 STK 122 )=TABA $(1 ; 1)$

 IF (MONO)GO TO 77
STK $(12)=\cos 157 K(I 2)$

76 CALL ADLST(2028)
$775 T K(12)=T A B A(2,1)$
607076
78 IF (IT. NE, $3 R T A N$ )GO TO 84
IF (MONO) GO TO B0
STK(I2) $=\operatorname{TAN}(S T K(I))$

80 STK (I2) $)=T A B A(301)$
RTK 112$)=T A B E(3.1)$




88 RTK(IT:NE. SRSEC)GO TO 92 IF (MONO) GO TO 90 STK $(12)=: / \operatorname{COS}(5 T K(12))$
RTK(12) $)=: \operatorname{TRG}(515 T K(12))$

89 CALL
90 STK $(12)=T A B A(5) 1)$

IF (IT.NE:3RCOT)GO TO 67
IFMONO)OTO 94
STK(IZ) $1 /$ TAN (STK(I2)
RTK (L2) =atRg ( $6 \cdot \operatorname{STK}(T)$ ) $)$

5 GO TO 100
s 60 TO 72
s $12=12-1$
${ }_{5}^{\text {GO }}$ TO $\operatorname{RTK}_{\text {RTK }}^{100}(I 2)=T A B B(2,1)$
5 12=12-1

100 continve s go to 93
102 NF(LI.EQ.1)GO REMAINING OPERATORS STILL IN ISTK( )
 10 RETUR
subroutine pak
COMMON/PRNT/LIST(10), KAD(Q0),IPAK,Ll,LZ


TPAK=LSHFT(IPAK:6).OR.IX

IF(L2.GT:0)RETUR
LISTLL) $\mathrm{L} 2=10$
I (LI)
PRINTLT:GIRETURN
 $\operatorname{LIST}(1)=10 \mathrm{H}$
$\mathrm{L}=2$
END
$\mathrm{IPAK}=0$
$\mathrm{P}=\mathrm{L}=\mathrm{L}+1$
IPAK $=0$
LZ $2=10$
subroutine phntill
COMMON/PKNT/LIST(10), KAD(80),IPAK,L1,LI
*** List current expression - do not advance line if i is nonzero IF (IPAK.EQ.01GO TO 10

*. above card uncertain

10 Li=L1-1
11
$1 F(1, N E, 0) 15,12$
12 PRINTNE:0)15,12
13 FORMAT $16 \times(L I S T(J), J=1, i 1)$
13 FORMAT (6x, 10A10)
15 PRINT 16, (LIST (J), J=1, LI)
i6 FORMAT (1H:
sUBROUTINE DP(M)
*E. INSERT COMMONP INTEGER ETC CAROS MM M M M $6, ~ \$ \quad 12=12-2$
-

15 CALL ADLST (M+200B)




RTK(12)=RTK(12+1) ©RTK(IZ) \& GO TO 15

KTK(I2) ERTK(I2+1)/RTK(IE) S $\quad$ G0 TO 15







subroutine adlst (m)
COMMON/POLE/IMP (100), ISTK(20), STK(20),RTK(20), IJ,IK,II,I2,LAST,LNK

XBPI, BP J.INDEX, RANK
INTEGER GIVE
c CALLED BY S/R POLISH TO ADD ON a cell-guad as the polish list
IS CREATED
LNK=GIVE(I) BACKWARDS
ACELL
(LLNK)
STK (I2)



integer function give (x)
COMMON/LST/ICELL(511), ACELL(511), BCELL(511),KCELL(511), PPIPTPJ
COMMON/F/IH:JH,KHpLHPAH.NH
c
GIVE=TPI CELL QUADRUPLE TPI=ICELL(TPI) S RETURN
end subroutine save (n)
COMMON/LST/ICELL(511). ACELL (511), BCELL (511), KCELL(511), TPI,TPJ,
XBPI,BPJOINDEX

C SAVE CELL-GUADN $\quad$ BPI=ICELLIBPI) $N$ RETURN
END
FUNCTION PP (K)
COMMON/POLE/IMP(100),ISTK(20),STK,20),RTK (20),IJ,IK,I1,IZ,LAST,LNK COMMON/PRNTALIST110):KAO(RO),IPAK,LI,LZ
INTEGER PP
INTEGER PP
LOGICAL JPAK, MONO
e** PP RETURNS NEXT NON-BLANK CHAR. UNLESS EOF ENCOUNTERED
c COMMON JPAK $\quad$ LOGICAL JPAK
RFEADELTABAD

IFIEOF:1)10,3
4 IF (KAD(IK), EQ.1R 15.6

6 PP=KAU (IK)
RETURN
S
10 PP=0 S RETURN


```
\(\ldots\left({ }^{(\# 13)} \ldots\right.\)
INTEGER FUNCTION RANK（L）
INTEGER RL，DA，FF，DF：FR
COMMON NX，JPAK，MONO：ISCH，ERR
lOGICAL MONO
c c 23 NOY 1970 RETURN THE RANK OF TCELL（L）
```



```
2 RANK 5 － 1
```





```
10 rank＝－1
RETURN
subroutine copyil
SOMMON／IST／ICELL（511），ACELL（511），BCELL（511），KCELL（511），TPI，TP」） CPI：GPJ，INDEX
LH．MH．NH
INTEGER RL，DA，FA，DF，FR
INTEGER GIVE COPY WFF－L AND RETURN ADDRESS OF dUPLICATED LIST IN L
```



```
5 LAST＝0
```




``` LAST＝J \(5 \quad 1=R L(1)\)
IF（KCELL（I）．GT．IND）PRINT 55 ，I．KCELL（I），IND
455 FORMATLSX，＊KCLL \(1 *, 13, *)=* 15, * G T\) IND \(=*, 151\)
```



```
\(\mathrm{G}=\mathrm{GCV}\) TO
5
A．ICELL（LAST）＝ICELLILAST：．4．777 000777 \＆RETURN
RELEASELEASE
IF（IH．EQ．O） 60 Tosoal
palnt ra：L
```



```
080 CONTINUE
```




```
END
COMMON／LST／LELL（511），ACFLL（511），BCELL（511），KCELL（511），TP1，TPJ \(\times\) CPD \(\because \mathrm{BPJTINDE}\)
EEx Left－LINK
temporary debugging msg to be removed
```


## 

 ENDINTEGER FUNCTION RL（L） COMMON（5T／ICEL（511），ACELL（51），BCELL（511），KCELL（511）．，TPI；TPJ，
XGPI，BPJPINDEX GEING MSG TO BE REMOVED
TEPI，BPJP INDEX
IFIL．EQARY DEBUGGING MSG TO
O $\qquad$
RL＝LSH
RETURN
ENDEGER FUNCTION OF（L）
XGR1，8P ST／ICELL（511），ACELL（511），日CELL（511），KCELL（511），TPI，TPJ
DF RETURNS THE DATA AND FLAG FIELDS
RETURN
indeger function dafli
COMMON／LST／ICELL（511），ACELL（511），BCELL（511），KCELL（511），TPI，PPJ，
RETURNS DATA FIELD OF ICELL－L
DAELSNFTICELL（L），－18）．．．．．7日
eturn
END INEGER FUNCTION FBRL：
COMMON／LST／ICELL（511），ACELL（511），BCELL（511），KCELL（511），TPI，TPJ，

FB＝LSHFT（ICELL（L），－24），A． 3
RETURN
END
INTEGER FUNCTION FR（L）
COMMON／LST／ICELL（S1），ACELL（511），BCELL（511），KCELL（511），TPI，TP J．
X BPI ， BP J ．INEEX
remove front cell of list－l and return ney header adoress

RETURN

COMMON／LST／ICELL（511），ACELL
XBPIBPJ•INDEX
INTEGER RL，UA，FB，DF，FR
RETURN THE LCM INOT O OR ，OF THE POWERS OF EXP－I AND EXP－J
RETURN THE LCM INOT O OR 11 OF
IF NONE RELEVANT RETURN 1000
NPMR $=1000 \quad \underset{\$}{\$=1}$
a ${ }^{\mathrm{N} P \mathrm{~K}=\mathrm{L}}$

C $\stackrel{+}{\text { CaLL }}$ ROP $\stackrel{+}{(K, K K)}$


10 IF R（L．NE JIGO TO 11
11 $1=$ 」

IF（KK．NE．211日）©A．（KK．NE． $214 B$ ）GOTO 30



CALL ROP (KQKJ) $\mathrm{KK}=\mathrm{DF}(\mathrm{K} J)$
$K K=A C E L(K)$ $K K=A C E L(K J)$
IF ( $K$ K. EQ.
35 CALL WFF(K:KJ,KK)
IF (KJ.EQ.01G0 TO 10
C KJ IS ADORESS OF NEXT WFF
END
function xval(i)
COMMON/LST/ICELL (511), ACELL(511), BCELL (511), KCELL(511), TPI,TPJ,
COMMON/POLE/IMP(100),ISTK(20),STK(20), RTK(20),IJ,IK,I1,I2.LAST:LNK COMMON/XV/T(6),V(32),La(1) $)$.jFG(12),D(36),R(36 COMMON/F/IH, JH,KH,LL,MH
INTEER RL,DA,FA,DF,FR




12 STK (12) ) ACELL (K)

```
4 IFK.EG.I)GOTO 16 $ K=LL(K) S IFIK.NE.OIGOTO 5
OEHUGGER (Iz.EQ.z)GO TO \0
    MFINT 15;I2 S SAL RETURN,
    lal
    G0TO(21,21,21,21,?1,21,23,24,25,26,27,28,29,29),11
    21 GOTO(21,21,21,21,?1,21,23.24,
    23 STK(12-2)=5TK(I2-2)+5TK(12-1) s go то 31
    24-5TK(Lく-2)=STK(I2-3)-STK(IZ-2) & Go to 31
    25 STk(I2-1)=-STK(I2-1) , G0 то 14
    26 S゙TK(IZ-2)=STK(I2-?)05TK(1>-1) $ G0 T0 31
    27 STK(IR-2)=STK(I2-)
    2H STK(IZ-1)=1/STK(I2-1) & GO TO 14
    29 XVAL=STK(I2-1) & IF(XVAL.LT00)GOTO 32 s XVAL=XVAL**STK(12-2)
    31 12=12-1.14)XVAL=1/XVAL S STK(I2-2)=XVAL
    3) 
    lim(J.NE.(2*(J/Z)\)XVAL=-XVAL
```

END
subroutide settili

COMMON/F/IH
IF (IHREG.0)GOTOB080
77 FORMAT (1OX, *SETT CALLED, ARG=*,I4)
continue



RETURN $\$$ ENT
FUNCTION KFIG(I)
INTEGER RL DAA,FB,DF;FR
GIVE CONFIGURATION OF WFF-I
KFIG=0 $\mathbf{S}$ J $J=I$
IFII.EQ.0)RETURN


SUBROUTINE WFF(I,J,K)
C NOTE $\quad$ INEGER SLR WAFF NOW, TAKES 3 arguments .. there are wrong calls to INTEGER RANK
c LJNOV MOD. K IS RIGHT END OF WFF
GEGINNING OF THE NEXT WFF IN J - 2 ERO IF NONE


FUNCTION ATRG:(L,Z)
C RET. MAX INCONSIS VAL FOR TRG-FN-L WITH ARGUMENT $Z$
CCCCCCCC THIS FUNCTION EXISTS - BUT IS NOT EXPECTED TO BE USED CCCCCC


RETURN
END
SUBROUTINE RTP (M)

 THNEREORE MADE A EUMPEC
THETURN
END
subroutine distribil.n)
COMMON,LST/ICELL(511), ACELL(511), BCELL(511), KCELL(511), TPI,TPJ.

COMMOV/F/IH.JH,KH,LH,MH:NH
ategrr Give
c
GOTOT1，9，20，30），N
CALL DLELETE（L）
IX＝DF（I）\＆IF（IX，NE，？ПTB）GOTO 4 ．．．．（\＃17）．．．
ICELL（I） $\mathrm{ICELL}(T) \cdot 1000000$

C REMOVE ${ }^{2}$ IF PRECEDING $15 T$ COMPONENT－ELSE APPEND ONE
IXEGIVE（X）${ }^{\$}$ ICELL（IX）＝211000000 $S$ ACELL（IX）＝－ACELL（I） RETURN RISTRIBUTE \＆OVER＊＊＊．．．．IN CONTEXT OF









DISTRIBUTE＜OVER BES IN CONTEXT：\＆＊＊＊．．．

END
SUBROUTINE VAL（T．J．K．x．y）
SUBROUTINE VAL（IPJ•K，X，Y）
COMMON／LST／ICELL（511），ACFLL\｛511），BCELL（511），KCELL（511），TPI，TPJ，

COMMON／F／IN．JH，KH，TH，MH，NH OF EXP－I（Ix1 OR 2）UNOER SUEMATCH－J
IN X（MAX CONSISTENCY）AND Y（ALG－CONSISTENCY）
IF（J．NE．01GOTOL
$t+1-509$
$x=r=0$
00
5
$005 \mathrm{~L}=10 \mathrm{~K}$

 $\underset{x=x \rightarrow A C E L L}{ }$
NEGATION

CONTINLE \＆

22：CONTINUE



$\mathrm{Z}=\mathrm{AC}\left(\mathrm{N}_{1}\right) \quad \mathrm{Z}=\mathrm{BC}(\mathrm{N} 1)$
$Z=8 C(N)$
$Y=Y B C$
$Y=Y(N)$
 Y $=$ YC（N1）

IF（KH．EQ．0）GOTO 222


$22 z$ CONTINUE
sugroutine small（II．MM）
COMMON／LST／ICELL（511），ACELL（511）。日CELL（511），KCELL（511），TPI。TPJ。
COMMON／NOV／K5（25），JA（2，10），NSCH（2，3），M（2），JP（2），KPI ，KP
COMHON NX，JPAK，MONO，ISCH．ERR
COMMON／F／IH．JH：KH，LH：MH：NH
INTEGER RL，OA，FB，OF，FR
ANALYSE STEP－II IN KS＝TA日LE－RESOLVING INTO SUaSTEPS IF pOSSIbLE
ELSE OETERMINE STEP SIZE IF UNESOVABLE
RETURN MMM NONZERO IF UNRESOLVED AND LARGE，ZERO OTHERWISE
initialise
$\mathrm{I}=\mathrm{KS}$（I





TRIVIAL POWERS



$c \quad$ REMOVE LEADING OPERATOR PAIR


22＝nF（I21）

c INTERCMANGE（Mi（2））－1 HITH（M（z））－NO YORRY RE NEH（M（Z）I




c REMOVE＜PAIR




TF(I21.NE.211R) so To 28
I21=RL(M(2)) \$ I2Z=DF(I21


I21=111 \& I22=112 1
....(\#19)....

I21=RL(Mi2) $\$$ I $122=D F(121)$


(2) GOTO 30

IF(I12.NE. 211 R) GOTO 30 ISP I22=M(1) \& Gото 27
$30 \mathrm{IFLAG}=0 \quad$ \& CALL TYPE $(M(1), 111)$ \& CALL TYPE(M(2), 122)
GRTO $140,41,42,43,44,45,45,47,48,49,50,51,52,53,54,55,56), 122$
35 stop 5




44 GOTOI $75,77,60,70,60,70,75,77,80,80,88,88,84,84,84,84,881,11$

46 दै

48 GОТО (80, 80, $80,80,80,80,80,80,80,80,80,80,90,90,90,90,80), 111$



52 соТО (А4, $84,84,84$, R4, $84,84,84,90,90,84,84,84,84,84,84,84), 111$

54 (\%)
55 OTHER


$6 \prime$ ASSIGIV G2 TO JHACK
61 CaLL PWR(M(1).II1)

CALL MANTISA(M(1))
IJl=M:
\&

c ERROR

66
IF(ABS(ACELLIII)-ACELL(I22)).LT.10E-8) ©OTO 69
 goto
$A=-\mathrm{B}$
70 ASSIGN 71 TO JBACK 71 NTT=NT+1


C $A=1 / B \quad O R \quad A=-1 / B \quad A C E L L(122)$.GT.10E-8) 63,67


C 77 ASSIGN 78 TO JBACK $\quad$, 601061








TRY (E)-SUBMATCH
84 IF IN12.EQ.010TO 85

CALL NCOMP ( $A(2), 212 \mathrm{~B}, 111)$
 PRINT 99
99 FORMAT (15X.\#....... RETURNED FROM S/R SGMATCH ...*)
909 CONTINUE 909 CONTINUE

c TEST SIZE OF CURRENT STEP IF IT WAS NOT RESOLVABLE

** ABOVE CARD REDUNORNT ANO SILLY
IF(M) 2 . ER.0)GOTO 890





C $x$ - LSHFT(N11,18) - LSHFT(N12,24) - LSHFT(N21,30) LSHFT(N22.36)
subroutine sbmatch(fzajz)
SUGROUTINE SBMATCH(51), ACELL(511), BCELL(511), KCELL(511), TPI,TPJ,
XAP $1, B P J$, INOEX COMMON/NOV/KS(25), Ja(2,1n)
COMMOIt NK, JPA PMORO ISCH. ERR
COMMON/F/IHOUHOKH,LH,FHH.NH
COMMON/F/IH•JH,FH,LH, MR
$\mathrm{JZ}=0$
RESOLUTION INTO COMPONENTS SECTION

| $\mathrm{K}=1$ |
| :--- |
| ADITIVE S |
| IFIIZ.NE.01GOTO 10 |

2 IFIM(K).NE. 0160 TO 302
$J P(K)=J A(K, 1)=0$

ONLY 1 CUMPONENT


CALL DISTRIE (M(K):1)

7 CALL RESOLVE(M(K), 2D7B,K)

- IF (K.EQ. 2) GOTO 25 ,
c MULTIPLICATIVE COMPNNENTS
$10 \mathrm{IF}(M(K)$. NE. O1GOTO 3 O 3
1JP(K) $=J A(K, 1)=0$ Gо то 18

IF (III.EQ.2118)GOTO 22
IFIIT NE,214B)GOTO 14


12 CALL DISTRIH (M(K), 4) 13 IF(IZ.EQ.212B)GOTO


c DISTRIBUTE \& IN CONTEKT <-E*世...


17 CALL HESOLVE (III, PIPH.K)





 CALL UISTRIG(M(K), 2
c EXit FKom resolutiom section

HO1 $=\mathrm{NOZ}=0$


- of chuse of in handing of implicit steps = some cleaning
because of change in hannl
up of old codes in order


30 IF ((11.GE.N1):A. (I2.GE.NZ) 60 TO 32
IF(NF $1, N E, 0)$ CALL RJA (NF1,I1,N1)

NSCH $(1,1)=0$
IF(II.GT.N1) GOTO 430
MI NCM(N1)I1) 5 GO TO 431


32 IF (JZ.EQ.O)RETURN





K
$\mathrm{LM} 2=1 \quad \$ \quad \times 2=Y 2=3000$
IFX
IS
FLAG SET FOR ALG SUBSTEP
C ${ }_{435} \mathrm{IFXX}_{\mathrm{IF}=0}$ IS A FAG SET FOR ALG SUBSTEP
$35 \quad 1 F X=0$
$050 \quad I=1, L M 1$
IF (N1.LT.II) GOTO4.36

436
CONTINUE
DO $200 ~$
$J=1, L M Z$

CALL G(N2,2,I2) $\begin{aligned} & \text { CALL } \\ & \text { VAL( } 2, I 2, I 2, \times 2 . Y 2) ~\end{aligned}$
c (*) OR (*) SUBMATCH
c IF(IZ.NE.0) GO TO $1+0$
$(+)=5 /$ MATCH ATTEMPT


c IS IT $\begin{gathered}\text { algenraic } \\ \text { NTENT\&1 }\end{gathered}$

```
    IF(ABS(Y1-YZ).GT.ERRIGO TO 60
    IF=5 $ GO TO 60
        40 IF(ABS(ABS(X1)-ABS(X2)).GT.ERR)GO TO 150
```



```
        NFL=1 NT=NT +1
    IF(ABS(AGS(Y))-ABS(YZ)).GT.ERR160.38
    c
    T=NT*1
    G IF(ABS(XZ).GT,ERR)GO TO POO
        CALL THV(2.12,I11)
        NZ=5 S CALL ONEIIZ;NK
        JZ=5 S S=NT+1 OLL ONE(IZ,NK)
    C IMPLICIT ALGEPRAIC
        IF(I2.LT.NZIGOTO 105 s n2=0 & G0 T0 20
    105 I11=1
        IP=NSCH(2,I11) $ IP=JA(Z,IP),A.7T7B
```




```
    IMPLICIT T-MATCH
    KS(KP2)=M(2)*LSHFT(NX.9)
    \122 KP2=KPZ+1 $ NZ=0, $ GO TO 28
        IF(ABS(ACELL(IP)+1).LT.ERR)CALL TAGON(IP,0)
    KPZ=KP2+1 S*STMX:9)
    150 IF(NOZ.GE.IZ1GO TO 200
        IF(AGS(AGS(X2)-1).GT.ERRIgo to 200
        IF(ABS(AHS(x2)-1).GT.
        CALL TR(2,I2,111)
        NFZ=5
    IF(ABS(AUS(YZ)-1).GT.ERR)120,101
    O0 CONTINUE
        IF(NO2.GE:IN)GOTO 250
        IF(ABS(XI).GT.ERR)GOTO 250
        IF(ABS(X)),GT,
        CALLTHV(1,I1,I11)
        NFI=1
        JZ=10 NT=NT+1, CAL ONE(IZ,NX)
    IMPLICIT ALGEERAIC
```


IP $=N S C H(1,11) \quad \$ \quad 1 P=J A(1, I P), A, 777 B$
$C A L L$
DETAC





$K S(K P 2)=1 P+L S M F T(N X X G)$
$K P Z=K P 2+1$
GO TO 210
IF(ABS (ABS (X1)-1).GT.ERR)GO TO 250
CALL TRV(1,I1,I11)
IF(IIINE, 0 ) GO TO 250

IF (ABS (ABSTY1)-1).GT.ERR1220,201

60 TO 27
PRINT $56, A C E L L(I 11), ~ A C E L L(I 12) ~$
55 PRINT 56, ACELL(II1), ACELL(I12) S STOP


 CALL WELD (2,IZ,IZ,I12)
s $M(1)=0$

- IF(ABS (ACELL (I11)*ACELL(I12)).LT.ERR)CALL TAGON(I11,0)

64
$\begin{gathered}\mathrm{N} 2=0 \\ \text { CALL } W E L O(1, I Z=M(2) \\ \text { S }\end{gathered} \quad M(2)=0$
$\mathrm{N} 1=\mathrm{N} 1-\mathrm{Il}$
GO TO
81

 CUNPENSATE SIGN IF (ABS (ACELL(II), ACELL(T12)).LT.ERR)CALL TAGON(III,0)





 IF(ABS(ACELL(I11)*ACFLL(T)Z)).LT.ERR)CALL TAGON(M:1),0)



```
    71 IF (NX. NE,NY)GOTO 72 T12
```



```
    : 0 e** make sure all refs to pointer in \(J A(-,-)\) are masked
    \(72 \mathrm{IP}=\mathrm{NSCH}(111, \mathrm{I} 12) \quad \& \quad \mathrm{IP}=\mathrm{JA}(\mathrm{I} 11, I \mathrm{P})\). A .777 B
```




```
    80 CALL RELEASE GM(1) GOTO \({ }^{71}\)
        Call release(m(2))
    return
\(\stackrel{\rightharpoonup}{c}\)
end
COMMON/LST/ICELL(511),ACELL(511),BCELL(511), KCELL(511),TPI,TPJ,
    COMMON/LST/ICE
    COMMON/NOV/KS(25),JA(2,1n),NSCH(2,3),M(2),JP(2),KP1,KP2
COMMON/F/IH
    INTEGER RL,DA,FB,DF,FR
C RESOLVE EXPRESSION- \(K\) ( \(K=1\) OR 2) BEGINNING AT I INTO ( + )-COMPS
```



```
    IFIIN-EQ.01G0T0 606
    17 FORMAT (12X: SSAR RESOLVE, ARGSE**319
    sos continue
```




```
\(c\)
TO BE REMOVED
IFII.EQ.01STOP 424
```



```
    IF(ID.EREJIGOTO 15
IF ID NE.J NEGATE FLAG ENTRY
    IF ID, NE.J NEGATE FLAG ENTR
JA (K,IP)=JAK,IP)
15 IF(IN.EQUMMGOTO 20
    IN=IN+1 \(\$ \quad\) IL=iL(IL)
    20 CLEAN UP
c CALLING SEquENCE: NCOMD\{I,J.K\}
```



```
25 \begin{tabular}{l}
\(\mathrm{K}=1\) \\
\(\mathrm{I}=\mathrm{I}=\mathrm{UF}(\mathrm{IN}) \quad \mathrm{IN})\) \\
\hline
\end{tabular}
```



```
    IFIII.EQ.211日)GOTO 27
    26 RETURN
```



```
    28 IN=RLIIN) S GOTO 25
```



```
CALL RELEASE(MIT11))
make sure all refs to pointer in jaro,n) are masked
72 IP \(=\) NSCH (II1,II2) \({ }^{5}\) IP \(=J A(I I 1, I P)\) A. \(777 B\)
```



```
\(80 \mathrm{CALL}^{\text {CALLELEASECM(1) }}{ }^{\text {GOTO }}{ }^{71}\) \$ Call release(m(2)
there is still case of ..fl*Fr*f3...* 0 to consider
END
COMMON/LST/ICELL(511),ACELL(511), BCELL(511), KCELL(511),TPI,TPJ.
XEPIMPJ, NDEX
COMMON/NOV/KS (25),JA(2,1n),NSCH(2,3),M(2),JP(2),KP1,KP2
INTEGER RL,DA,FB,DF,FR
```



``` IF (IN.EQ.0)GOTO 606
17 FORMAT (11
606 CONTINUE
```



```
\(\begin{aligned} & 10 \mathrm{IP}=1 \\ & 12 \mathrm{I}=\mathrm{PL}(\mathrm{II}) \\ & \mathrm{S}\end{aligned} \quad \mathrm{JA}(\mathrm{K}, \mathrm{IP})=11\)

```

IF IENE,J NEGATE FLAG ENTRY
$15 \begin{aligned} & \mathrm{JA}(\mathrm{K}, \mathrm{IP})=\mathrm{JA}(\mathrm{K}, \mathrm{IP})+10000 \mathrm{IF} \\ & \text { INO.EQ.IM GOTO } 20\end{aligned}$
CLEAN UP \$ ILJLL(IL) \$ GO TO 12
$20 \underset{\text { RETURN }}{\text { JP }}$
CALLING SEQuENCE: NCOMD\{I,J,K)

```

```

IF (Il-EQ.211日)G0T0 28
28 IN=RLIIN) S GOTO 25

```

UPDATE JA-TABLE FOLLOWING SUBSTEP DETACHMENT
I \(\quad 1\) OR \(2, J=11\) OR I2 ANO \(K=N 1\) OR N2
\(K K=K+J\)
DO 60 IN \(=1,1\)
IM \(=\) NSCH(I,IN)
CONTINUE
\(60 \underset{\substack{\text { CONTIN } \\ \text { IM } \\ 0}}{ }\)


to continue
RETURN
c RETURN \(k\) NONZERO IF IMPLICIT MATCH IS WITH SELF - I.E 0 vs o


 IF 1 DF
ENO
SUBRO
SUBROUTINE TIME ( X , TM)
DIMENSION LT (4) \(\mathrm{CLS}(\) ( )
CALL LTIME
C WE NEED LT(4) EVEN THO WE USE ONLY 1 ST TMO BECAUSE LTIME EXPECTS IT IF (X.EQ.0) GOTO 2 (2) PRINT 50.LS(1):LS(2),LT(1):LT(2),TM

\(2^{\text {XTIME } L S(1)=L T(1)}\) S \(\operatorname{LS}(2)=L T(2)\) S RETURN S END
subroutine detachil,J)
COMMON/LST/ICELL (511), ACELL(511), BCELL(511),KCELL(511),TPI,TPJ,

XAPI,BPJ,INDE
COMMON/F/IH
INTEGER RL, DA,FB, DF,FR
DETACH WFF-I FROM FORMULA-J FREE WFF-1


5 WFF-I IS FZ
\(10 \mathrm{KCELL}(J L)=K C E L L(J L) \cdot 1\)

11 CALL DELETE (JL)

15 IF (KLELL (L)-IND) 12 © 18 ( 16
\(16 \mathrm{CALL} R \mathrm{ROP}(\mathrm{L}, \mathrm{IG})\)
\(1 \mathrm{~L} \quad \mathrm{~L}=\mathrm{DF}(\mathrm{L})-206 \mathrm{~B}\)

20 ACELL (L) \(\mathrm{GOCACELL}(\mathrm{JL})+\mathrm{ACELL}(16)\)
21 ACELL(L) \(=A C E L L\) (JL)-ACELL (IG) s OCELLIL)


23 ACELL(L)=ACELL(JL)*ACELL(IG) s BCELL(L)=ACELL(JL)*BCELL(IG
\(24 \triangle\) GUTO \(\mathrm{ACELL}(\mathrm{L})=\)
GOTO 12 =.CELL(JL)/ACELL(IG)
5 BCELL(L)=BCELL(JL)/BCELL(IG
aCELL(L) \(=1 /\) ACELL (JL)
s BCELL(L)=1/BCELL(JL)
c 30 NEITERE



.
IF(LI.NE.2118)GOTO 42
1 CALL DELETE (L) GOTO 11
C \(42 \mathrm{ICELL}(\mathrm{JL})=\mathrm{ICELL}(\mathrm{JL})+1000000 \mathrm{~B}\)
ACELL(JL)=-ACELL(L) 5 BCELL(JL)=-BCELL (L
3 GOTOLI2. 213 IFISTOP 42
IF(LI-EO.214B)GO TO 4
C CONVERT; TP <
 ACETO 12
END
FUNCTION NCM(N,M)
COMMON/F/IH
RETURN N-COMBINATION
NR=N+1 \({ }^{2} \quad N U M=1\) NDEN \(=\)

10 CONTINUE
REMOVE DEBUGGING PRINT
NCM=NUM/NDEN
IFIIN.EQ.01GOTO 505
505 CONTINUE

subroctine gingt, j)
COMMON/NOV/KS (25),JA (2,1n),NSCH(2,3),M(2),JP(2),KP1,KP2
COMMON/F/IH COMGINATION TF J-WRT-N
- if This is a lst call - initialise to 15 t value

(N1) \(\quad\) K \(k=1, J\)
\(N S C H(1, K)=k\)
- cuntinue
- RE TURN

10 IF (NSCH15,J):LT:N11:12
heturn
\(12 \times=1\)
IFIJ.GT. HGUTO 13


NSCH (1.J-K) \(=\) NSCH \((1) J-K=1\) TO

subroutine tagonitik
COMMON/LST/ICELL(511), ACELL(511),BCELL(511), KCELL(511), TP1,TPJ. XBPI, BPJ, INDEX
COMMON/F/IH, JH,KH,LH,MH,NH
C TAG ON A OIVE OR A TO THE FRONT OF EXP-I DEPENDING ON HHETHER K=

ICELL(J) \(=211000000\) - LSMFT (IIO9)

\(10 \mathrm{~J}=\) GIVE (X) \(\$\) ICELL ( \(J\) ) \(=2140000008+\) LSHFT (I, 9 )

RETURN
FNTRY RWFF
c PREMOVE WFF-I AND RETURN ITS LL IN K
CALL WFF(I,J\&K)
ICELL(K) \(=\) ICELL (K).A. 77700 O777
\(\mathrm{K}=\mathrm{LLL}(\mathrm{I})\)
\(\mathrm{ICELL}(\mathrm{I})=\mathrm{ICELL}(I), A .7777770000\)
PATCH-UP GAP
IF(K.EG.0)GO
ICELL(K) 1 (ICELL(K).A. 777 (J00 7778).O.LSHFT(J.9
11
IF (J.EQ.0)GOTO ZO
ICELL(J)=1ICELL (J). A. 777 777 000日).0
20 CONTINUE
RETURN
ENTRY ON
ENTRY ONE
RETURN A -LIST OR 1-LIST DEPENDING ON I ( 0 OR 1) AND RETURN
\({ }_{c}^{C}\) RETURN A 3-LIST OR 1-LIST DEPENDING ON I (0 OR I) AND RETURN
 RETUR
ENO
END
subroutine deletell)
COMMON/LST/ICELL(511), ACELL(511), BCELL(511), KCELL(51), TPI,TPJ.
XGP ITGPJ.INDEX
NTEGER RL, DA.FB,DF.FR


5 ICELL(IL) \(\operatorname{IFIICELL}\) (I)
5 IF (IR.EQ.O)RETUFN
RETLRN S ERD
SUBROUTINE INSET (L.M)
SOMMONTLSE INSERT(L,M)
insert quad-L betwefn guad -(M-1) and ouad-M


ICELL (IL)
ICELL \((M)=(I C E L L\)
(M).AL:.777777000B).O.L
RE TURN
ENTRY LINK
COLN LIST-H TO THE RIGHT OF LIST-L
CALL WF (L.IL,IK)

ICELL（IX）\(=(I C E L L(I X)=A, 7770007778) \cdot 0 . \operatorname{LSHFT}(M, 9)\)
\(\operatorname{ICELL}(M)=(\operatorname{ICELL}(M) \cdot A \cdot 7777770008) \cdot 0 R \cdot\) IX
RELTRN
EITRY ADON

subroutine mantisafl）．．．．（\＃29）．．．．
\(c\)
\(c\)
TAAN＠くAMM SAAN ETC AND SET L＝ADOR．O NEM LIST
1 \begin{tabular}{l}
\(\mathrm{I}=\mathrm{OF}(\mathrm{L})\) \\
\hline
\end{tabular}


3 FORMAT।
5 CALL UELETE（L）

L＝RL（L）\＄RETURN \＄END
SUBROUTINE ROP（1，J）
COMMON／ST／ICELL（51），ACELL（511），日CELL（511），KCELL（511），TPI？TPJ，
XBPI』BPJ，INOEX
COMMON／F／IH，JH，KH，LH，MH，NH
TNTEGER RL，UA，FB，DF，FR
INTEGER RLOUA，F日，DF，FR
LOCATE RIGHT OPERAND OF OPERATOR ICELL－I AND RETURN IT IN \(J\)
\(\mathrm{J}_{\mathrm{J}=1} \mathrm{~F} \quad \mathrm{I}=\mathrm{K}\) CELL（J）
\(J=R L\{J)\)
IF（KCELL（J）．EQ．IU）RETURN
GO TO
ENO
suaroutine welo（II，Iz，IG，Ja）
COMMON／LST／ICELL（511），ACELL（511），BCELL（511），KCELL（51），TPI•TPJ，
COMMON／NOV／KS（25），JA（2，11），NSCH（2，3）•M（2），JP（2），KP1，KPP
COMMON／F／IH，JH，KH，LH，MH，NH
INTEGER GIVE，RANK
CREATE EKP FROM COMPONENTS AND DO HOUSEKEEPING
\(I I=1\) OR 2 ． 10 IS \(I 1\) OR 12 ．JQ RETURNED WITH ADDRESS OF NEW EXPR．

CALL DETACH（NQ：M（II）
（•）－COMPS
－TAG ONA：



JGIVE（A）\(\quad\) IF（11．A． 1000
CELLL
HCELL \()=A C E L L(J Q)+A C E L L(K O)\)



＝ 1
（＊）－Cumps

20 IF（II．A．100nO日）．ER．OIGO TO 25
CALLTAGON（JU，1）
25 IFIKK．EO．IO）GOTO 40


\(\triangle \operatorname{ACELL}(J)=A C E L L(J Q) * A C E L L(K Q)\)
\(\triangle A C E L L(J)=A C E L L(J Q) * A C E L L(K Q)\)
\(R C E L L(J)=B C E L(J Q) * B C E L L(K Q)\)
ICELL（J） \(2212000000 \mathrm{~B}^{2} \$\) GO TO 3
BCELL（J）＝BCELL（JQ）／RCELL（KQ）
ICELL（J）\(=213000000 \mathrm{~B}\)
c
CALL ADON（JQ，J）\＆ 60 TO 25
40 RESET INDICES
40 CALL WFF（JQu，
KCELL
41 KK \(1=-1\)
 KCELL（KK）＝KCELL（J）－RANK（KK）
\(4 \begin{aligned} & \text { GOTO } \\ & 4 . \\ & \text { CONTINUE }\end{aligned}\)
44 CONTINU
－ENO
SUHROUTINE TYPE（I，J）
COMMON／LST／ICELL（511），ACELL（511），BCELL（511），KCELL（511），TPI，TPJ． X CPI I，BPJ．INDEX
c RETURN THE TYPE NO OF EXP－I IN J
FOR NON－EXISTANT EXPRESSIO
COMMON／F／IH，JHOKH，LHOMHONH
LOOK AT 1 ST LEADING OPERATOR（IF ANY






IF（II，NE． 2148 ）GO TO 2



\(11 \begin{aligned} & J=15 \text { S RETURN } \\ & \text { IFII．NE．21581GO TO } 12\end{aligned}\)

＊＊＊＊＊＊









** NOTE: ABOVE 50 OR SO CARD VERY ERROR-phone cause im sleepy
c J=8 s RETURN
\({ }_{c}^{c}\) it is assumed that \(\rightarrow\) precedes \& hatre they occur together
c return in \(\lrcorner\) the exponent of the leading \(+O R+0\) EXP-I
RETURN
\(11=1\)
\(j=D F(I)\)








- \((T A N+S E C) /(T A N+5 E C-C O S)=(S I N / C O S+1 / C O S) /(S I N / C O S * 1 / C O S-C O S)=(S I N+1) /(S I N+5 I N+2\)


( \((1)+T A N-S E C) /(S E C * T A N-1)) /(1+S E C-T A N) /(S E C * T A N+1)=(11 * T A N-S E C) *(S E C+T A N * 1) /\) (SEC*TAN-1) \((1+\) SEC-TAN \()=(11+\) TAN \()+2-S E C+2) /(S E C+2-(T A N-1)+2)=(1+2\) TAN*TAN+
 (1+SIN)* \((1+\operatorname{Cos})\) )






< CSC/(COT+TAN) \(=(1 /\) SIN \() /(\operatorname{COS} / S I N+S I N / C O S)=\)
\((S E C-T A N) /(S E C+T A: H)=(S E C-T A N /-(S E C-T A N) /(S E C+T A N)=(S E C-T A N)=(S E C+2-Z * S E C *\)




 5) \(=(1 * 2 * \sin * \cos -1) /(5 \sin * \cos )=z>\)

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[^0]:    * Here we take a problem to be one whose solution yields an 'answer' in contrast to a proposition or a theorem whose truth has to be demonstrated in a proof and yields no 'answer'.

[^1]:    * As an indication of this, the system took more than two years to develop. In terms of card volume, the software, including the compiler for ALFIE, ocoupies about 25,000 cards.

[^2]:    *Depressing the index key positions the typewriter carriage on the same column on the next line.

[^3]:    * The field axioms are the ring axioms (see Appendix B) together with the two additional axioms :
    (9) If $c \neq 0$ and $0 \cdot a=c \cdot b$ then $a=b$ (cancelてation)
    (10) $\vee a \in R, ~ a \neq 0, \exists a^{-1} \varepsilon R$ such that $a^{-1} \cdot a=1$ (multiplicative inverse)
    $R$ is then a field, if these axioms hold.

[^4]:    * I am grateful to Dr. J.G. Sanderson for bringing this application to my attention.

[^5]:    * A rational function is one which is expressible as the ratio of two polynomial functions.
    ** Since our trigonometric expressions do not have variables, $x_{1}, x_{2}$, $\ldots x_{6}$ would be sufficient actually.

[^6]:    * An algebraic manifold is the solution set of a system of polynomial equations. See Appendix $B$ 。

[^7]:    * This means whenever $f^{\circ}(\underset{\sim}{X})$ and $g^{\circ}(\underset{\sim}{X})$ are well-defined, they are equal. We shall abbreviate this qualifying clause to pwd (provided weZZ-defined).

[^8]:    *See definition of permitted variants in Chapter $V$.

[^9]:    * i.e. provided $f^{\circ}(\underset{\sim}{X})$ and $g^{\circ}(\underset{\sim}{X})$ are both well-defined. In this section we shall take such qualifications as understood to avoid the frequent need to specify them by 'pwd' etc.
    ** The equation defined by a permitted variant of I1, in its X-form, is of this form. For $\cos \theta-1 / \sin \theta \rightarrow 0, g^{\circ}$ is $X_{1}$ and for $\sin \theta 1 / \csc \theta$, it is $X_{4}$.

[^10]:    * Finite if we discount the trivially distinct expressions derived by the redundant or repeated use of parentheses, identity elements 0 and 1, and the unary + and - as in: $f,(f),((f)),((f)), \ldots .0$, $+(f),+(+(f)), \ldots, f^{*} 1, f^{*} 1 * 1, f^{*} 1 * 1+0, \ldots,-(-f+0-0+0), \ldots$.

[^11]:    * Here we include the supplementary single C-sets $\{J 1\},\{J 2\},\{J 3\}$ cand $\{J 4\}$.
    ** $\Phi^{\prime}$ is the set of mules $\Phi$ with rationalisation included. Rationalisation refers to operations like $a+b / c \rightarrow\left(a^{*} c+b\right) / c$ and $a / b+c / d \rightarrow\left(a^{*} d+b^{*} c\right) /(b * d)$.

[^12]:    * A step is sparse with respect to its C-set if there is a function in the $C$-set absent in the step, e.g. $\csc \theta /(\cot \theta+\tan \theta) \rightarrow \cos \theta$ does not contain the function sec $\theta$, which occurs in its $C$-set $\{I 2, I 3, I 7, I 8\}$.

[^13]:    * Proof: Suppose $g_{l}^{\prime} \equiv k g_{l}$ and $g^{\prime}{ }^{\prime} \equiv k g_{r}$ thus satisfying:
     $f^{*} g^{n}: f^{*} g_{r}^{n}$ where $f^{2} \equiv k^{n * f}$. (4) is a special case of (5) in which $n=1$.

[^14]:    * Proof: Suppose $g^{\prime}{ }_{l}-g^{\prime} r \equiv g_{l}-g_{p}$. Then $f \pm n g^{\prime} l: f \pm n g^{\prime} r$ is aiso of the form $f \pm n g_{\ell}: \tilde{f}^{\prime} \pm n g_{r}$ where $\widetilde{f} \equiv f \pm n\left(g_{\ell}^{\prime} g_{l}\right) \equiv$
    $f \pm n\left(g^{\prime}{ }_{r} \dot{-} g_{r}\right)$. $n=1$ gives the case (6).

[^15]:    * The hybrid C-subsets of $\{I 1, I 3, I 8\}$ are $\{I 1, I 8\}$ and $\{I 3, I 8\}$, but they
    imply functions not indicated by the configuration 101100; e.g. $\{11$, I8\} would imply the presence of $\cot \theta$.

[^16]:    * One configuration is said to be denser than another if it has more '1' bits.

[^17]:    *     + and - have equal hierarchy as have * and /, but the latter pair are of a higher hierarchy thon the former.

[^18]:    * An index, being normally a small integer, should be packable into the spare bits of IC. However in Super-2, the indices are negative because we used an earlier definition of index in which ' $I(i)=$ I(i+1)+R(ei)' (see D.11).

[^19]:    ＊$M(r)$ is the set of zeroes of $r$ in $\mathbb{C}^{n}$ ，i．e．$\left\{\underset{\sim}{X} \in \mathbb{C}^{n} \mid r(X)=0\right\}$ ．

