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**PROGRESS AND NEW  
TECHNIQUES IN  
BUFFET ALLEVIATION**



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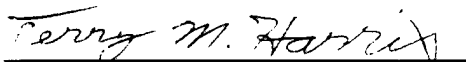
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## FOREWORD

This technical memorandum documents the activities of the Unsteady Aerodynamics Integrated Product Team (UAIPT). Dr. Wladimiro Calarese, Chairman of the UAIPT from September 1993 until his retirement in January 1997, and Elijah Turner, a member of the UAIPT from October 1994 to the present, prepared this memorandum based on the work of the UAIPT. The study reported herein was conducted under work unit 24044951.

The support of all of the members of the UAIPT, SARL wind tunnel personnel, and other Flight Dynamics Directorate personnel is gratefully acknowledged. Bob Weyer (ASC/ENFT) performed the Euler simulations while working in WL/FIMC.

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## I INTRODUCTION

The problem of buffet excitation on vertical twin tails at high angle of attack has been studied by many scientists for many years with various degrees of success. Shock wave-boundary layer interaction, separated flows at high angles of attack, vortex interaction and bursting are phenomena responsible for buffet excitation and structural response of vertical twin tails of aircraft flying and maneuvering at high angles of attack. The magnitude of the structural loads can approach limiting values and would considerably reduce the fatigue life of the structure.

Various techniques for buffet attenuation have been developed. Unfortunately, the problem has not been solved. Advanced fighter aircraft capable of maneuvering at high angles of attack and high g's experience strong multiple-mode tail buffeting. Buffet attenuation and possible elimination must be studied both theoretically and experimentally. In order to achieve reliable results, the different static and dynamic effects on an aircraft structure must be analyzed simultaneously.

The first studies of buffeting started in the 1930's and both the USA and European countries showed a lot of interest in the problem (Ref 1). Later on, some predictions of tail buffet loads and fatigue damage experienced by fighter aircraft during high angle of attack maneuvering were reported for design application (Ref 2). Predictions were obtained for the F-111 using forcing functions derived by integration of pressure time histories with the natural buffeting modes, correlation of predicted and measured damping, and correlation of predicted and measured buffet response (Ref 3).

Wind tunnel testing was used extensively to measure unsteady pressures present on the tails of aircraft at high angles of attack and the buffeting response (Refs 4-5). Experimental research was carried out separately by the structures and aerodynamics scientists. Huston (Ref 6) used traditional methods to correlate wind tunnel data with flight buffeting response while Mabey (Ref 7) presented an evaluation of dynamic loads due to the separation of the flow field. Investigations of buffet on wings, fuselage, and weapon bays of aircraft were also reported by various researchers ( Refs 8-11).

This report refers, in chronological order, to studies of buffet excitation on advanced fighter aircraft tails and, in particular, to the F-15 twin vertical tails.



## II BACKGROUND

Aircraft can experience buffet when unsteady pressures associated with separated flow excite modes of vibration of the aircraft structure. For twin tail fighter aircraft, buffet can be severe when maneuvering at high angles of attack, due to separation at the leading edge of the wing being convected down stream and impinging on the vertical tail. This buffet is a function of the geometry of the wing, fuselage, and vertical tails. Triplett (Ref 5) performed wind tunnel tests to obtain the buffeting pressures on the vertical tail surfaces of a 13 percent F-15 model equipped with a rigid and a flexible tail. The MCAIR low speed tunnel was used. The research indicated that, for the configuration tested, the pressures and the buffet response levels reached a maximum at 22 degree angle of attack, and the predominant mode was the first torsion. Kulite pressure transducers were used to measure both steady and unsteady pressures. These pressures on the flexible tail were different in magnitude and distribution when compared to the rigid tail. For the same tail incidence, the lift was three times as large for the flexible tail. The results obtained were very valuable for the analysis and design of a torsional oscillation suppression system for the vertical tails.

At first, aerodynamicists and structures experts researched vortex-dominated and buffet flows separately. As mentioned in the introduction, Huston (Ref 6) indicates the traditional methods used to correlate wind tunnel and flight buffeting response; Mabey (Ref 7) gives an assessment of dynamic loads due to flow separation.

Other researchers tried to predict buffet on empennage by theoretical and experimental techniques. Edwards (Ref 12) assessed the validity of Euler as well as Navier-Stokes equations in modeling vortex-dominated flows conducive to buffet. He stressed the importance of grid density to obtain accurate, converged calculations, and showed that computational finite difference methods can provide accurate solutions of the thin-layer Navier-Stokes equations for flows about complex aircraft. Ferman et al. (Ref 13) developed a unified approach for predicting buffet response of a fighter aircraft empennage operating at high AOA. Ferman derived two approaches for predicting buffet response of a fighter aircraft empennage. The first one used elastically scaled models in wind tunnel tests to provide full scale prediction. The second was based on calculations using measured pressure data from wind tunnel tests. The latter method was considered to be more versatile.

Zimmerman et al. (Ref 14) show the buffet pressure frequency responses for an advance fighter aircraft; the peak frequency decreases with increasing angle of attack. Cunningham et al. (Ref 15) report unsteady pressure and flow visualization tests on oscillating delta wing models, with particular reference to the vortex systems (strake and wing vortices). Vortex lift augmentation is shown to occur between 8 and 18 deg angle of attack and the downward break in the lift curve slope indicates the onset of burst vortex flow over the planform. The maximum normal force coefficient,  $C_n$ , occurs at 35 degree AOA; at higher angles the flow is fully separated and the value of  $C_n$  falls. The aerodynamic community is trying to understand the physics of separated vortical flows,

and data bases are being gathered which can be used to validate CFD codes. Experiments have been performed on static, rigid models.

Elsenaar et al. (Ref 16) report results of vortex flow development on a 65 degree cropped delta wing at Mach 0.4 to 4.0. Both sharp and rounded leading edges were tested for validation of Euler and Navier-Stokes codes. Other experiments have used non-intrusive 3-D laser Doppler velocimeters to improve the data quality for code validation. Pagan and Soligna (Ref 17) investigated in detail the bursting of vortices generated by a 75 degree delta wing. RMS velocity components were reported together with mean velocity. This was done in order to study the unsteady aspects of the flow field. The region downstream of the vortex burst generated strong fluctuations.

Komerath (Ref 18) reported a quantitative study on the low speed flow environment of a scaled model of an F-15 fighter aircraft at high angles of attack. Laser sheet flow visualization was used to observe the various locations of vortex generation, and the evolution of these vortex flows. Laser Doppler velocimetry was used to obtain quantitative values of the velocity field. Although the vertical tails were immersed in rotational flow, no concentrated vortex was observed. At 22 degrees AOA, the flow separated on the outside surfaces of the vertical tails. Mabey (Ref 19) performed extensive studies of tail buffeting at high angles of incidence on a complete scale model with a single fin. He found that the buffet excitation in the first bending mode was controlled by the wing flow separations and contained a peak at a well-defined frequency parameter. Adding trapezoidal or gothic canards strongly influenced the fin buffeting, and sideslip or strakes increased it.

Other researchers studied, both theoretically and experimentally, the tail buffet characteristics on the F-18 (Refs 20-22). Komerath et al. (Ref 20) observed sharply peaked spectra both inboard and outboard of the upper portion of the vertical tails. The narrow-band fluctuations appeared to originate in the separated flow over the wing surfaces. This demonstrated that the tail oscillations were driven by narrow-band fluid dynamic oscillations, whose frequency varied with angle of attack and flight velocity.

Zan (Ref 23) measured the buffeting on a single-tail generic fighter aircraft, such as the F-16. The results were correlated in terms of the buffet excitation parameter  $\sqrt{nG(n)}$ . At low angle of attack, where the flow on the forebody remained attached, the buffeting on the tail was negligible. The beginning of buffeting coincided with the onset of symmetric vortices and increased with increasing angle of attack, up to the onset of asymmetric vortices. At higher angles of attack, the buffeting decreased considerably. It was evident that the buffeting was directly connected with the vortex flow in the vicinity of the tail. Bean (Ref 24) then tried tangential leading edge blowing to alter the vortex flow pattern and characteristics on a single fin model with the intent of attenuating the fin buffet. Blowing at a constant rate delayed vortex breakdown and shifted the maximum buffet response to higher angles of attack. It is probable that the optimum blowing profile would be wing dependent and change with flight condition. Using an optimum blowing

profile might completely suppress the buffeting response without significantly changing the wing characteristics.

Jacobs (Ref 25) used artificial intelligence for predicting empennage buffeting pressures and elastic response as a function of upstream flow field and geometric conditions. The effort employed a combined neural network and finite element modeling to predict flexible tail response based on rigid pressure information. Weeks and Nagaraja (Ref 26) surveyed a number of numerical codes used for linear and nonlinear problems which can analyze vertical tail buffet and the aeroelastic responses of 3-D vehicles at high angles of attack.

Other studies were conducted during the time span 1993-1995 on vertical tail buffet for existing fighter aircraft, such as the F-15 and F-18. Some were directed towards the analysis of the vortex flow surrounding the tail, and vortex burst over the wings and tails (Refs 27-43). Cornelius (Ref 40) evaluated criteria for vortex breakdown. The parameters that govern stability were formulated in terms of the local vortex flow variables. Laser measurements were taken and showed that the critical parameters, such as the ratio of axial-to-crossflow energy, decreased downstream from the adverse pressure gradient along the vortex trajectory, providing conditions that correlate with the location of vortex breakdown. Visbal (Ref 38) ascertained that breakdown emerged from the growth and upstream propagation of essentially axisymmetric disturbances which subsequently lose stability to helical modes. Both spiral and bubble modes of breakdown were compared with experimental measurements. Compressibility was shown to have a significant effect on the flow structure above a 75 degree swept wing at incidences corresponding to breakdown onset. Others studied the characteristics of surface pressures due to buffet (Refs 44-45). Correlation of wind tunnel and flight data were obtained for the F/A-18 vertical tail buffet (Ref 46). Mabey et al. (Ref 47) performed measurements in a cryogenic wind tunnel in order to find out the importance of the variations in frequency parameter and Reynolds number, the choice of model material ( considering stiffness and damping), and the effect of static aeroelastic distortion. The choice of the wind tunnel gave them the opportunity to obtain conditions independent of temperature effects and to test at higher Reynolds numbers. Dima and Jacobs (Ref 48) investigated the effects of dynamic pitch-up maneuvers on empennage environment by means of a system of local-stationary equations based on the steady-state response equivalence. This system constituted a design tool to obtain more accurate values of buffet response and structural fatigue. Wolfe et al. (Ref 49) investigated the surface pressure loading on buffeting fins and concluded that the onset of vortex breakdown played a major role in dictating the spectral content of the pressure fluctuations on the fin. Pendleton et. al (Ref 45) and Meyn et. al (Ref 50) performed wind tunnel buffet studies on a full scale F/A-18 with and without a LEX fence. The fence significantly reduced the magnitude of the rms pressures and bending moments for angles of attack up to 22 degrees. The importance of this experiment lay in the comparison of the full-scale results with small-scale tests. It showed that the tail buffet frequency scales very well with length and velocity. Moses and Pendleton (Ref 51) also compared the pressure measurement results of a full-scale and a 1/6 scale F/A-18 twin tail during buffet. In 1995/96, multidisciplinary methods

were used to compute the vertical tail buffet (Ref 52). Three sets of equations were used on a multi-block grid structure. The first set was the unsteady, compressible, full Navier-Stokes equations. The second set was the coupled aeroelastic equations for bending and torsional responses. The third set was the grid-displacement equations used to update the grid coordinates due to the tail deflections. This system allowed the computation of coupled and uncoupled bending-torsional responses. Cunningham (Ref 53) illustrated problems associated with nonlinear aerodynamic effects and their impact on structural integrity.

### III F-16 UNSTEADY AERODYNAMICS INVESTIGATION

Fighter aircraft can experience oscillations of external stores that critically affect structural integrity and result in performance limitations. Limit Cycle Oscillations (LCO) result from a variety of phenomena that produce unsteady separated flow for some store configurations. The F-16 experienced LCO for several store configurations due to shock-induced trailing edge separation on the wing. Engine spillage during throttle transients can cause vibration on the down stream structures such as store fins and antennas, resulting in fatigue damage.

Cunningham (Ref 53) performed a detailed investigation with regard to the fatigue life of the ventral fins of the F-16 fighter aircraft. The fatigue life was shortened considerably with the use of LANTIRN pods upstream of the fins. Inlet spillage also contributed to the deterioration of the fins. Airflow separating and reattaching continuously ahead of the fins (caused by strong turbulence) was another cause of the fins fatigue problem. Modification of the aircraft, such as increased inlet size for larger engines, inlet thin lip effects (such as severe flow separation) during throttle chops, and the addition of the cooling system exhaust deflector accentuated the buffet loads even more and led to fatigue problems on the fins. As a result, the ventral fins had to be re-designed. Using a semi-empirical model, various modifications were investigated, such as increasing the stiffness by 40%, leading edge nose cap, and using a constant NACA airfoil section from root to tip for the fins. Results showed that the solution that takes into consideration the aeroelastic nonlinearity has the best chance to solve the fin problem. As stated above, it is important to limit the effects of two types of nonlinear aeroelastic problems, i.e. limit cycle oscillations and large amplitude buffet.

#### IV TECHNIQUES FOR BUFFET ATTENUATION

Various techniques for buffet attenuation have been developed with some degree of success. Unfortunately, the problem has not been solved. Advanced fighter aircraft capable of maneuvering at high angles of attack and acceleration experience strong multiple-mode tail buffeting.

Ferman (Ref 54), referring to the vertical tail buffet, stated that "traditional fixes related to structural fatigue consisted of reinforcing the broken structure. This tended to merely chase cracking in the secondary structure from one area to another on the tail. With the use of composite material technology and adhesive bonding technology, it was possible to improve the F-15 vertical tail durability". He then tried to reduce the strong buffeting of the F-15 vertical tails by using a bond-on composite stiffening doubler called Exoskin. This approach should reduce the tail vibration response created by high angle of attack buffeting forces. However, this patch has not been in use long enough to determine its effectiveness.

Mabey and Pyne (Ref 55) performed some new research on the effects of wing leading edge blowing, similar to what had been done before by Bean et al. (Ref 24). The buffet excitation parameter  $\sqrt{nG(n)}$  decreased consistently with increasing blowing momentum coefficient  $C_{\mu}$ , up to the attainment of an optimum  $C_{\mu}$  for a given angle of incidence. The indication was that buffeting could be attenuated. In addition, the overall L/D increased. They believed that this technique was promising.

Rock and Ashley (Ref 56) presented a technique that used active control to reduce the fin buffet response on the F/A-18 vertical tail. They first developed a model for control design generated by finite element structural analysis and linearized potential aerodynamic theory. With this model they designed a feedback control law that affected the movement of the rudder by means of feedback signals received from an accelerometer mounted on a fin-tip vane. They proved that it was possible to reduce the bending moment associated with the first modal frequency by 34% with the rudder motion limited to 2 degrees. A similar model was also effective on the F-15 aircraft. This result was based on theoretical analysis and was not proven in practice. However, there was a potential for enhancing the fatigue life of the empennage structure of aircraft operating at high angles of attack. Later on, RANN Corporation and McDonnell Douglas (MDA) suggested the use of adaptive feedback neural network controllers to activate the rudder command signal.

Barrett et al. (Ref 57) tried to reduce the buffet response of an advanced fighter tail section by passive damping, i.e. they started a research and development program whose goal was the development of buffet and fatigue resistant structure. They applied passive damping technology to redesign structural components. The specific components addressed included the beavertail section of the F-14D and the spars of the F/A-18 vertical tails. The damping material used consisted of advanced composites. Benefits

can be obtained by including damping as a parameter in the design of parts of the structure that are subjected to dynamic loads.

Hauch et al. (Ref 58) studied the possibility of reducing tail buffet response by using integrated piezoelectric actuators. They performed their experiments on a 5%-scale aeroelastically-tailored structure that had similar vibration response to a full-scale aircraft structure. At high angles of attack, the leading edge vortices generate severe buffet pressures on the vertical tails, causing excitation of the first few natural modes of the flexible tail. Simple control algorithms were used with piezoelectric actuators and sensors to attenuate the strain at the root of the tail. Spectral analysis showed that the peak response was 65% less than the one without actuators.

Lazarus et al. (Ref 59) also addressed the feasibility of using active piezoelectric buffet suppression system to reduce buffet vibration in the vertical tails of aircraft. Full-scale piezoelectric buffet suppression systems were designed and evaluated. Many different actuator distributions, sensor locations and controller architectures were examined. Significant performance improvement was achieved (greater than 70%) with minimal weight penalties. This study showed that the tail vibrations could be reduced and the fatigue life extended.

It is important to list past and on-going WL efforts on techniques for tail buffet attenuation. The past efforts included a contracted F-15 buffet test in 1982 on a 13% scale-model with one rigid and one flexible vertical tail by Triplett (Ref 5), and a RANN analytical effort for active control using rudder on the F/A 18 and a tip vane on the F-15 (Ref 60). WL supported NASA Ames wind tunnel tests on a full-scale F-18 by conducting ground vibration tests on the vertical tails and measuring buffet data on one of the vertical tails (Ref 45). WL also supported NASA Langley Research Center's (LaRC) test on a 16% scale F-18 model through the supplying of a technician and test equipment and by supplying a control law through a data exchange agreement (DEA) with Germany. WL supported ACX and Rohini International with SBIR contracts for research on buffet load alleviation, provided an in-house numerical simulation of the interaction between leading edge vortex and a rigid vertical tail (Ref 61), awarded a grant to Dr. Singh (Clark Atlantic University), Dr. Sankar (Georgia Tech University) and Dr. Smith (Georgia Tech Research Institute) to modify an Euler/Navier-Stokes computer code (ENS3DAE) and include a trim module in order to perform trimmed and untrimmed aeroelastic analyses. Funding was also provided to Georgia Tech Research Institute to improve the computer code FASIT (Fluid and Structures Interface Toolkit), which is used to transfer data between different computational grids; specifically, it transfers data between CFD and structural grids in order to perform static aeroelastic calculations. FASIT is being enhanced to include data transfer for solutions of dynamic aeroelastic problems, as well as data transfer to/from unstructured CDF grids. On-going WL efforts include RANN analytical research on the F-22, ACX Phase II SBIR research for buffet load alleviation on the F-18 vertical tails, and Rohini International Phase II SBIR research for buffet load alleviation on the F-15 vertical tails.

Another on-going effort is NASA LaRC's ACROBAT (Actively Controlled Response of Buffet Affected Tails) program. This program consists of wind tunnel tests in NASA LaRC's 16-foot transonic dynamic tunnel to ascertain the effect of piezoelectric actuators and rudder on vertical tail buffeting. Moses (Ref 62) performed the experiment and recently presented some preliminary results, which indicated a reduction in power spectral density (PSD) of the root strain (bending moment) of up to 60% for certain angles of attack. In the Active Vertical Tail (AVT) tests, McDonnell Douglas Aircraft (MDA) and NASA LaRC conducted buffet suppression tests using integrated piezoelectric actuators. The model was a generic fighter that could be assembled into different configurations. MDA chose an F/A-18 to pursue the Buffet Load Alleviation System Technology (BLAST) program which refers to vertical tail buffet. An adaptive neural network is proposed for control of the rudder actuator. The Navy also conducted in-house wind tunnel tests and CFD simulations on a generic fighter configuration similar to the MDA/NASA model.



## V ROLE OF WL/FI RESEARCH TEAM

In view of the importance of obtaining solutions of unsteady aerodynamic problems, WL decided at the beginning of 1994 to establish the "Unsteady Aerodynamics Integrated Product Team" (UAIPT). This team was formed by scientists and engineers from three different divisions in order to coordinate multidisciplinary research. The three divisions were the Aeromechanics Division, mostly involved in experimental and computational aerodynamic problems, the Structures Division, involved in both metallic and composite structures development, and the Flight Control Division, mainly involved in establishing and evaluating flight control laws (Fig 1).

The UAIPT was considered the center for coordinating and integrating unsteady aerodynamic research at WL (Fig 2). It initiated contacts with the various System Program Offices (SPOs) at Wright-Patterson AF Base, such as the F-15 SPO, the F-16 SPO, the F-22 SPO, the C-17 SPO, and the B-2 SPO. Among the many problems in unsteady aerodynamics, such as Limit Cycle Oscillations (LCO), buffet, flutter, separated flow, etc., the buffet problem seemed to be the most important due to the many requests received for immediate attention and support (Fig 3). Buffet attenuation and possible elimination had to be studied both theoretically and experimentally in-house and by contract. In order to achieve reliable results, the different static and dynamic effects on an aircraft structure had to be studied simultaneously. Team members had to work together and interact with each other to define and conduct an in-house program. Support was received by another service, the Navy, by a Government agency, NASA, and private companies, such as Rohini International, RANN Corporation, ACX, and MDA (Fig 2). Research was centered on computational fluid dynamics (CFD), finite element research, vibration tests, and wind tunnel tests. The first project selected by the UAIPT consisted in improving present technology to obtain significant buffet vibration reduction.

Twin tail buffeting problems are quite different for different aircraft. For example, the F/A-18 problems are attributed to the bursting of strong vortices and the attendant high intensity turbulence which drive the structural dynamics modes at high angles of attack. F-15 aircraft investigations show a concentration of energy fluctuation over the wing at high angles of attack, which then propagates downstream in a narrow band of frequencies enveloping the vertical tails.

Rohini International was awarded a Phase II SBIR contract for research on buffet load alleviation on the F-15 vertical tail (Ref 63). Under this contract the use of stacked piezoelectric actuators was investigated as a means of suppressing buffet. Structural dynamic tests were conducted on a full scale F-15 vertical tail subassembly with piezoelectric actuators and reported by Hanagud et al. (Ref 64). Hanagud was able to determine the vertical stabilizer dynamic response characteristics. Natural frequencies, mode shapes, and damping ratios of the modes were studied to determine their interaction. The results of these vibration tests correlated well with data from an operational F-15 aircraft. Modes from the laboratory test article (F-15 subassembly) and the aircraft were identified and found to be the same. The nonlinearities that were

observed in the F-15 vertical tail structure appeared to be quadratic. Therefore, the laboratory subassembly could be used to predict the effects of structural modifications of the vertical stabilizer and the effects of active or passive vibration controllers on the full scale aircraft (Ref 63). Since stiffening of the tail structure alone is not an effective means of reducing the vibrations, it may be necessary to use an active vibration absorber capable of sensing the buffet induced structural dynamics reducing the multi-mode vibration.

In the Rohini/Georgia Tech effort, lateral and torsional vibrations in the plane of the vertical tail were controlled by applying stresses and strains with piezoelectric actuators. The optimum locations for the actuators that would give a maximum response to lateral and torsional vibrations of the vertical tail had to be determined. That was accomplished by using in-plane actuators and measuring lateral and torsional deflections at various desired locations. In this way the best locations for controlling the vibrations at each individual mode were found. The force disturbances were generated by a shaker mounted on the outboard trailing edge of the vertical tail. Transfer functions between the accelerometer and the actuator were determined. A control system was designed whose purpose was to reduce the bending response (2nd bending at 39.8 Hz) of the tail as measured by a tip mounted accelerometer. Tests results showed that the magnitude of the acceleration at the tip could be reduced by nearly 40%.

A computer program was developed to construct a finite element model from the measured experimental modal data. The first step in the program was to input the experimentally measured modes and natural frequencies. The second step in the program was to construct the mass matrix from the data provided in the vertical tail drawings, the densities of different components, and the total weight of the vertical tail. In the third step, the measured relative modal amplitudes were normalized with respect to the mass matrix. Next, the damping and stiffness matrices were calculated, and the natural frequencies were calculated from the reconstructed mass, damping, and stiffness matrices. This experimentally-based finite element model yielded a range of frequencies which were reasonably accurate.

ACX, Inc. was also supported by WL in their research on buffet load alleviation with distributed piezoelectric actuators applied to the vertical tails of an F-18 aircraft. SBIR Phase I and Phase II contracts were awarded, with the goal to conduct ground vibration tests on a full scale structure, measure the vibration level reduction, and demonstrate piezoelectric actuators' authority at full loads.

In Phase I (1994), ACX assessed the feasibility of employing piezoelectric actuators. This was demonstrated on a scale model with simple geometry by Lazarus (Ref 59). Design and feasibility studies were conducted on a full scale tail. A distribution of actuators in the vertical tail was selected in the areas of maximum strain. ACX demonstrated the effectiveness of buffet suppression using piezoelectric actuators and active control. Power requirements and weights were expected to have minimal impact on aircraft operation. For an 8% increase in tail weight, the damping of the first

mode was increased by 60% which would significantly reduce structural damage and fatigue.

In Phase II, ACX addressed the fabrication and integration of the actuators, the electronics, and power conditioning. They evaluated the controller implementation, testing, and performance. The controller did not have to be inserted in the flight control system since it could be dedicated to the actuators only. In the meantime, McDonnell Douglas Aerospace (MDA) studied the cost benefits of equipping the tail with actuators instead of replacing it. The actuators should last the life of the tail to reduce maintenance of the buffet suppression system and the added weight should be less than 25 pounds per tail, with a maximum added weight to the aircraft of 100 pounds for both tails. The actuators were embedded in the aircraft skin and thermal control had to be addressed. The cable between the amplifiers and the actuators had to be shielded to avoid electromagnetic countermeasures (EMC) problems. Accelerometers and strain gauges were used as sensors; the accelerometers turned out to be more reliable. The NASTRAN finite element code was used for modeling the mode shapes, frequencies, and actuator modal influence. A linear unsteady aerodynamics code was used to compute the aerodynamic forces. The actuators were limited to peak actuation strain of 400 microstrain. In the case of least disturbance energy, up to 75% of buffet reduction was achieved, and in most severe cases, a 20 % reduction was still attained.

ACX, through The Technical Cooperation Program (TTCP), has set up a test program with the Defense Science and Technology Organization (DSTO), to be performed at the International Follow-On Structural Testing Project (IFOSTP) facility at the Aeronautical and Maritime Research Laboratory (AMRL) in Melbourne, Australia. This program is the Buffet Load Alleviation (BLA) experimental investigation. The USAF Technical Project Officers are Mark Hopkins and Doug Henderson, members of the UAIPT. The reasons to conduct ground tests in Australia are twofold: (1) A full size F/A-18 test aircraft is tested, i.e. a full size empennage is attached to the vehicle and not to a structure; (2) Even though this is going to be a ground test, the facility has the capability of applying realistic flight loads. It may be possible to go directly to flight testing upon completion of the ground tests. This international cooperative program will benefit a number of different aircraft, namely the F-14, F-15, F/A-18, F-22, and F-117. This program will be completed by March 1999.

The UAIPT decided to conduct an in-house experiment on a 4.7% scale- model of an F-15C aircraft to investigate the tail buffeting. The tests were performed in the SARL (Subsonic Aerodynamics Research Laboratory) wind tunnel located at Wright-Patterson AFB. A numerical investigation was conducted simultaneously.

The experiment used tangential blowing and later piezoelectric actuators to alleviate the buffeting response from the tail structure. The first test was limited to tangential blowing with sonic jets from the model's nose, gun bump, and a portion of the wing's leading edge near the root (See Fig 4). The model was equipped with one stiff vertical tail (the right tail) and one flexible tail. Fig 17 is a sketch of the modal patterns on the flexible vertical

tail; damping and frequencies for the first 3 modes are shown. The rigid tail was equipped with 12 dynamic pressure transducers, while the flexible one was equipped with 2 strain gauges, 2 accelerometers, and 12 dynamic pressure transducers. Fig 5 shows the model assembly in the wind tunnel. The second entry will include piezoelectric actuators. The locations of the actuators are shown in Fig 6 (note the axis location for the first torsion and second bending modes). A NASTRAN code was used to identify areas of high strain gradients which are effective locations for the piezoelectric actuators. Figs 36-38 are plots showing the strain intensity on the vertical tail for the first three modes. The accelerometer signals were used to determine the buffet excitation parameter,  $\sqrt{nG(n)}$ , in the vertical tail first bending mode according to the equation:

$$\sqrt{nG(n)} = \frac{2}{\sqrt{\pi}} \left( \frac{m\ddot{z}}{qS_f} \right) \xi^{1/2}$$

$G(n)$	=	power spectral density
$n$	=	reduced frequency
$m$	=	generalized mass in mode with respect to motion at tip (for accelerometer mounted on tip)
$\ddot{z}$	=	rms tip acceleration in mode
$q$	=	dynamic pressure
$S_f$	=	exposed tail area
$\xi$	=	total damping as a ratio of critical damping

The blowing tests were performed at Mach 0.2, angles of attack from zero to 32 degrees, sideslip angles from -4 to 4 degrees, and dynamic pressures up to 56 psf. Pressures on both the rigid and flexible tails were measured as a function of angles of attack with and without blowing. Fig 7 shows the location of the pressure transducers on the vertical tails. Representative test conditions are shown in Tables 1-4. The  $\beta = 0$  degree cases are shown in Figs 8-14 as plots of rms pressures acting on the flexible and rigid tails for different conditions (with and without blowing). The pressure plots in general show an increase in pressure with angle of attack, but the increase is more pronounced for the rigid tail (the values on the rigid tail are higher than the values on the flexible tail at the corresponding locations). Blowing had a beneficial effect at some conditions; at  $\alpha = 32$  and  $\beta = 0$ , blowing at 45 psi from the wing's leading edge reduced the rms buffet response for the first bending mode; at  $\alpha = 32$  and  $\beta = 4$ , the same amount of blowing from the wing's leading edge decreased the rms buffet response for the second bending mode. For other combinations of  $\alpha$  and  $\beta$  decreases of up to 36% were observed. Fig 15 is a laser light sheet photograph taken during the tests and showing a typical vortex pattern and the impingement of the vortices on the vertical tails. The buffet response from the tails was measured and power spectral densities are plotted for the first bending and first torsion modes in Fig 16. Additional data are presented in

Table 5. Figs 18-21 show the response of the different modes to the angle of attack variation for different sideslip angles and blowing coefficients. For the bending mode, the response increased with angle of attack up to the maximum test condition of 32 degrees, while for the torsion mode it increased up to an angle of attack of 24 degrees, then decreased drastically. Positive sideslip generally reduced the bending mode response; the torsion mode response decreased with a positive sideslip up to 24 degrees. At an angle of attack of 32 degrees the negative sideslip gave the smallest response for the torsion mode. The higher the blowing coefficient, the lower the bending mode response. The same occurred for the torsion mode up to 24 degrees. At higher angles of attack the blowing was detrimental. Specifically, for  $\alpha$  (angle of attack)=32 and  $\beta$  (sideslip)=0, the tests showed the largest buffet response. Results showed that: 1) Blowing from the wing leading edge with 45 psi of pressure reduced the rms buffet response by 2.9% and the peak frequency by 0.2% in the range of the first bending mode frequency; 2) For  $\alpha=24$  and  $\beta=0$ , in the range of the first torsion frequency, the blowing had an adverse effect, increasing the buffet response by 7.8%; and 3) For  $\alpha=32$  and  $\beta=4$ , in the range of the second bending frequency, the blowing decreased the buffet response by 7.2%, even though the peak frequency increased by 20%. Rms buffet responses were reduced for four different conditions from 6.2 to 36.1%. Only one other condition produced an increase of 1.7%.

The second phase of the in-house buffet test will investigate the use of piezoelectric actuation to reduce the response due to buffet. To evaluate the effectiveness of the actuators at various locations, frequency response tests were conducted. Figs 22-25 show the frequency response of the structure at the first bending, second bending, first torsion, and first and second bending actuator locations.

The numerical simulations were conducted by Bob Weyer, a UAIPT member (Ref 65). The computational model of a clean F-15C aircraft was similar to the wind tunnel model (Fig 26). Both models had flow through ducts, and the inlets and internal ramps were set for the subsonic high angle of attack condition. The engine sections on the inlet grid were bottlenecked to limit the mass flow without choking it. The geometry for this project was generated by a CAD system. This system retains the actual aircraft surfaces as files. The files are converted to discretized structured surface panels. All details of the aircraft were retained including the horizontal tail notch, inlet diverter gap, pods atop the vertical tails, separation between the horizontal tail and fuselage. A new unstructured grid generator (TETMESH) was used to create the grid around the complex configuration (see Fig 27). Computationally, a farfield boundary condition was modeled; therefore, tunnel effects were not modeled. An inviscid solution was obtained using the COBALT unstructured grid flow solver.

Fig 28 shows the flow over the gun bump. The vector components are colored to denote various pressures. From the top of the inlet the vortex core develops and moves downstream, then lifts over the wing and envelops the vertical tails (Fig 29). Fig 30 shows the same vortex pattern but the smaller vortices at the root of the tails are also visible. The streamline traces are shown in Figs 31-32.

The pressure on the vertical tails is shown in Figs 33-34. It is evident that the bottom of the left tail has outboard flow while the top has inboard flow. The right tail instead experiences outboard flow. For most of the conditions, the computational and measured pressure coefficients differed by about 20% (Table 7).

The computations for the flow-through case were compared to the experimental data for the forces and moments of the entire aircraft (Table 6). For  $\alpha = 24$  degrees and  $\beta = -4$  degrees, the lift coefficients differed by only 1% (computed value being larger), while the drag coefficients differed by 34% (computed value smaller). The pitching moments differed by only 7% (computed value less negative), but the rolling moments differed by 126% (computed value negative and measured value positive).

The follow-on computational effort included the engine-on case since the mass flow rate through the inlet with the engine on in similar flight conditions is seven times larger than the mass flow obtained with the flow-through inlet. Comparisons were made between the two cases. With the engine operating, the lift increased 6% but the drag increased by 10%. The pitching moment increased by 7%. The influence of the engine suction consisted in changing the location of the vortex origin. The origin moved forward on the leeward side while it moved aft on the windward side. The vortical flowfield is similar to the one with flow-through, but it is tighter and closer to the vertical tails (Fig 35).

The computational solution accurately described the flow field around an F-15 aircraft at high angles of attack and sideslip. The favorable comparison between computations and measurements indicated that the unstructured grid approach and an inviscid solution could be useful in further research.

## VI SUMMARY

The review of research performed on the buffet problems of fighter aircraft has revealed a continuous and steady progress toward the partial or full elimination of buffet on the vertical tails at high angles of attack. Tangential blowing had some beneficial effects at some conditions.

The latest, most promising technique of using piezoelectric actuators for active buffet control is being applied to the empennage of scale-models and full size aircraft. Preliminary results show that with a minimal weight increase due to the actuators, a considerable reduction in buffet is obtained with attendant increase of vertical tail fatigue life. The UAIPT is working in-house and with companies which are involved in different buffet load alleviation systems and on aerodynamic nonlinear effects.

Work in this area is continuing at present at a fast pace and the new results covering the performance of the actuators in ground tests and wind tunnel experiments will be presented as soon as they become available.

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APPENDIX

Figures and Tables



# UNSTEADY AERODYNAMICS IPT

- Goal: Coordinate unsteady aerodynamic research and focus an in-house multidisciplinary (Aeromechanics, Flight Controls, and Structures) team on key problems such as buffet, LCO, and aerodynamics-structural interaction.
- On-Going Project: Buffet Investigations Using a 4.7% Model of F-15
  - Experimental (SARL Wind Tunnel)
    - Characterization of buffet
    - Suppression tangential blowing/piezoelectric actuators
  - CFD Simulations
    - Euler
    - Navier-Stokes
    - Blowing

Fig 1. Unsteady Aerodynamics IPT





# TECHNOLOGY INTERACTION

## BUFFET RESEARCH

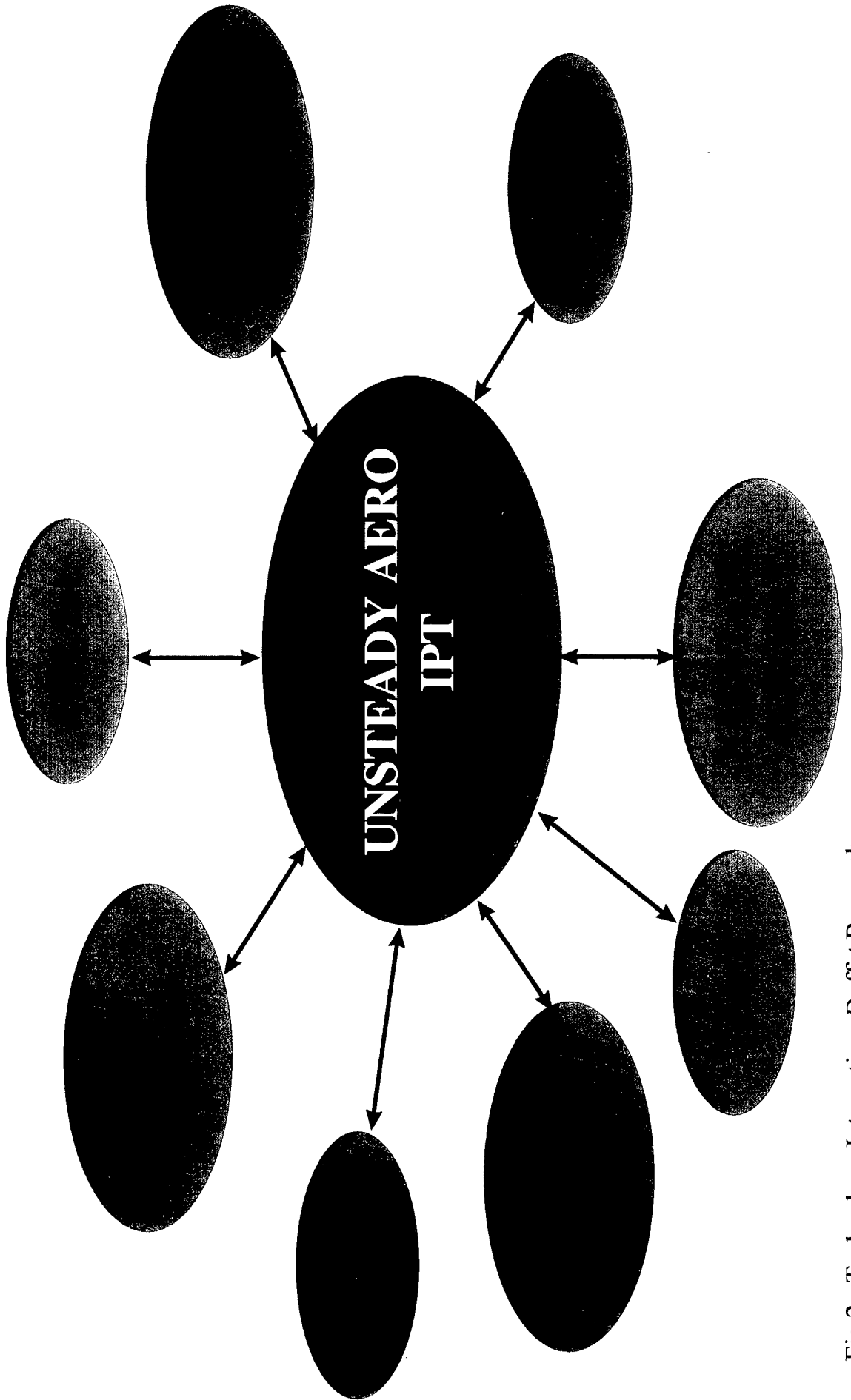


Fig 2. Technology Interaction, Buffet Research

# VERTICAL TAIL BUFFET RESEARCH

## Past Efforts:

F-15 Buffet Tests on 13% Model

Active Rudder Control Study for F/A-18 & F-15

NASA Ames Wind Tunnel Tests of Full Scale F/A-18

NASA Langley's F/A-18 Tests on 16% Model

## Current:

Phase II SBIR's

ACX - Buffet Alleviation (F/A-18)

Rohini - Buffet Alleviation (F-15)

In-House Buffet Suppression Tests on 4.7% F-15 Model

Phase I - Blowing

Phase II - Piezoelectric Actuators

Analytical Studies

Active Rudder Control Study of F-22

Application of CFD Methods for Loads Prediction

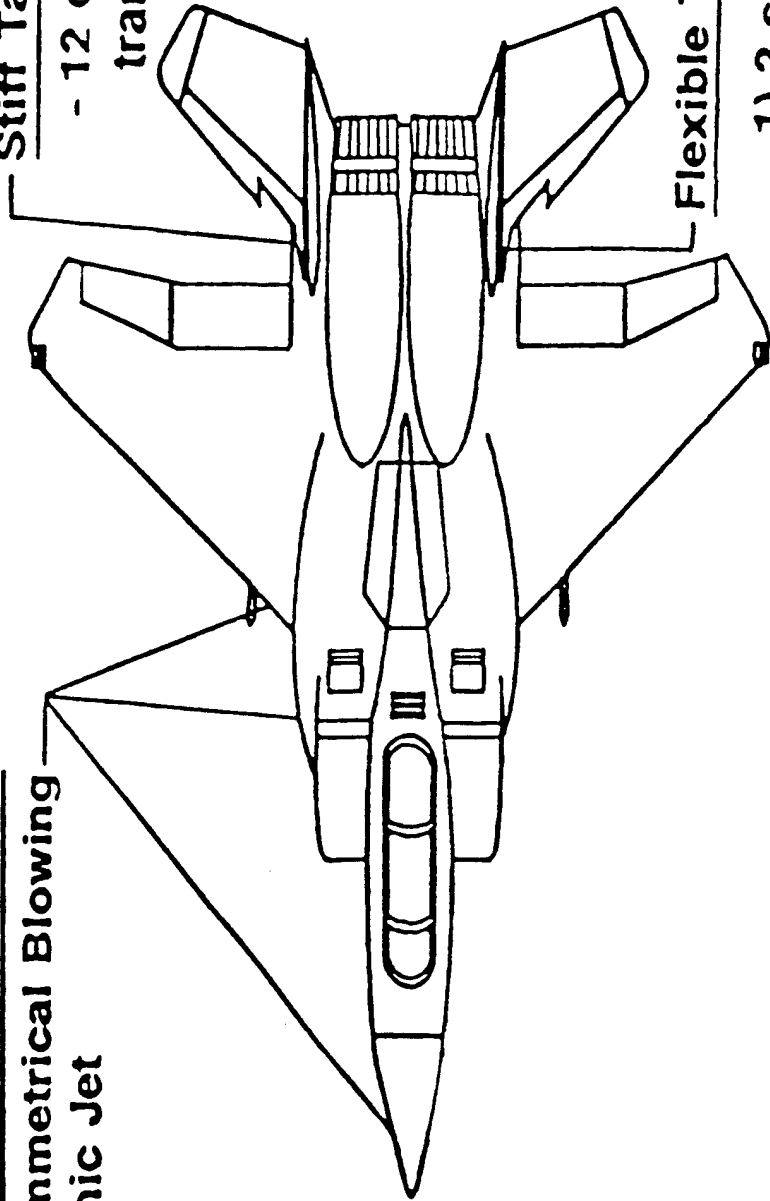
Fig 3. Vertical Tail Buffet Research

# F-15 Twin Fin Buffet Model

## Tangential Blowing Slots

- Symmetrical Blowing
- Sonic Jet

Stiff Tail  
- 12 dynamic pressure transducers



Flexible Tail

- 1) 2 strain gages,  
2 accelerometers,  
12 dyn. press. trans.
- 2) Piezoelectric actuators

Fig 4. F-15 Twin Fin Buffet Model

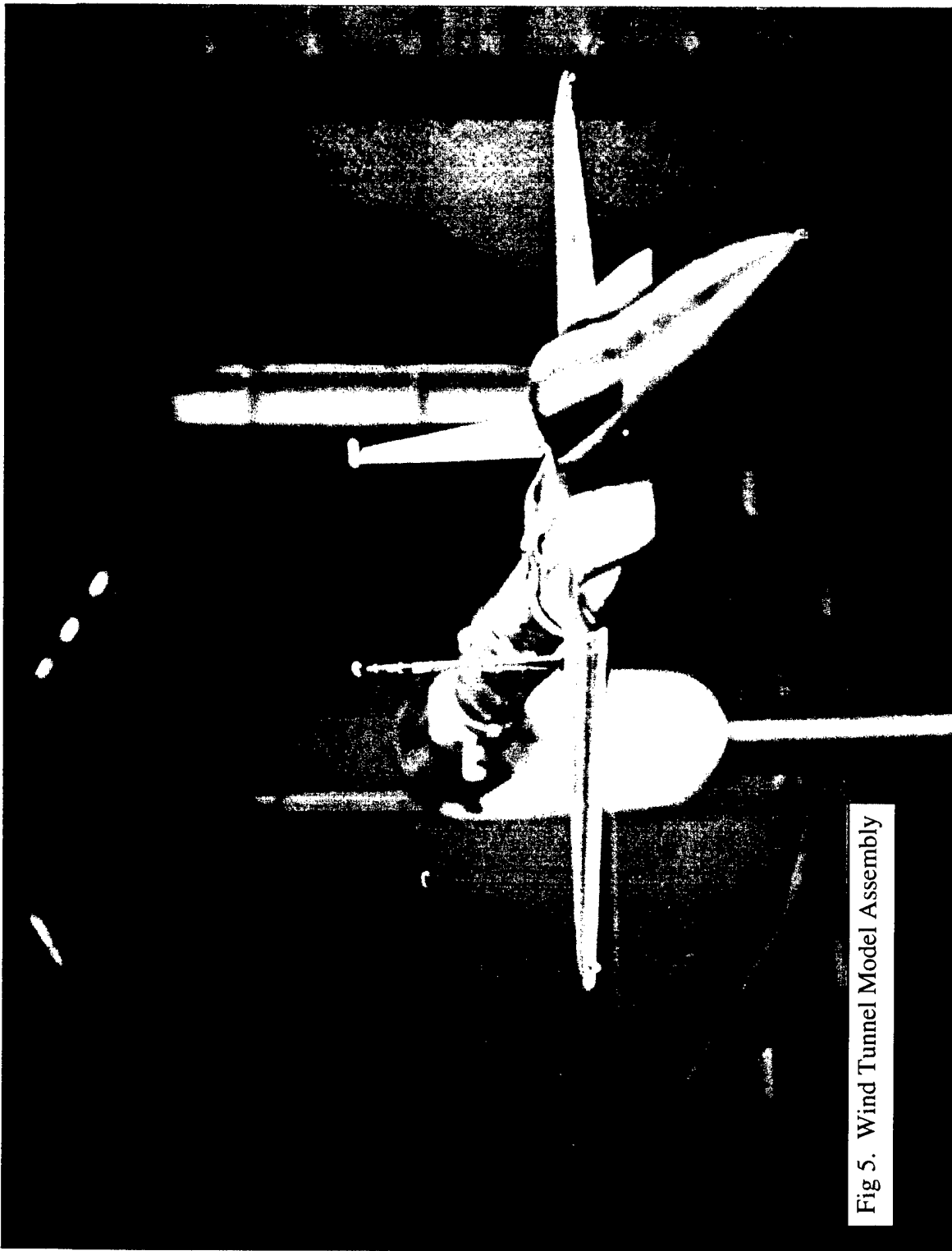


Fig 5. Wind Tunnel Model Assembly

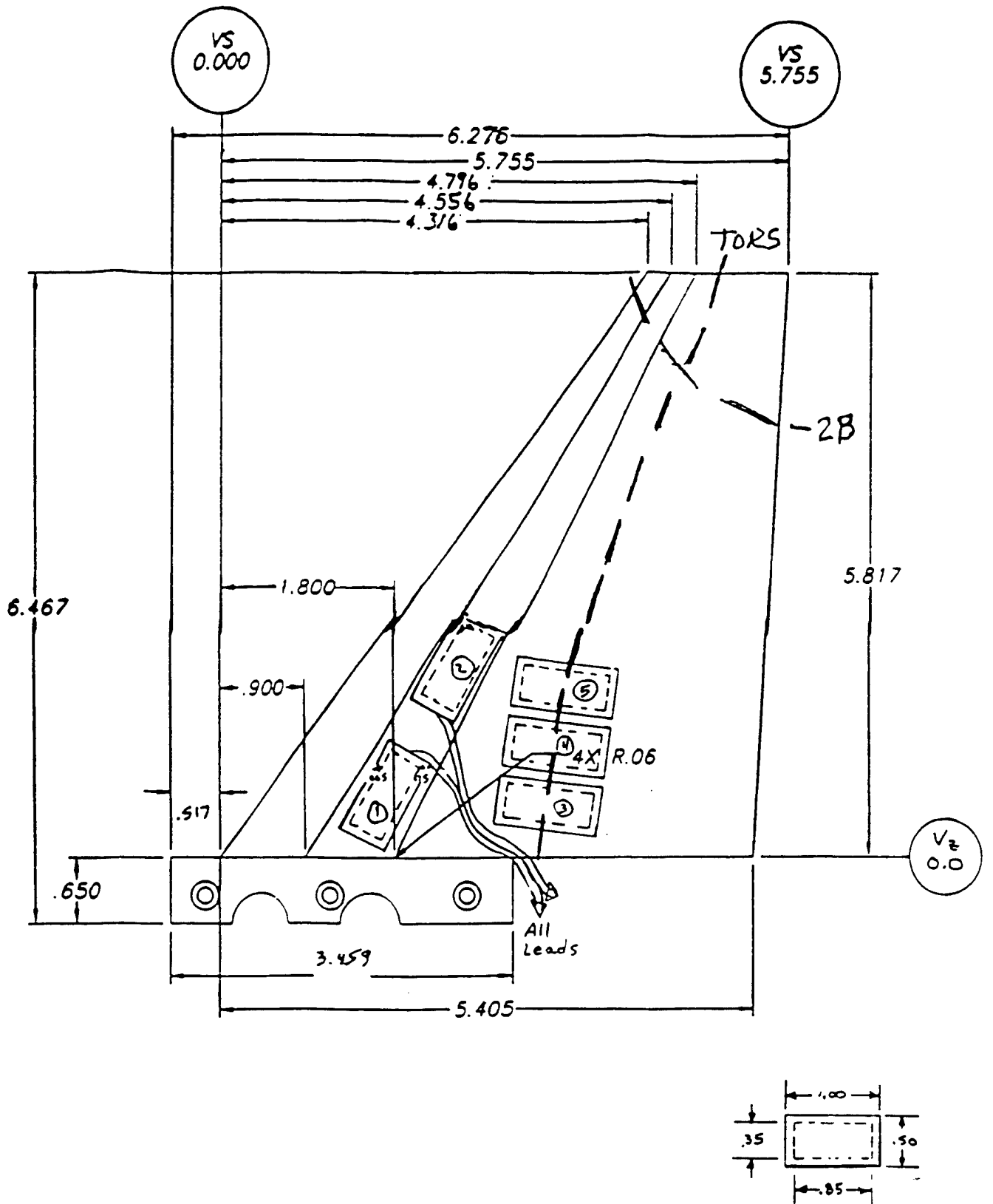
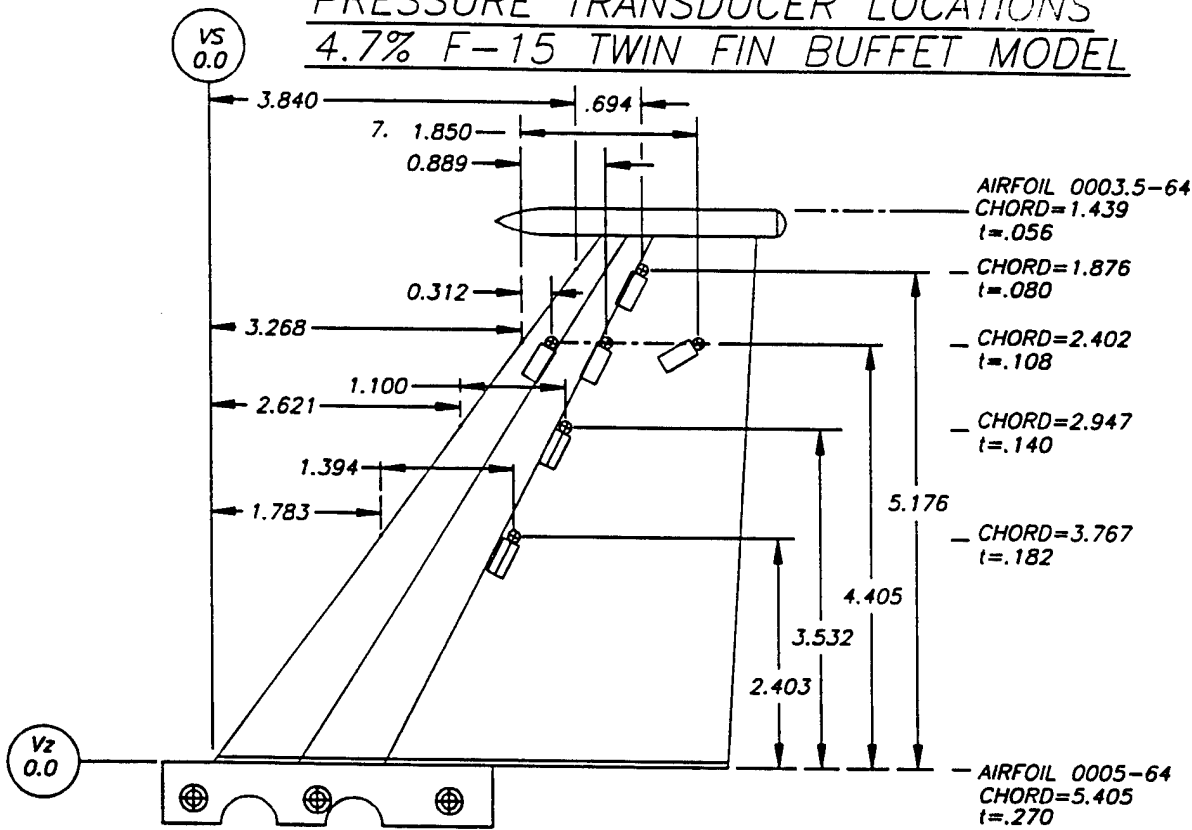
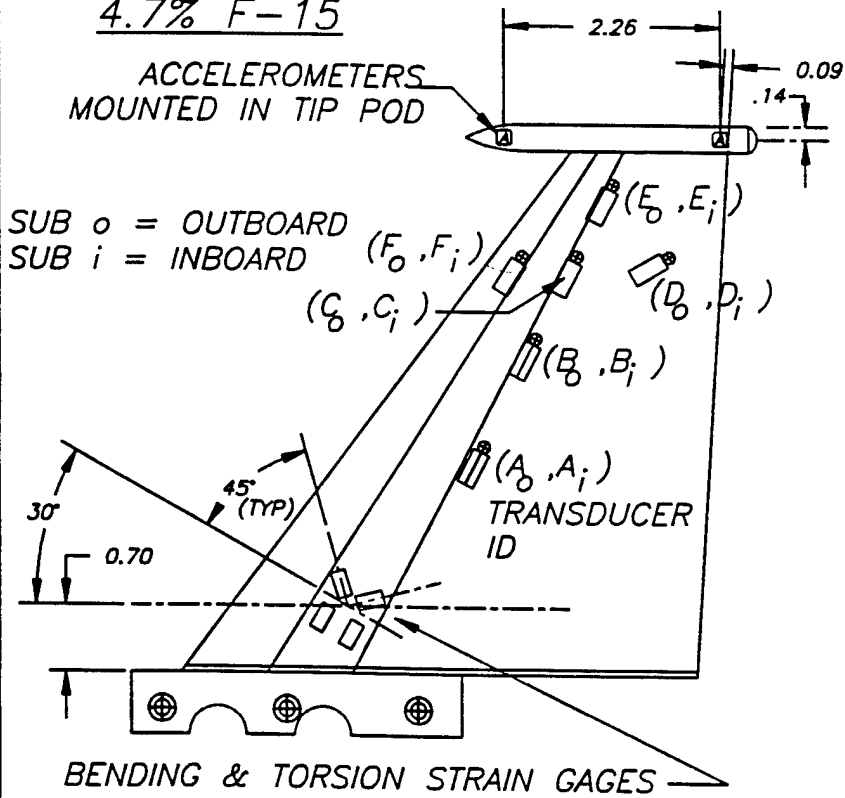


Fig 6. Flexible Vertical Spar

LEFT and RIGHT VERTICAL TAIL DYNAMIC PRESSURE TRANSDUCER LOCATIONS  
4.7% F-15 TWIN FIN BUFFET MODEL



LEFT FLEXIBLE VERTICAL TAIL INSTRUMENTATION DETAILS  
4.7% F-15



RIGHT RIGID VERTICAL TAIL INSTRUMENTATION DETAILS  
4.7% F-15

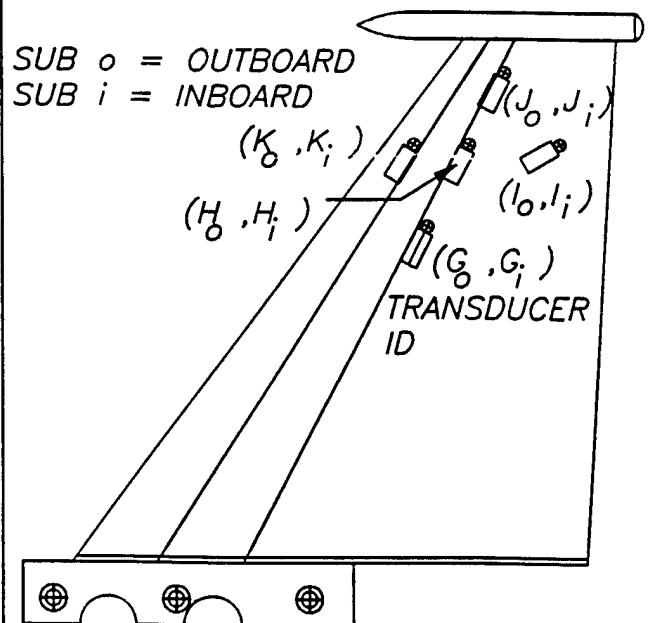
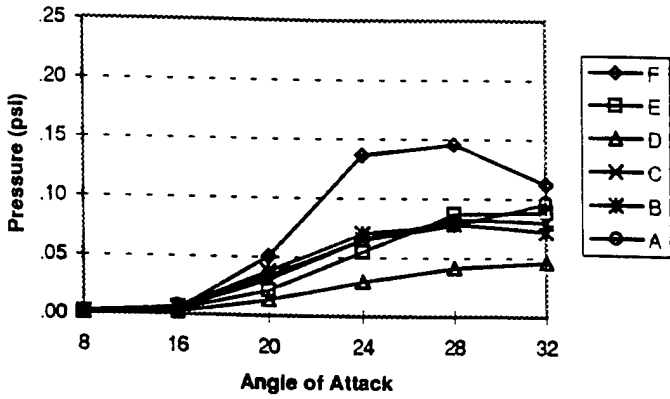


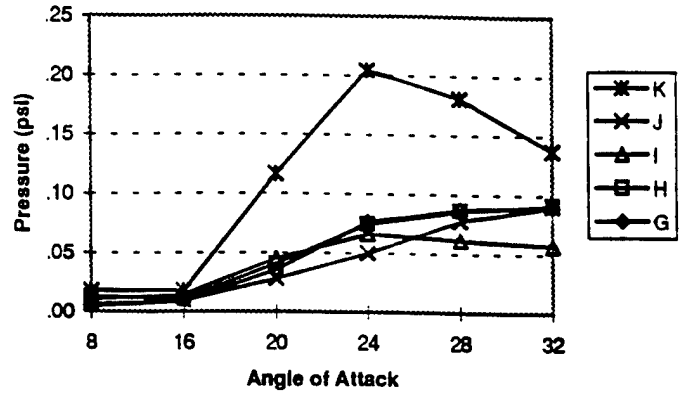
Fig 7. Left and Right Vertical Tail Dynamic Pressure Transducer Location

F-15 Vertical Tail Buffet Test

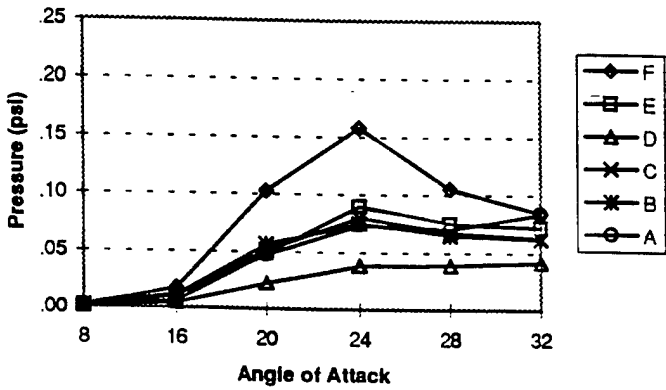
Flex Tail: Q=56 psf, Beta=0  
0 psi blowing @ wing L.E.



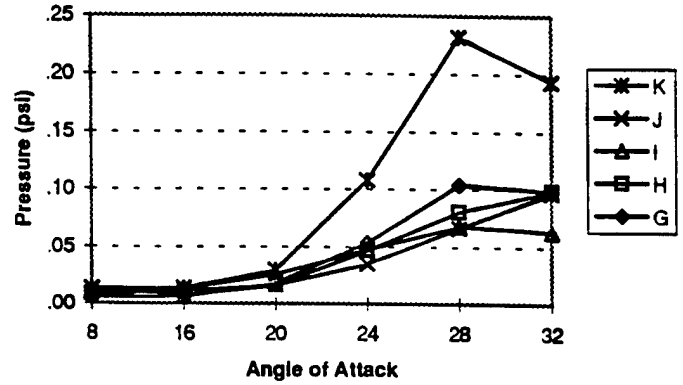
Rigid Tail: Q=56 psf, Beta=0  
0 psi blowing @ wing L.E.



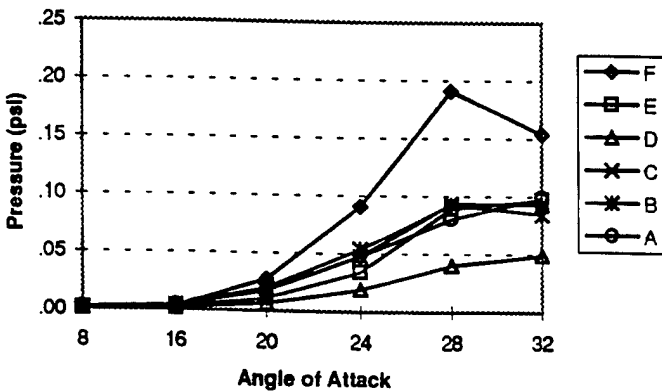
Flex Tail: Q=56 psf, Beta=-4  
0 psi blowing @ wing L.E.



Rigid Tail: Q=56 psf, Beta=-4  
0 psi blowing @ wing L.E.



Flex Tail: Q=56 psf, Beta=4  
0 psi blowing @ wing L.E.



Rigid Tail: Q=56 psf, Beta=4  
0 psi blowing @ wing L.E.

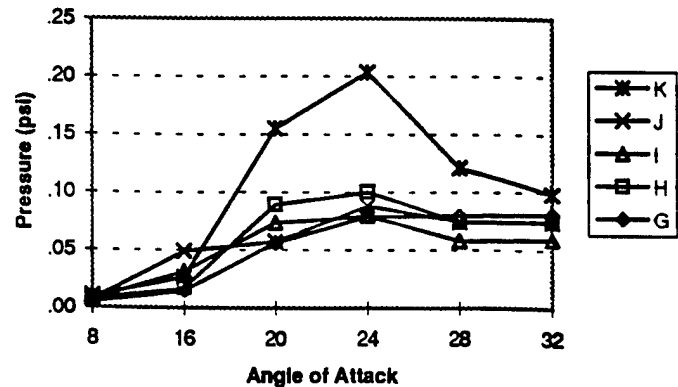
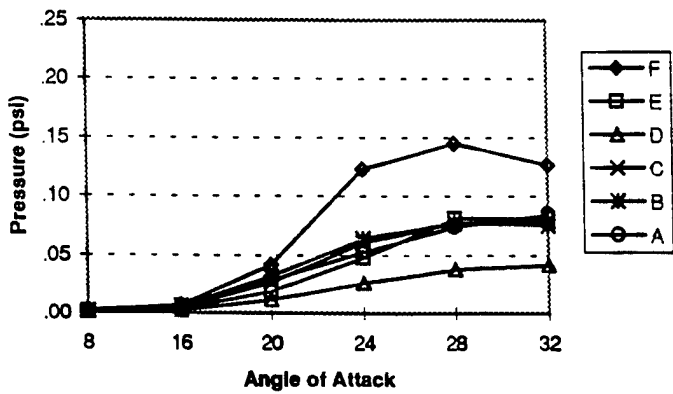


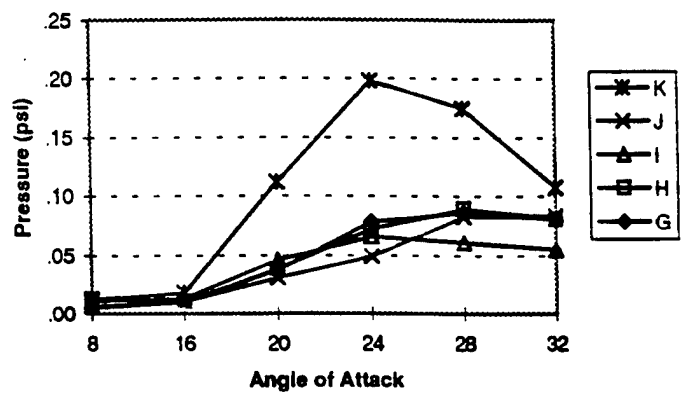
Fig 8. Measured Dynamic Pressure Distribution versus Angle of Attack

F-15 Vertical Tail Buffet Test

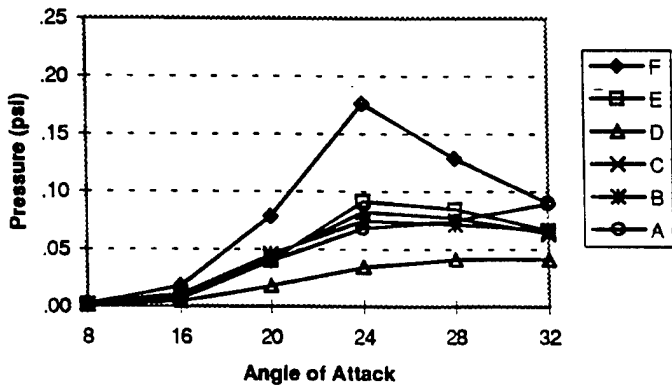
Flex Tail: Q=56 psf, Beta=0  
45 psi blowing @ wing L.E.



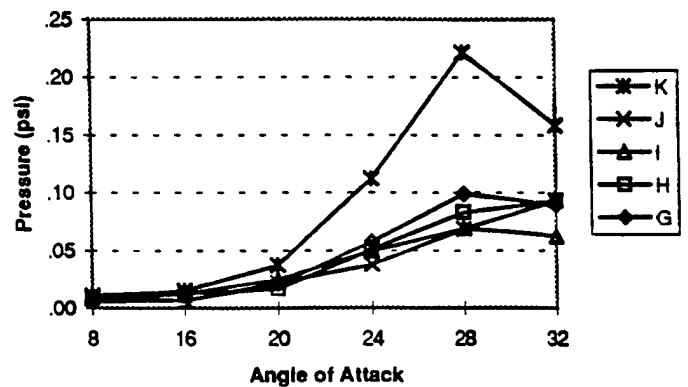
Rigid Tail: Q=56 psf, Beta=0  
45 psi blowing @ wing L.E.



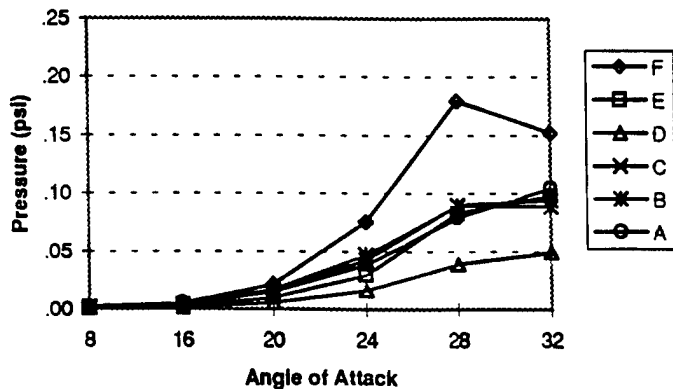
Flex Tail: Q=56 psf, Beta=-4  
45 psi blowing @ wing L.E.



Rigid Tail: Q=56 psf, Beta=-4  
45 psi blowing @ wing L.E.



Flex Tail: Q=56 psf, Beta=4  
45 psi blowing @ wing L.E.



Rigid Tail: Q=56 psf, Beta=4  
45 psi blowing @ wing L.E.

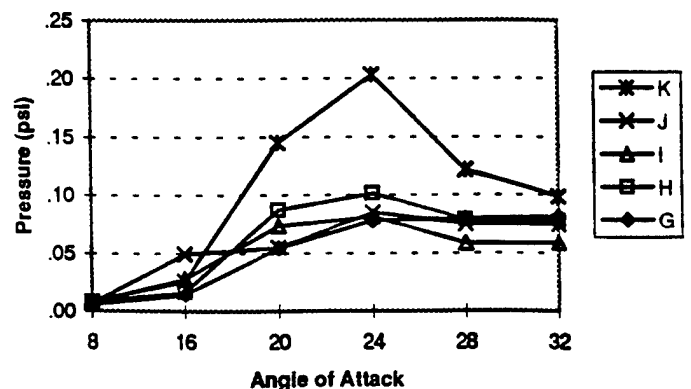
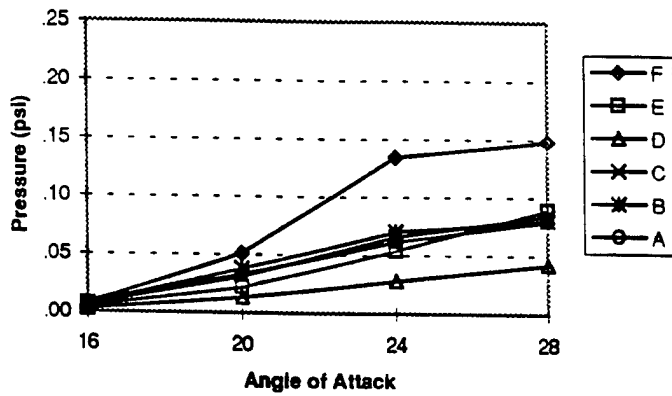


Fig 9. Measured Dynamic Pressure Distribution versus Angle of Attack

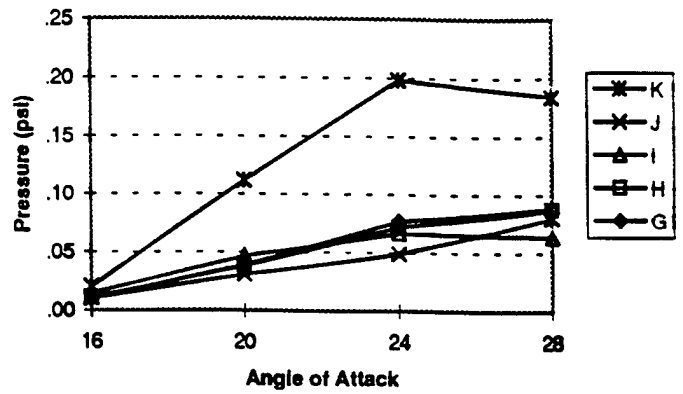


# F-15 Vertical Tail Buffet Test

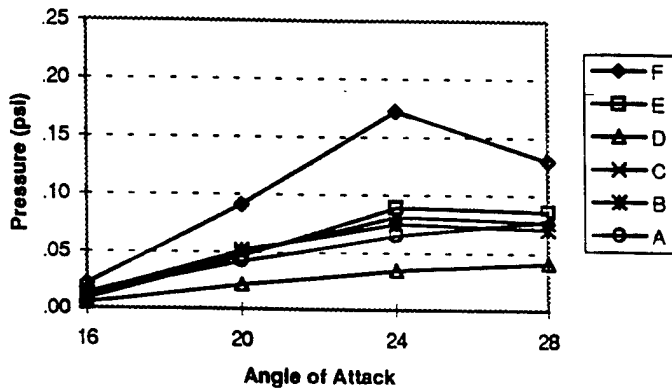
Flex Tail:  $Q=56$  psf,  $\beta=0$   
65 psi blowing @ wing L.E.



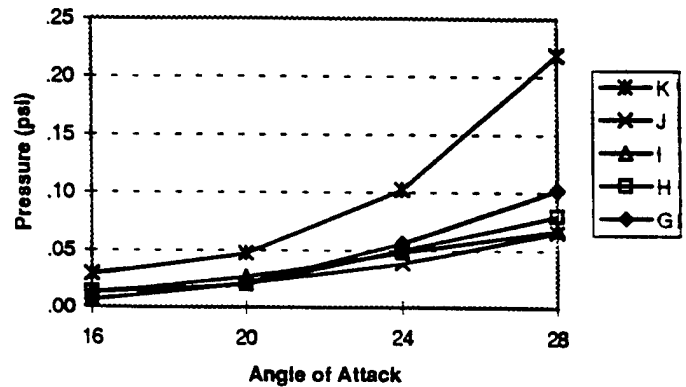
Rigid Tail:  $Q=56$  psf,  $\beta=0$   
65 psi blowing @ wing L.E.



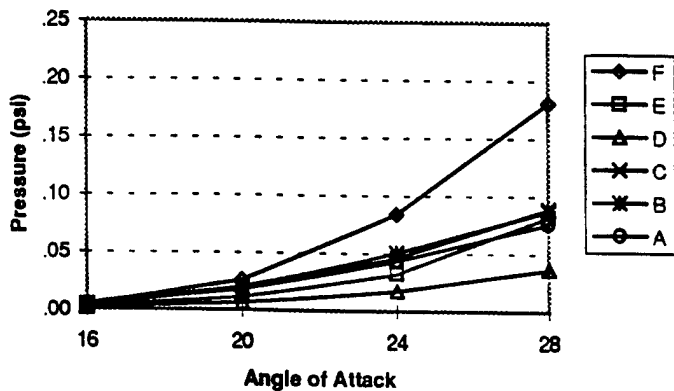
Flex Tail:  $Q=56$  psf,  $\beta=-4$   
65 psi blowing @ wing L.E.



Rigid Tail:  $Q=56$  psf,  $\beta=-4$   
65 psi blowing @ wing L.E.



Flex Tail:  $Q=56$  psf,  $\beta=4$   
65 psi blowing @ wing L.E.



Rigid Tail:  $Q=56$  psf,  $\beta=4$   
65 psi blowing @ wing L.E.

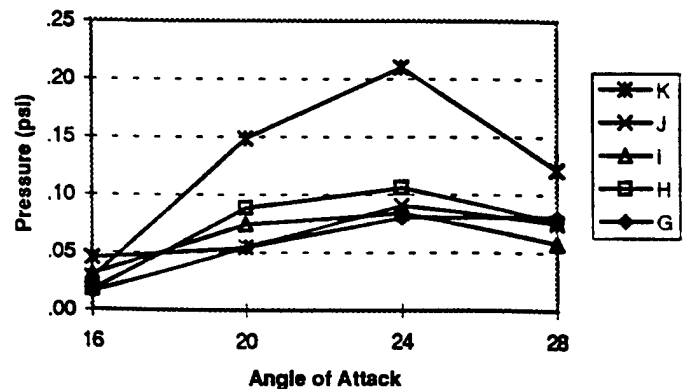
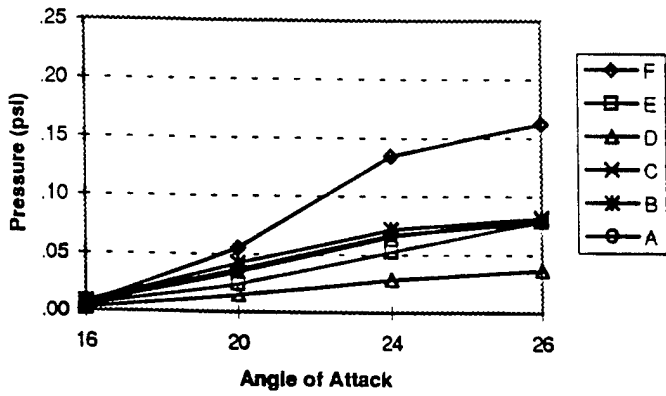


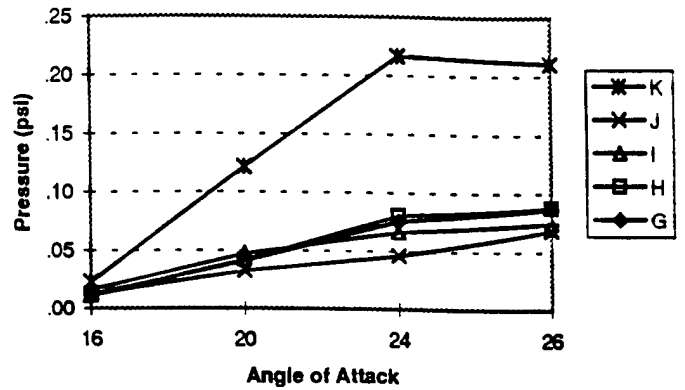
Fig 10. Measured Dynamic Pressure Distribution versus Angle of Attack

F-15 Vertical Tail Buffet Test

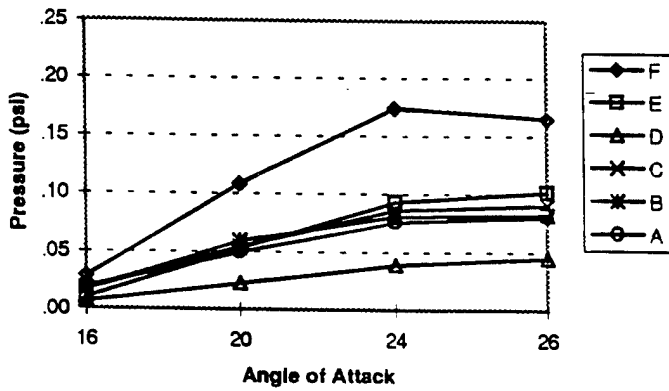
Flex Tail: Q=56 psf, Beta=0  
65 psi blowing @ gun only



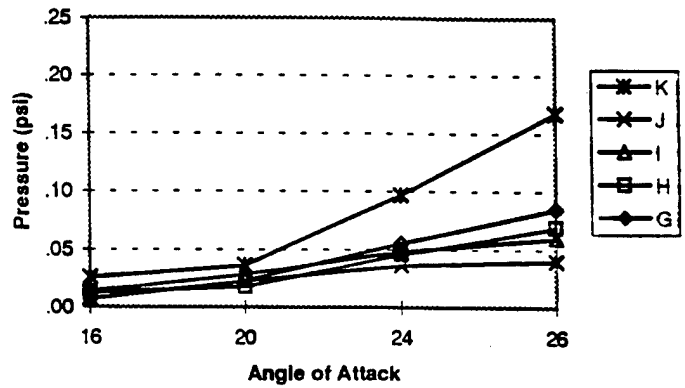
Rigid Tail: Q=56 psf, Beta=0  
65 psi blowing @ gun only



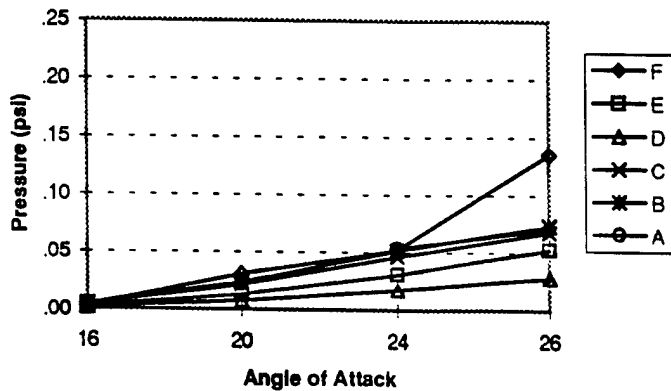
Flex Tail: Q=56 psf, Beta=-4  
65 psi blowing @ gun only



Rigid Tail: Q=56 psf, Beta=-4  
65 psi blowing @ gun only



Flex Tail: Q=56 psf, Beta=4  
65 psi blowing @ gun only



Rigid Tail: Q=56 psf, Beta=4  
65 psi blowing @ gun only

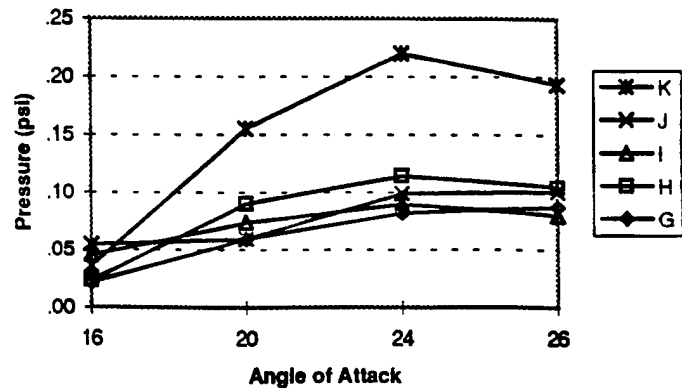


Fig 11. Measured Dynamic Pressure Distribution versus Angle of Attack

F-15 Vertical Tail Buffet Test

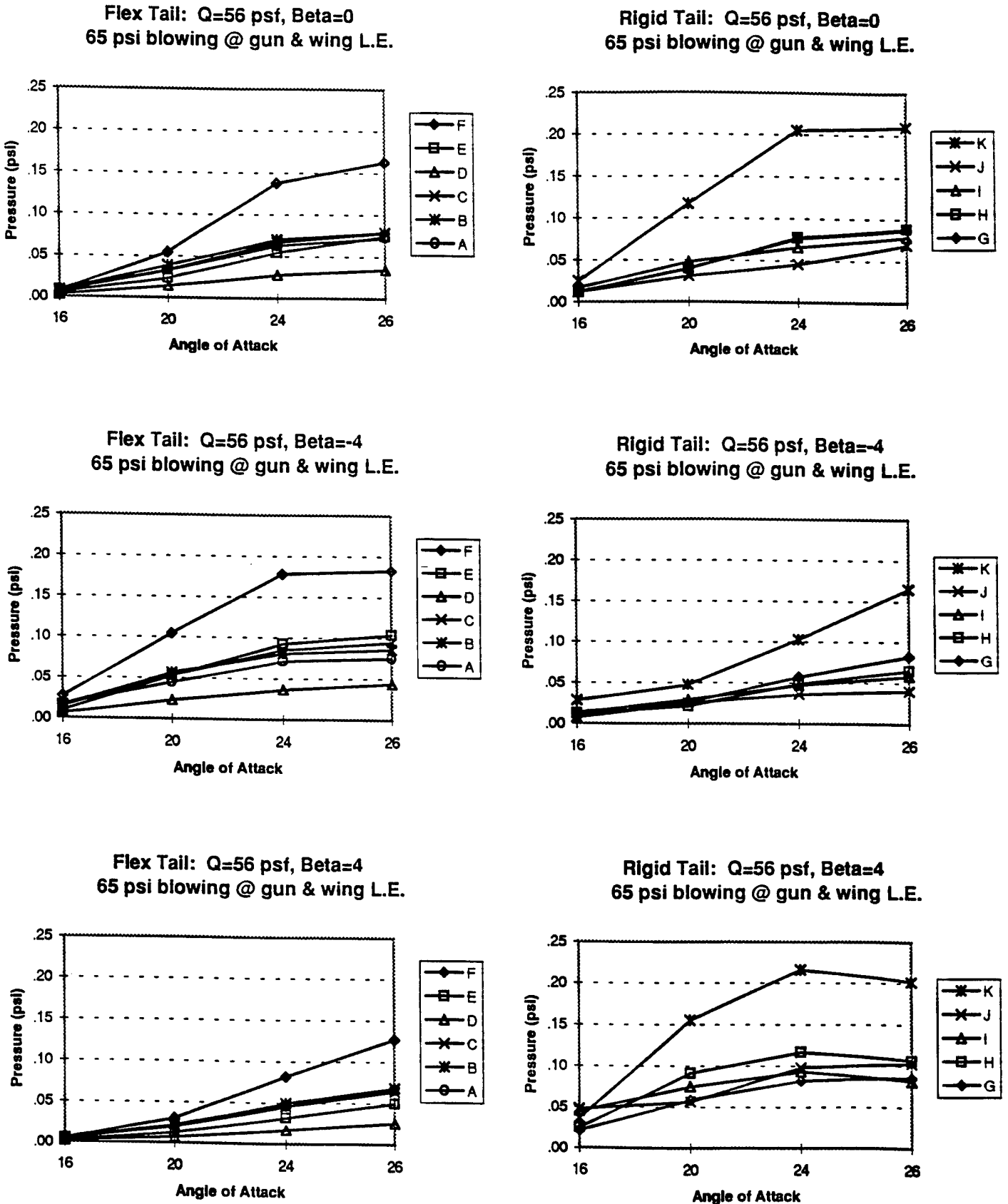
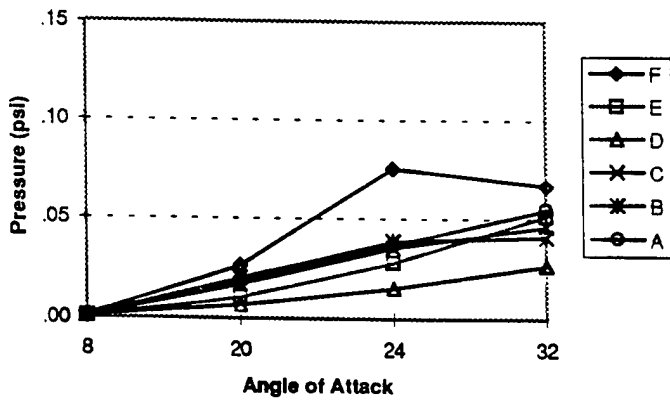


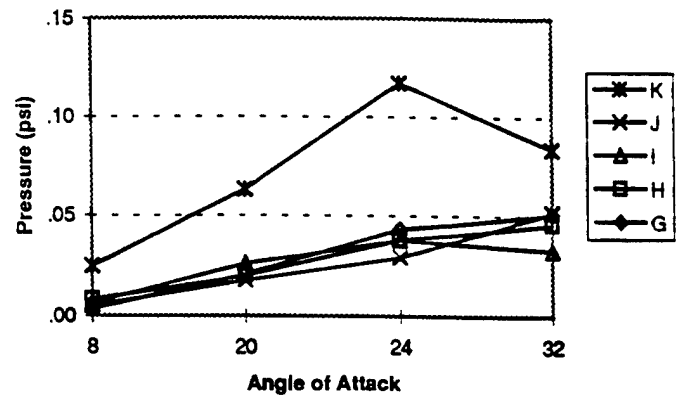
Fig 12. Measured Dynamic Pressure Distribution versus Angle of Attack

F-15 Vertical Tail Buffet Test

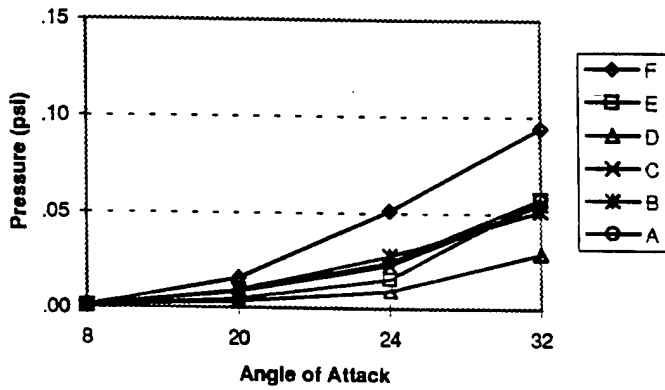
Flex Tail: Q=30 psf, Beta=0  
0 psi blowing @ wing L.E.



Rigid Tail: Q=30 psf, Beta=0  
0 psi blowing @ wing L.E.



Flex Tail: Q=30 psf, Beta=4  
0 psi blowing @ wing L.E.



Rigid Tail: Q=30 psf, Beta=4  
0 psi blowing @ wing L.E.

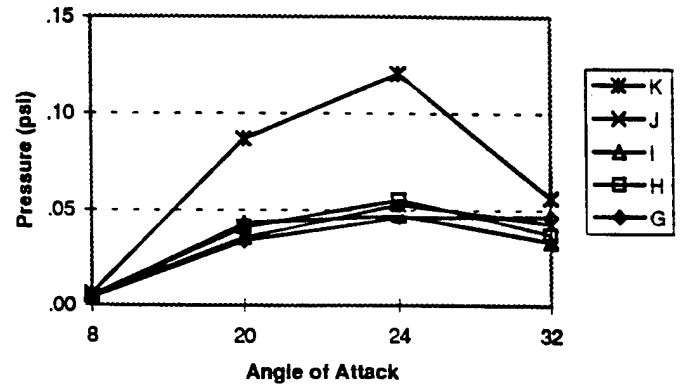
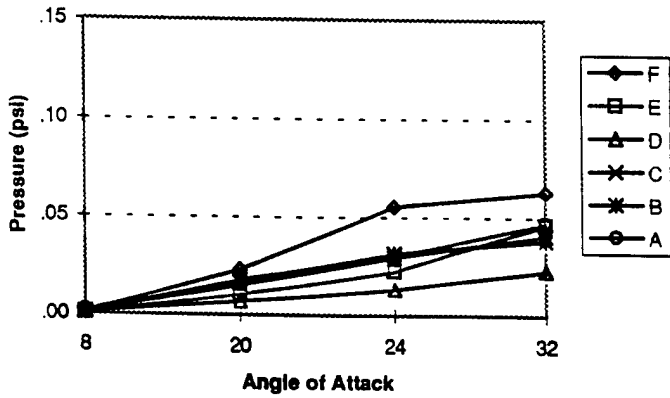


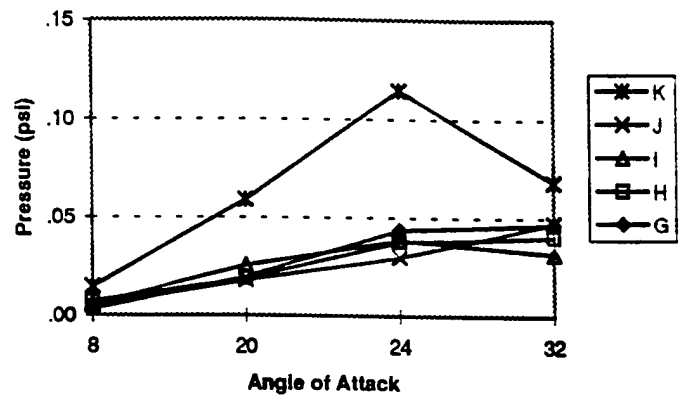
Fig 13. Measured Dynamic Pressure Distribution versus Angle of Attack

F-15 Vertical Tail Buffet Test

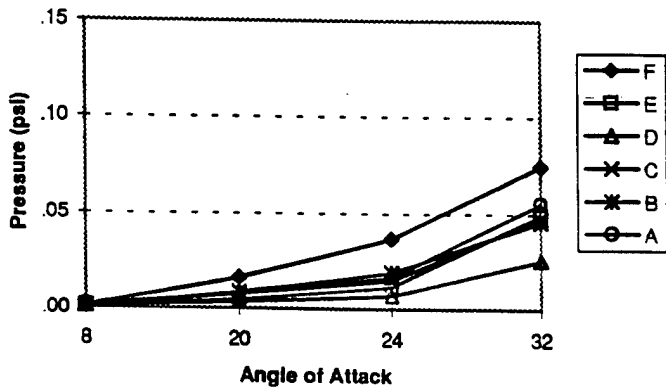
Flex Tail: Q=30 psf, Beta=0  
45 psi blowing @ wing L.E.



Rigid Tail: Q=30 psf, Beta=0  
45 psi blowing @ wing L.E.



Flex Tail: Q=30 psf, Beta=4  
45 psi blowing @ wing L.E.



Rigid Tail: Q=30 psf, Beta=4  
45 psi blowing @ wing L.E.

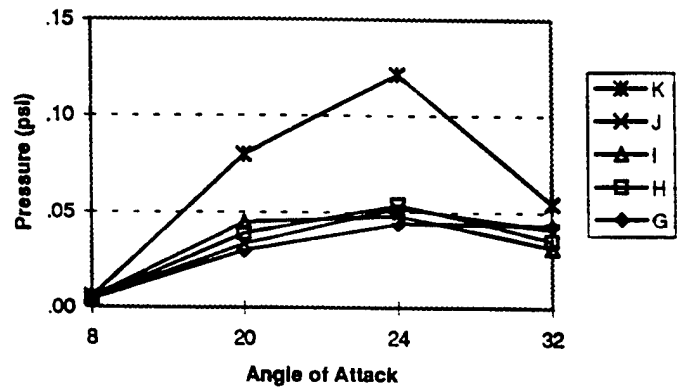


Fig 14. Measured Dynamic Pressure Distribution versus Angle of Attack



Fig 15. Photograph of Vortices Impinging on the Tail during Wind Tunnel Testing

# F-15 VERTICAL TAIL BUFFET DATA

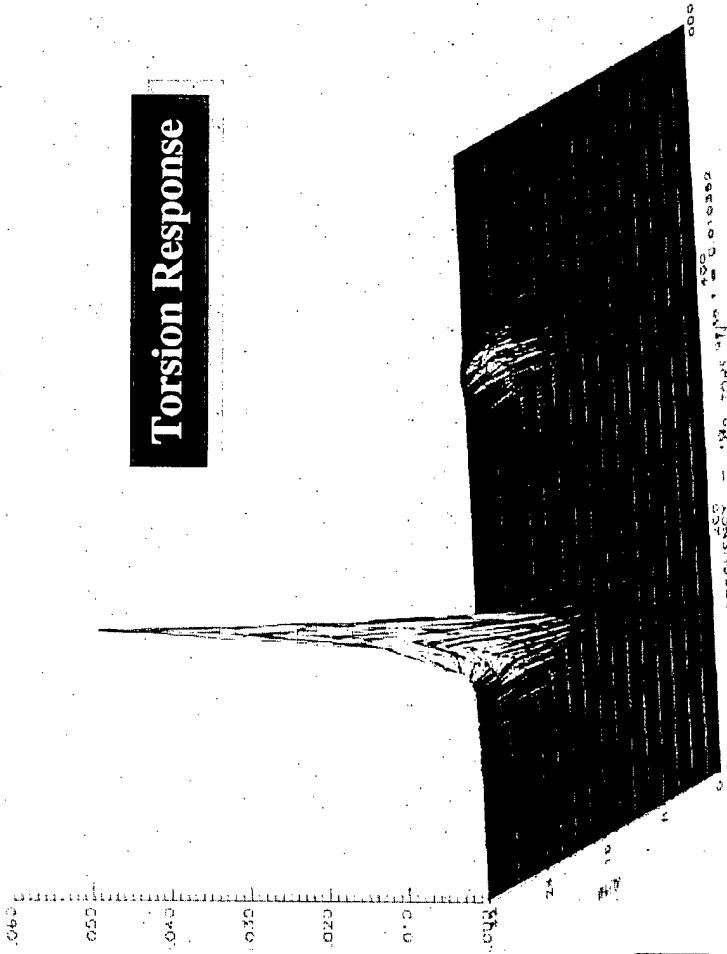
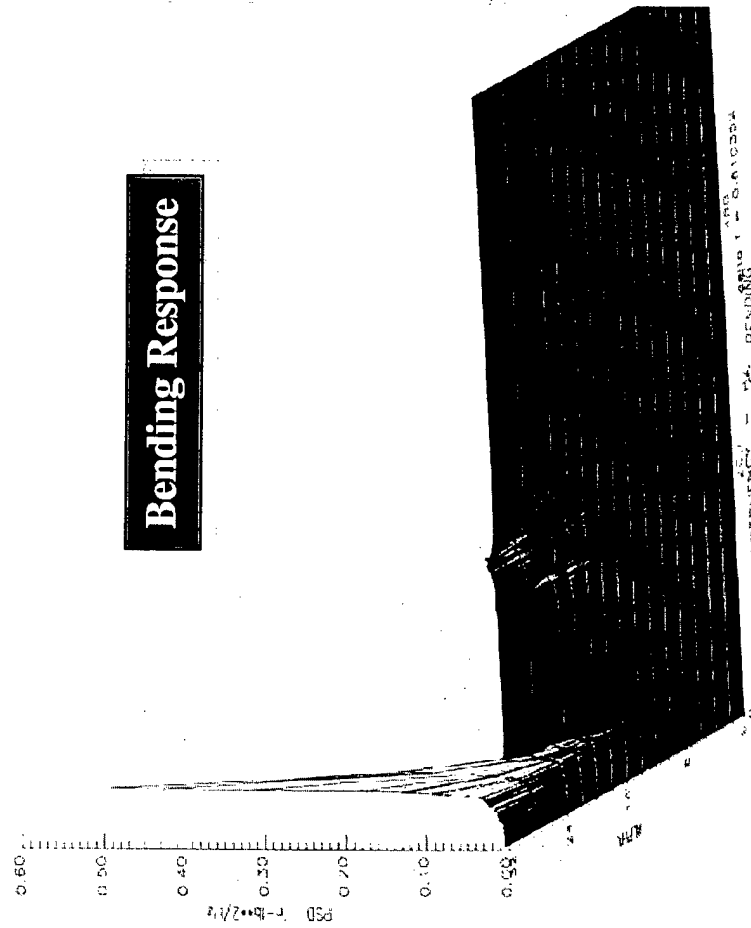


Fig 16. F-15 Vertical Tail Buffet Data

Sketch of vertical tail FEM showing nodal patterns

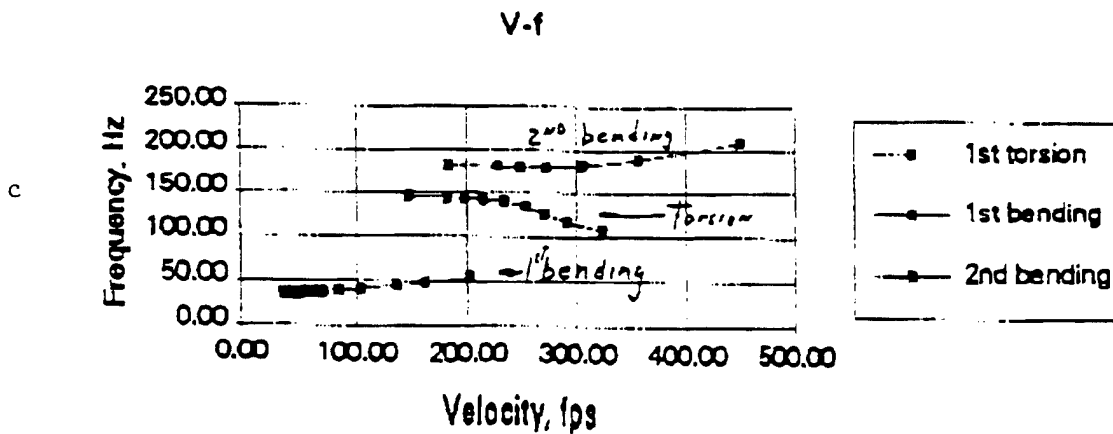
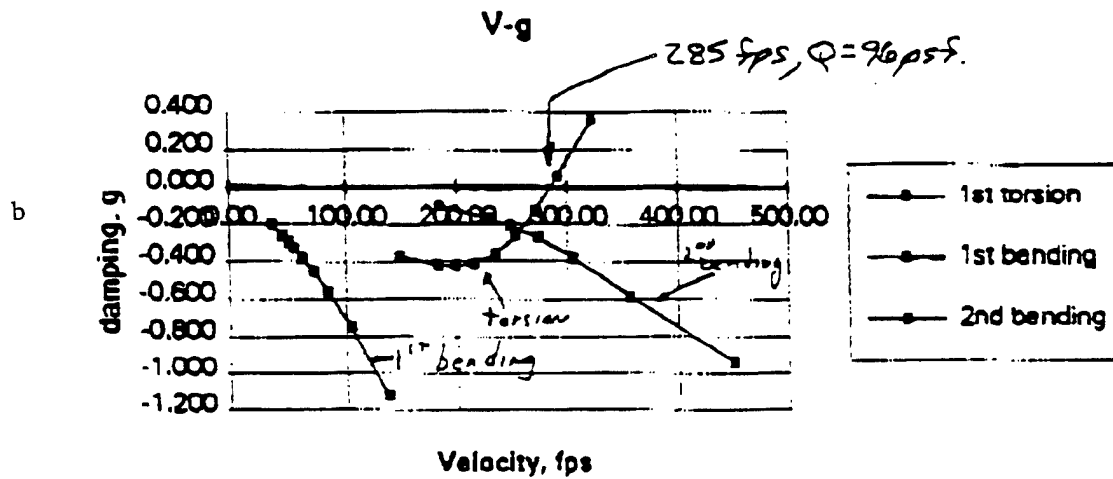
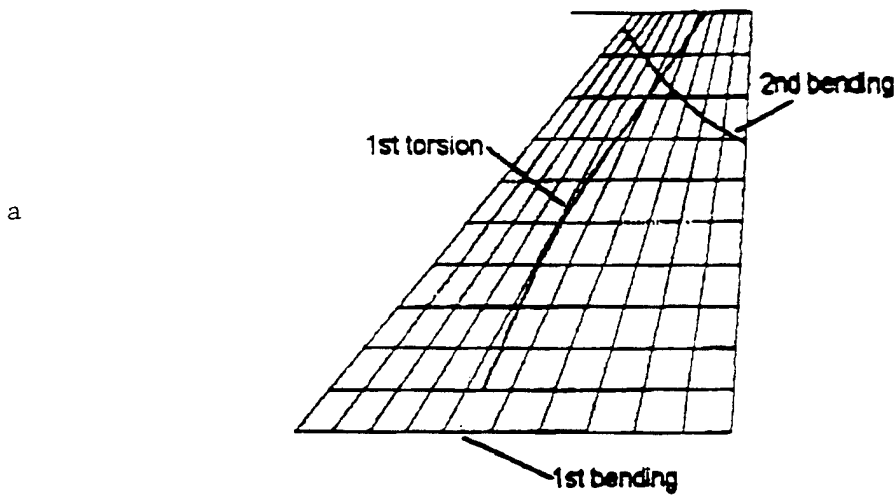


Fig 17. a) Sketch of Vertical Tail Showing Modal Pattern, b) Damping versus Velocity for the First Three Modes, c) Frequency versus Velocity for the First Three Modes



# Response of Bending Mode versus Angle of Attack

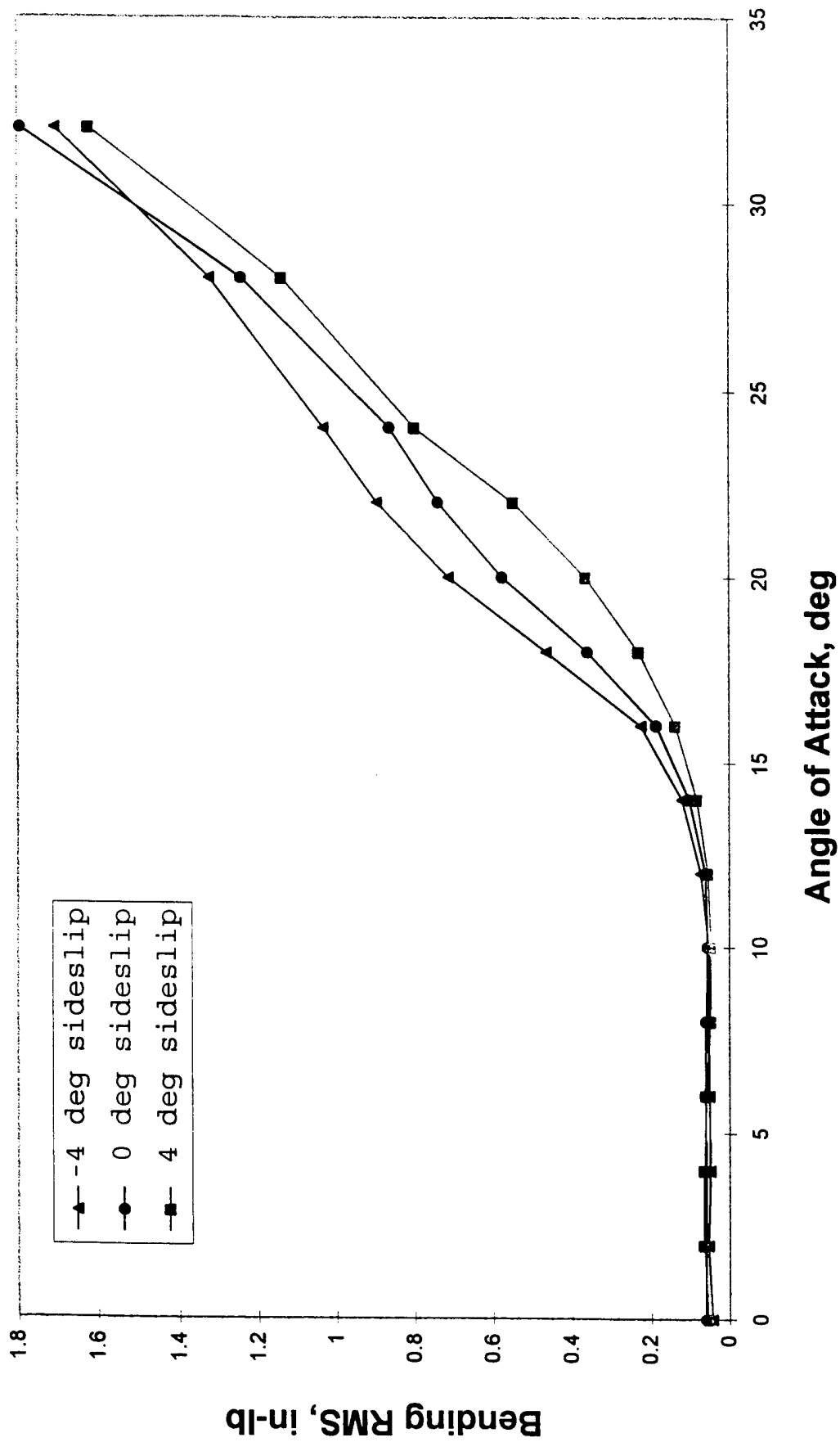


Fig 18. Response of Bending Mode versus Angle of Attack

# Response of Torsion Mode versus Angle of Attack

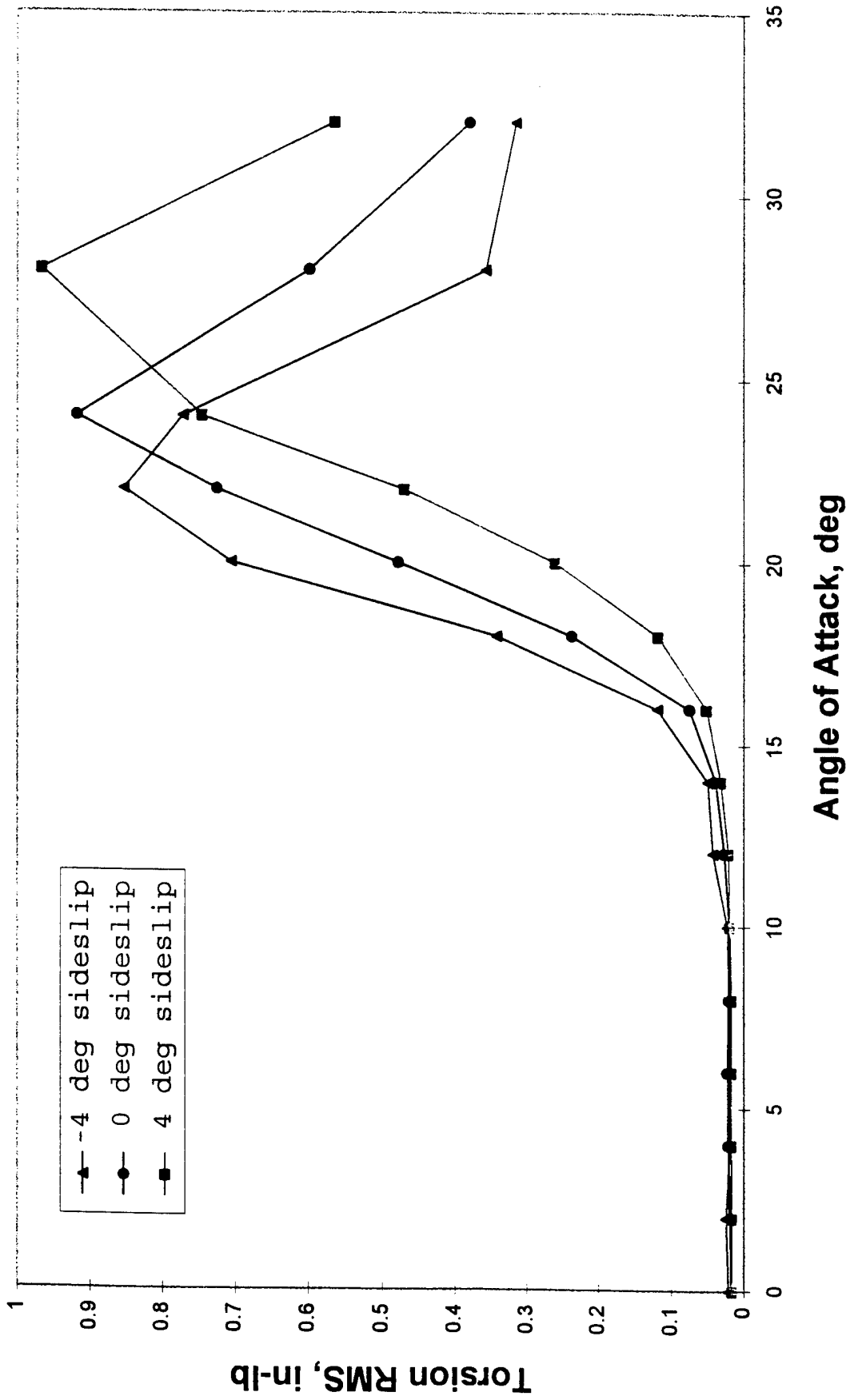


Fig 19. Response of Torsion Mode versus Angle of Attack

# Response of Bending Mode for Various Levels of Blowing

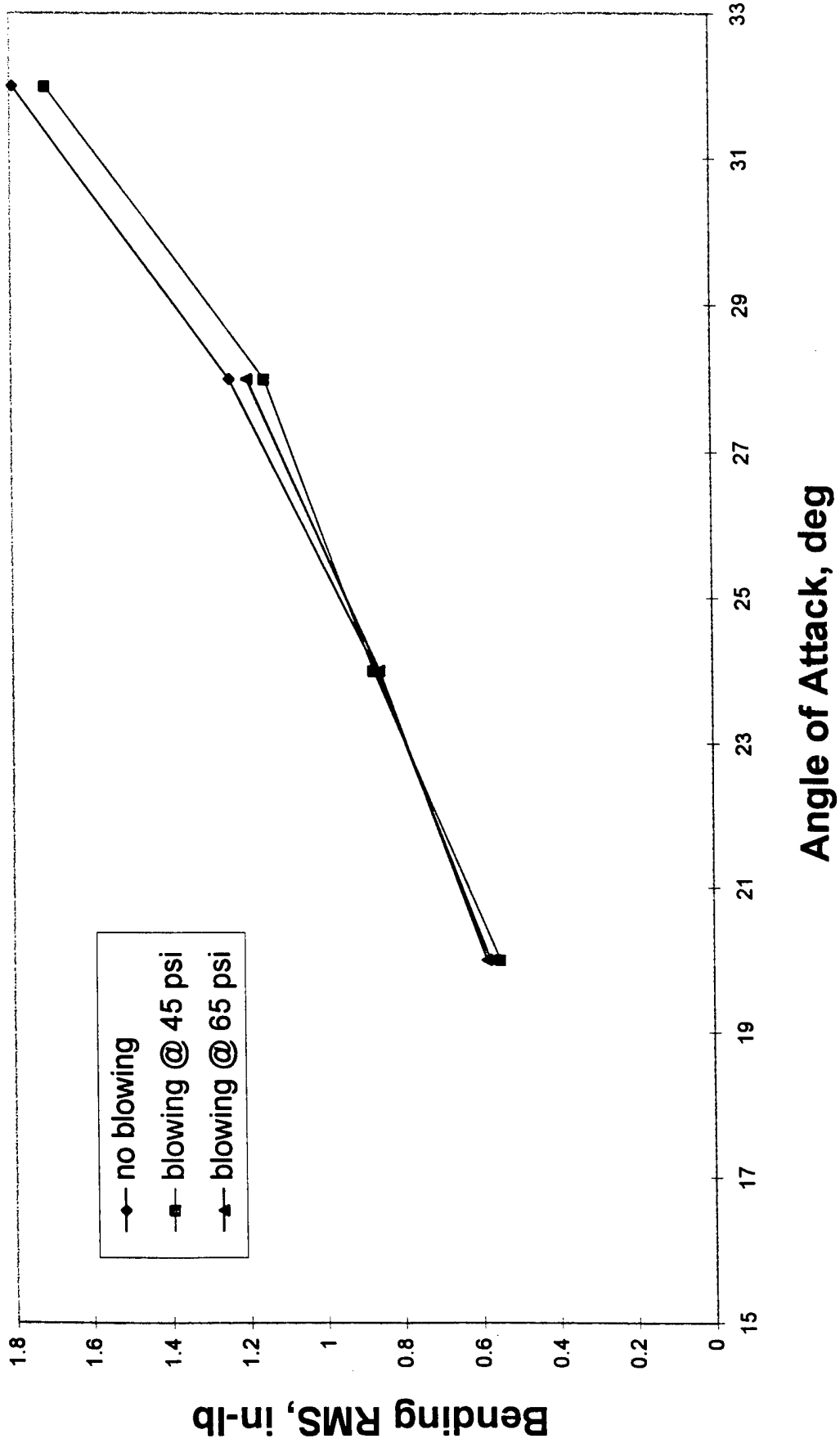


Fig 20. Response of Bending Mode for Various Levels of Blowing

# Response of Torsion Mode for Various Levels of Blowing

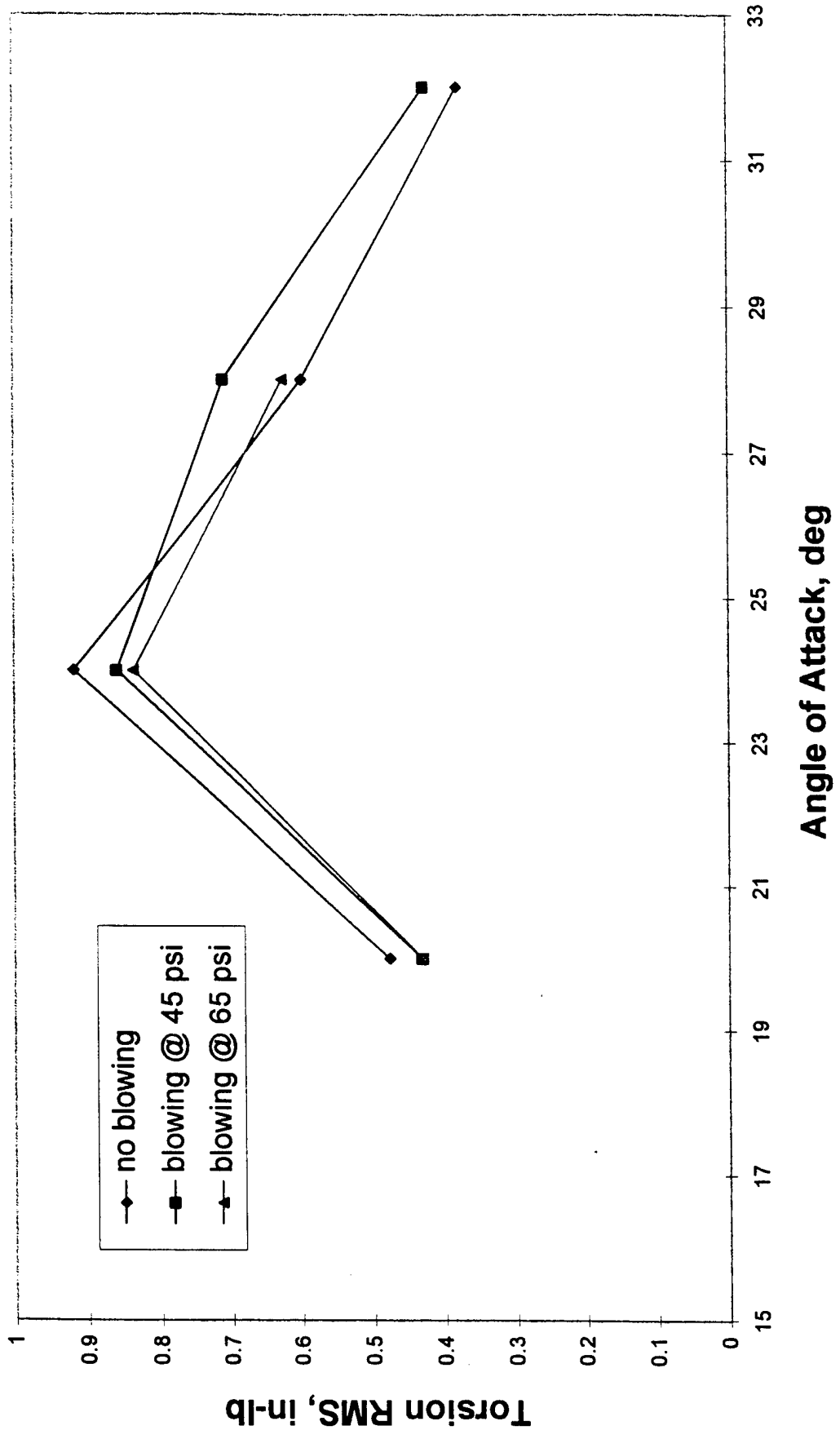


Fig 21. Response of Torsion Mode for Various Levels of Blowing

1st Bending Actuators

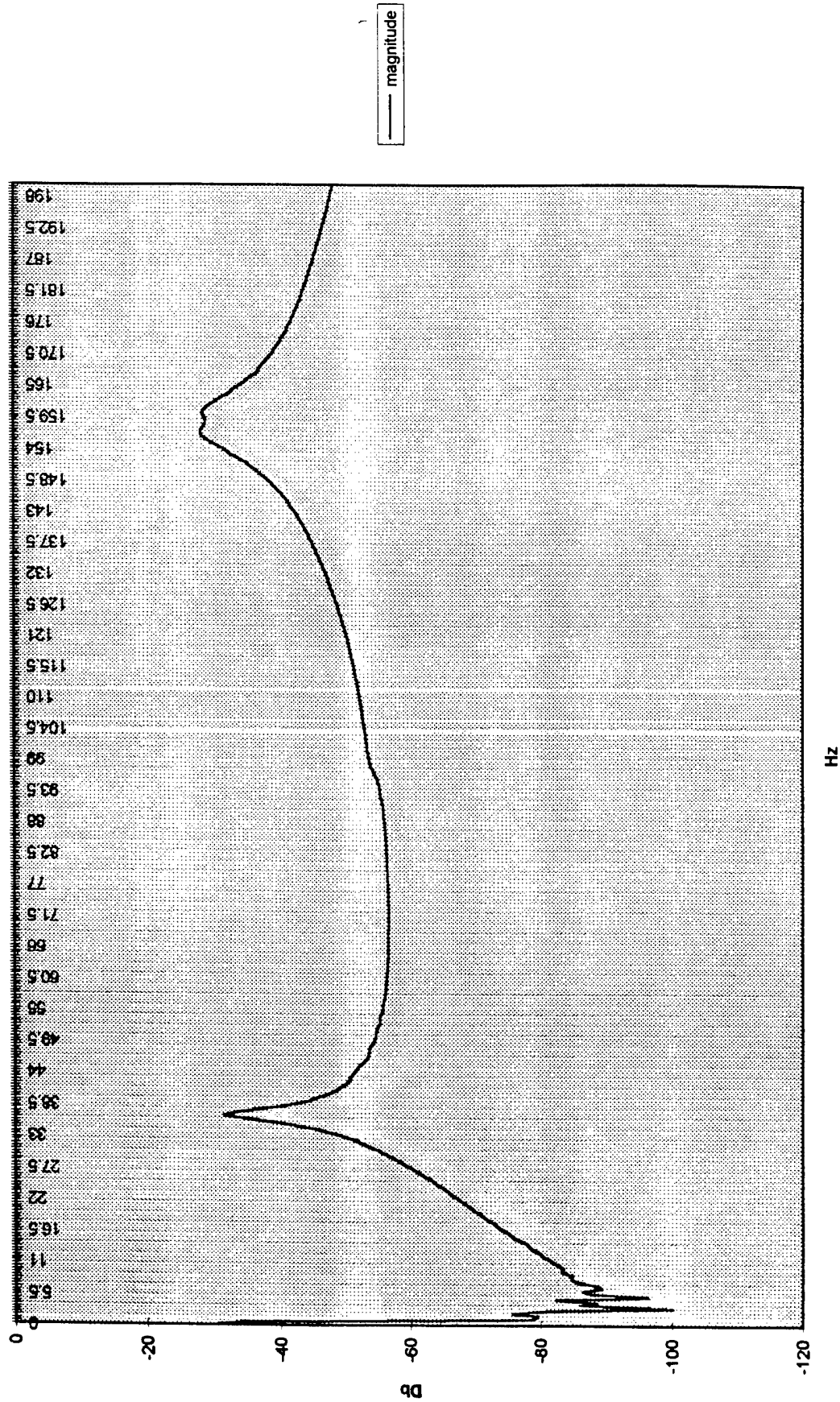


Fig 22. Structural Response due to First Bending Actuators

2nd Bending Actuators

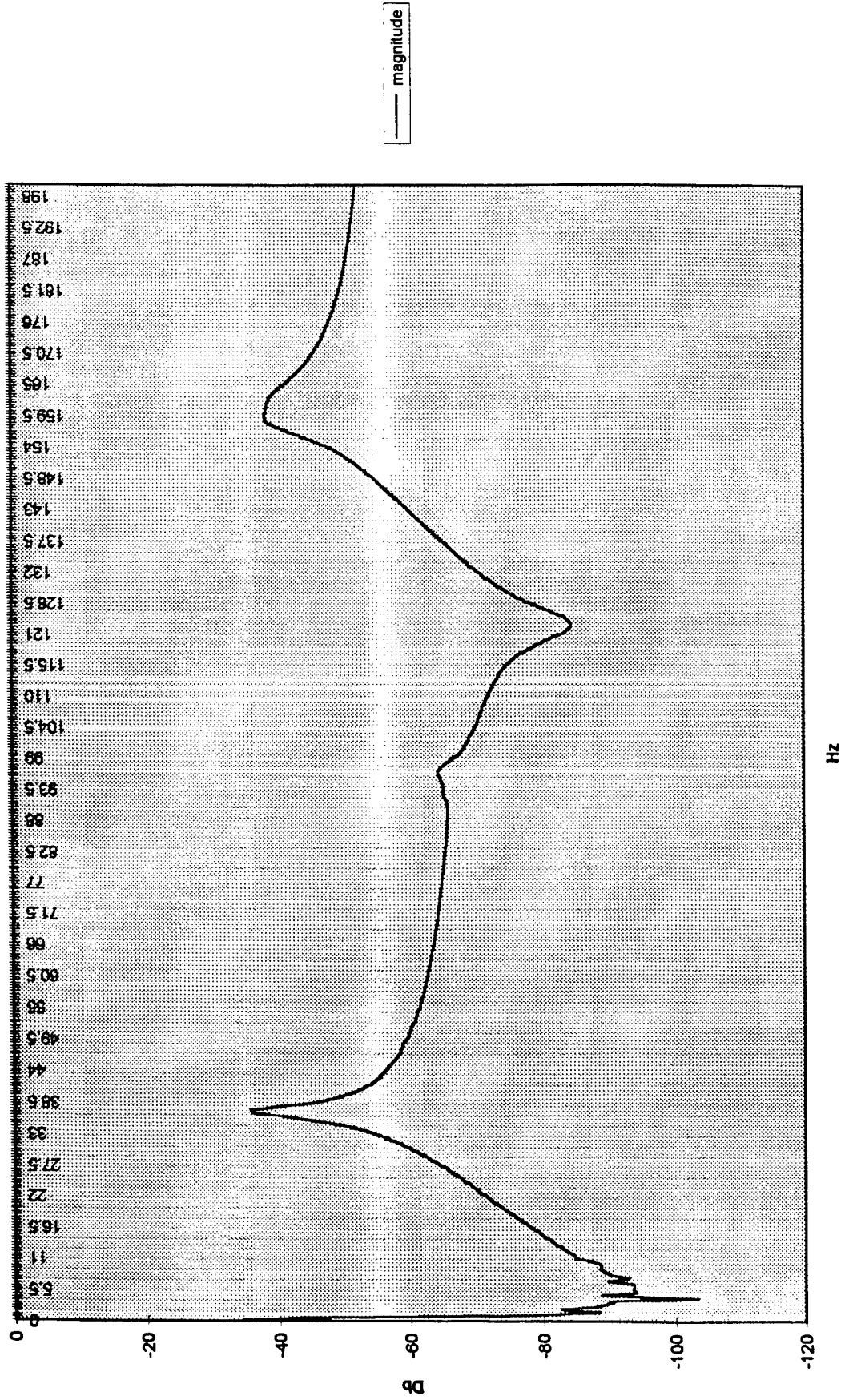


Fig 23. Structural Response due to Second Bending Actuators

1st Bending & 2nd Bending Actuators II

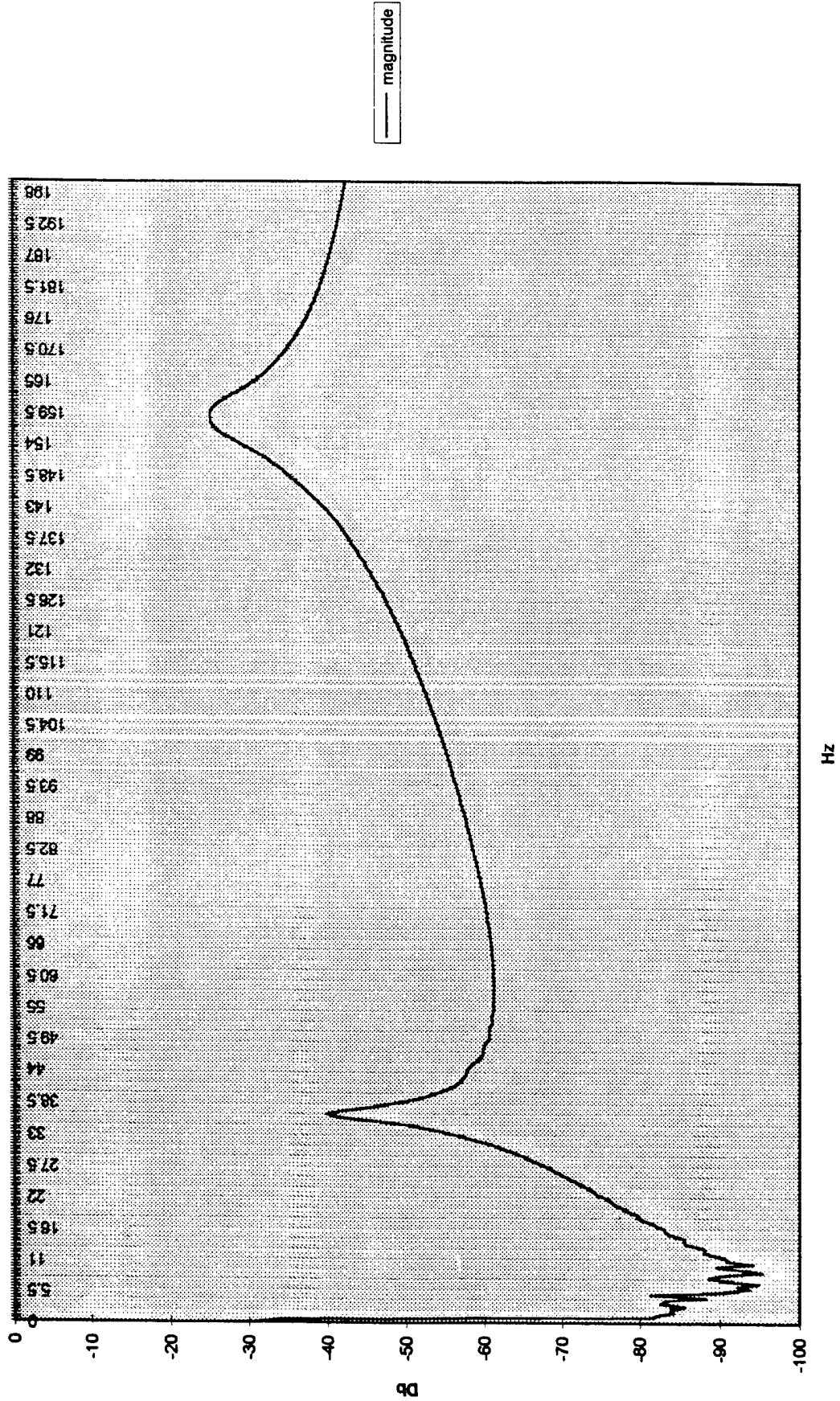


Fig 24. Structural Response due to First and Second Bending Actuators

1st Torsion Actuators

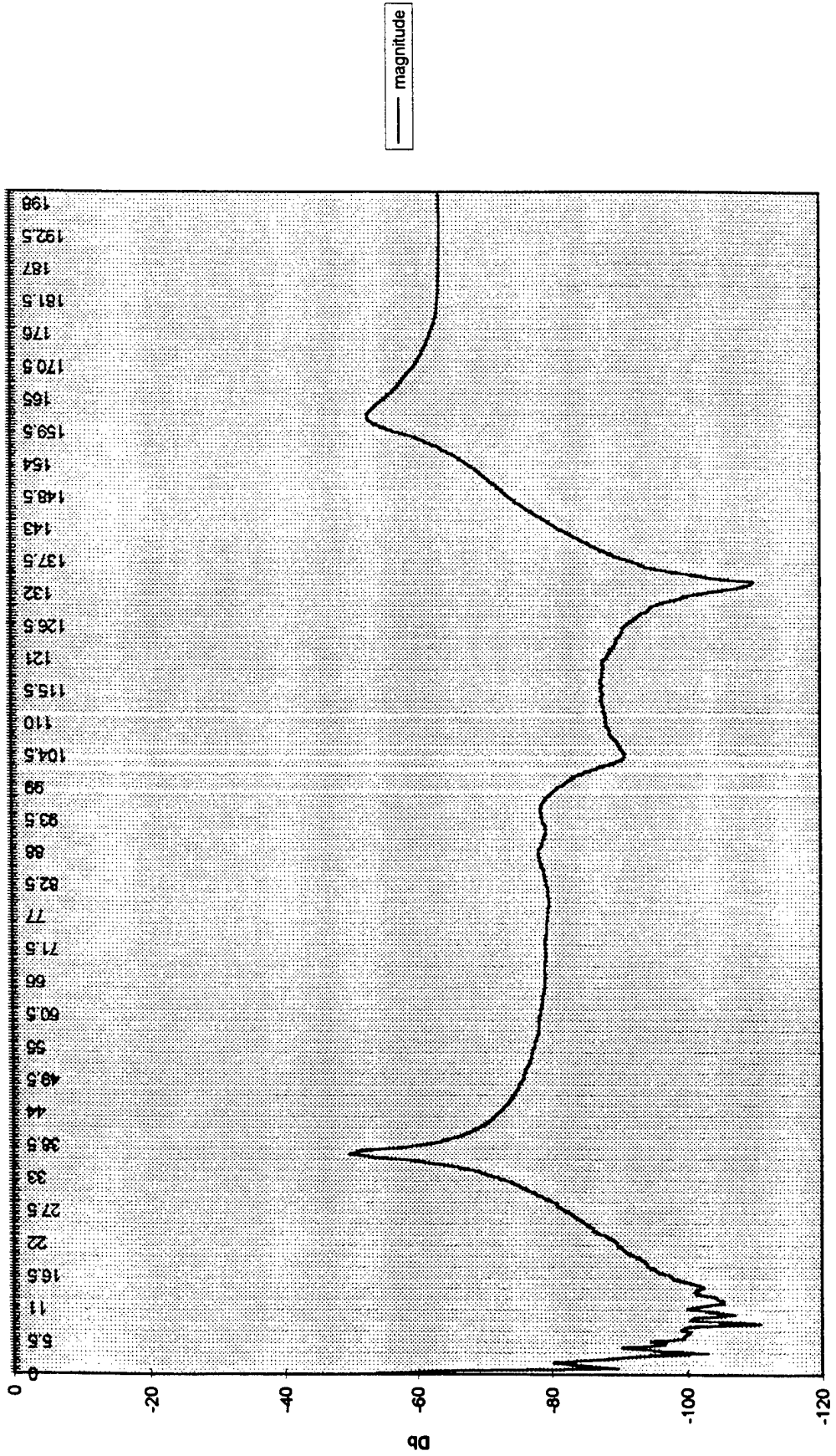
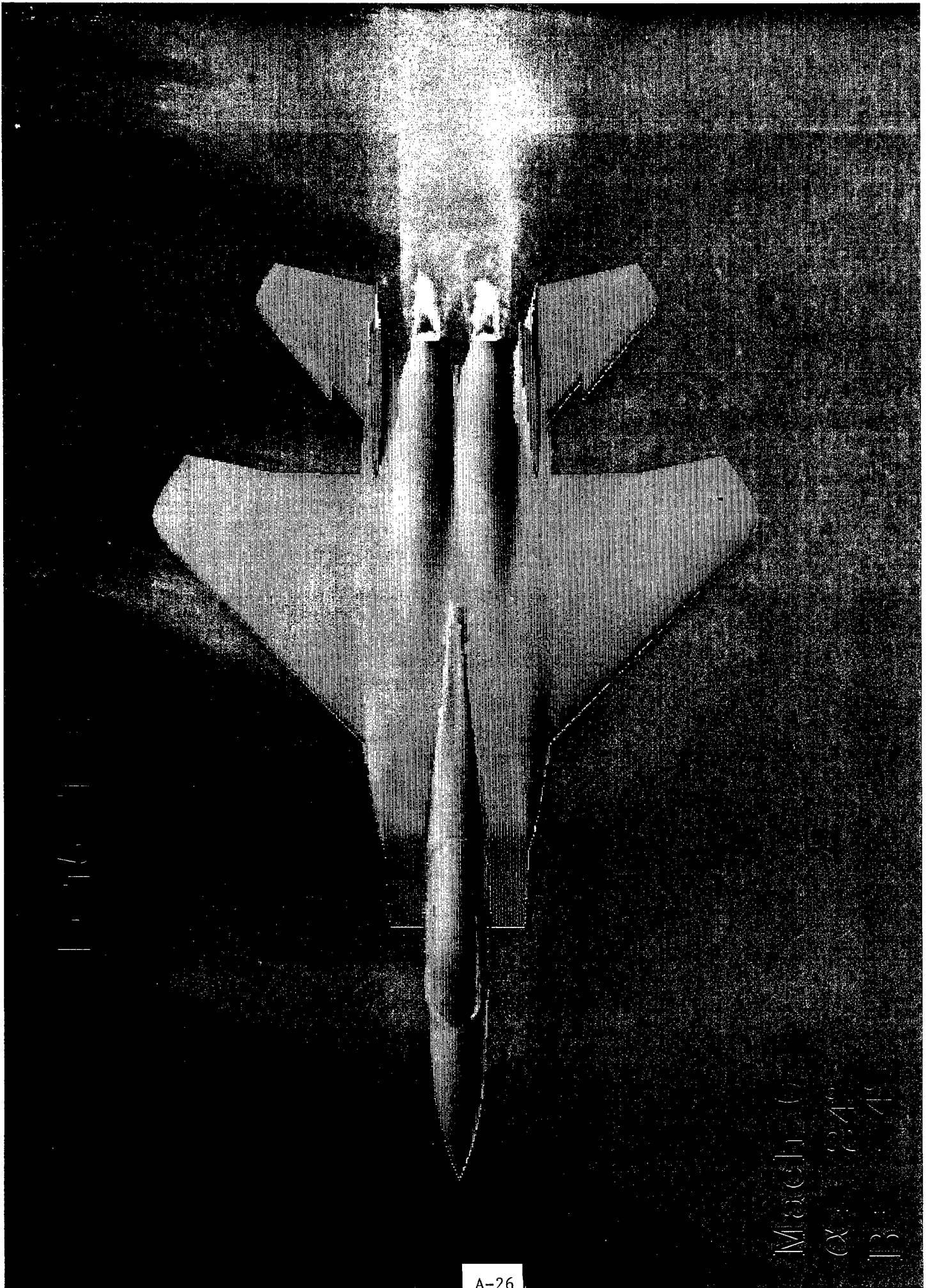


Fig 25. Structural Response due to First Torsion Actuators





Mach 0.84  
 $\alpha = 24^\circ$   
B-1

A-26

Fig 26. F-15 Tail Buffet Study

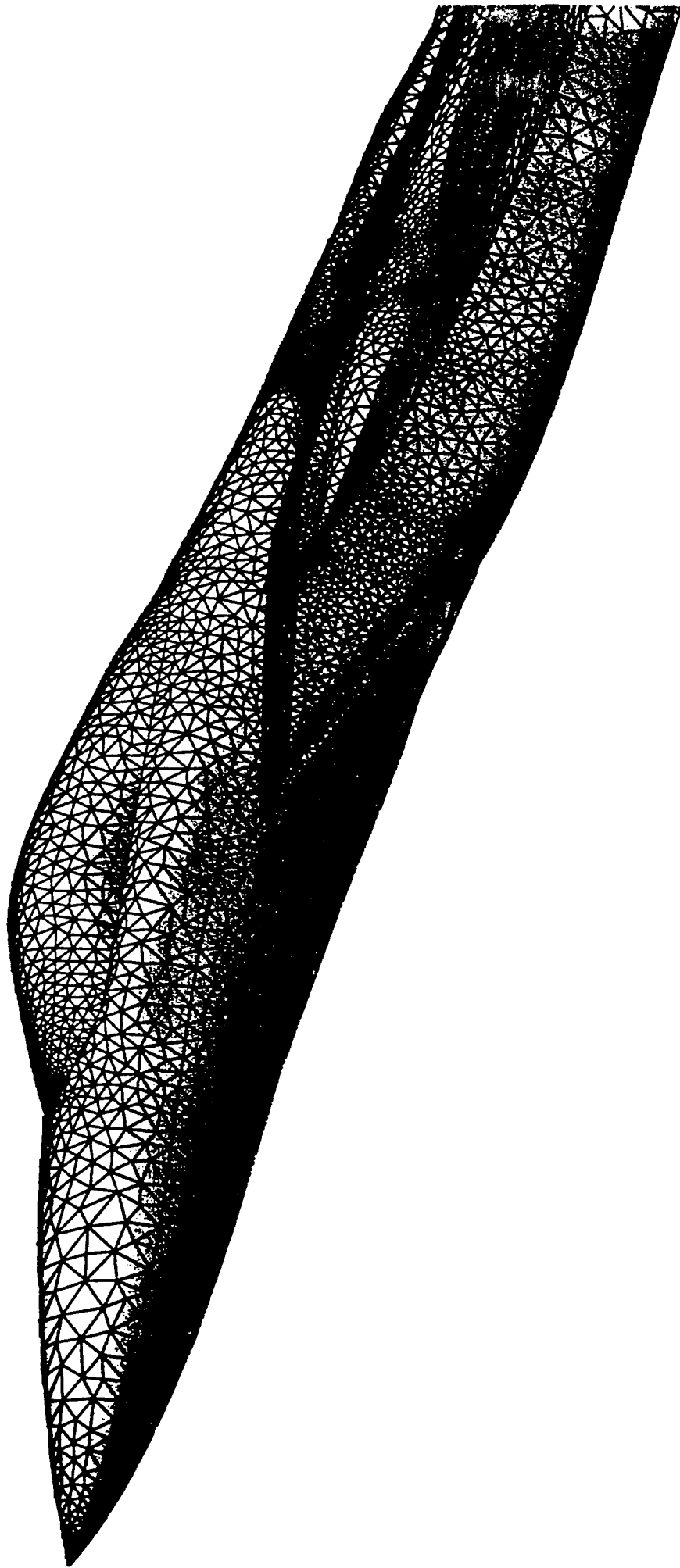


Fig 27. Unstructured Grid Using the Tetmesh Grid Generator

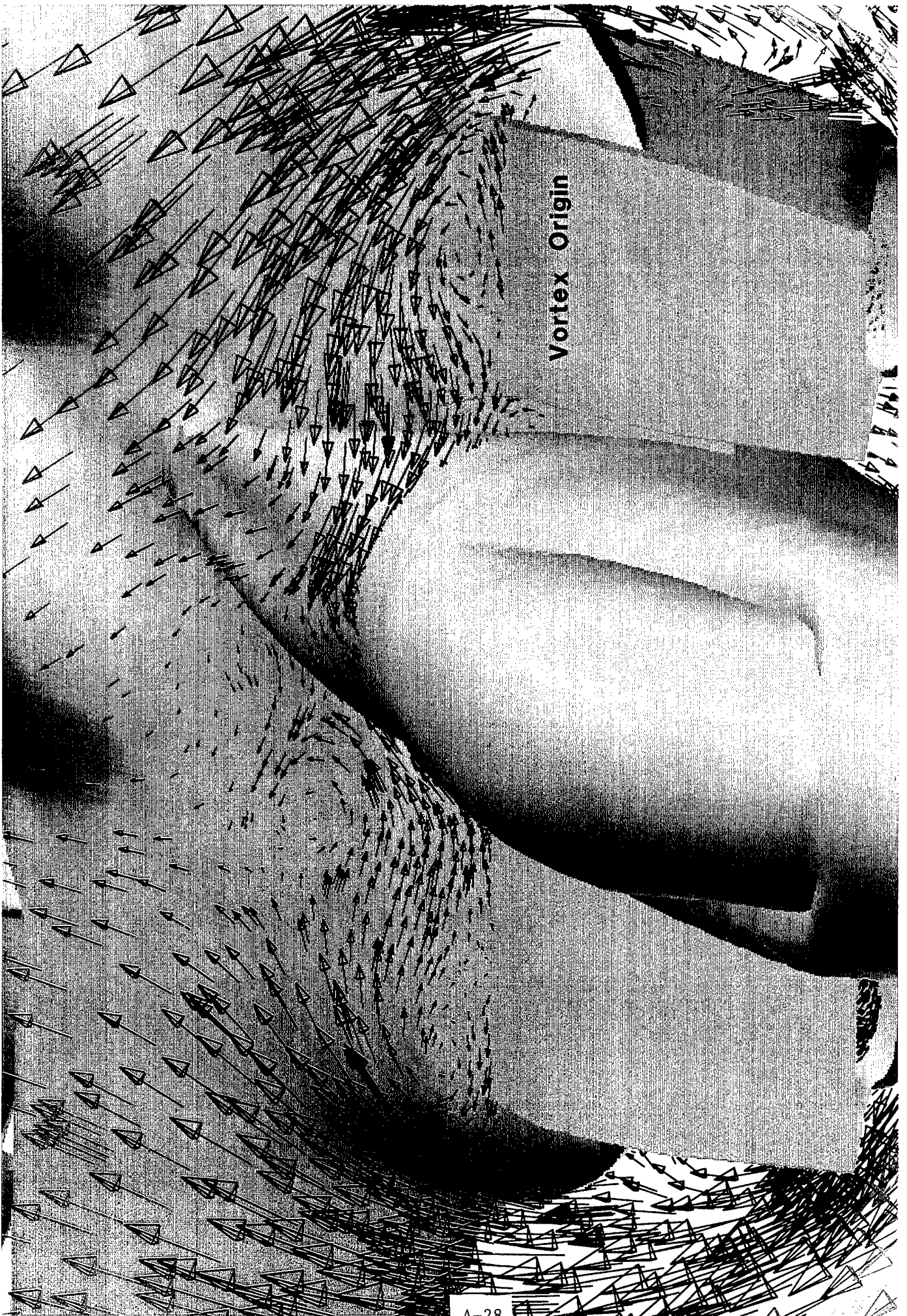


Fig 28. Flow Sweeping over the Gun Bump Fairing

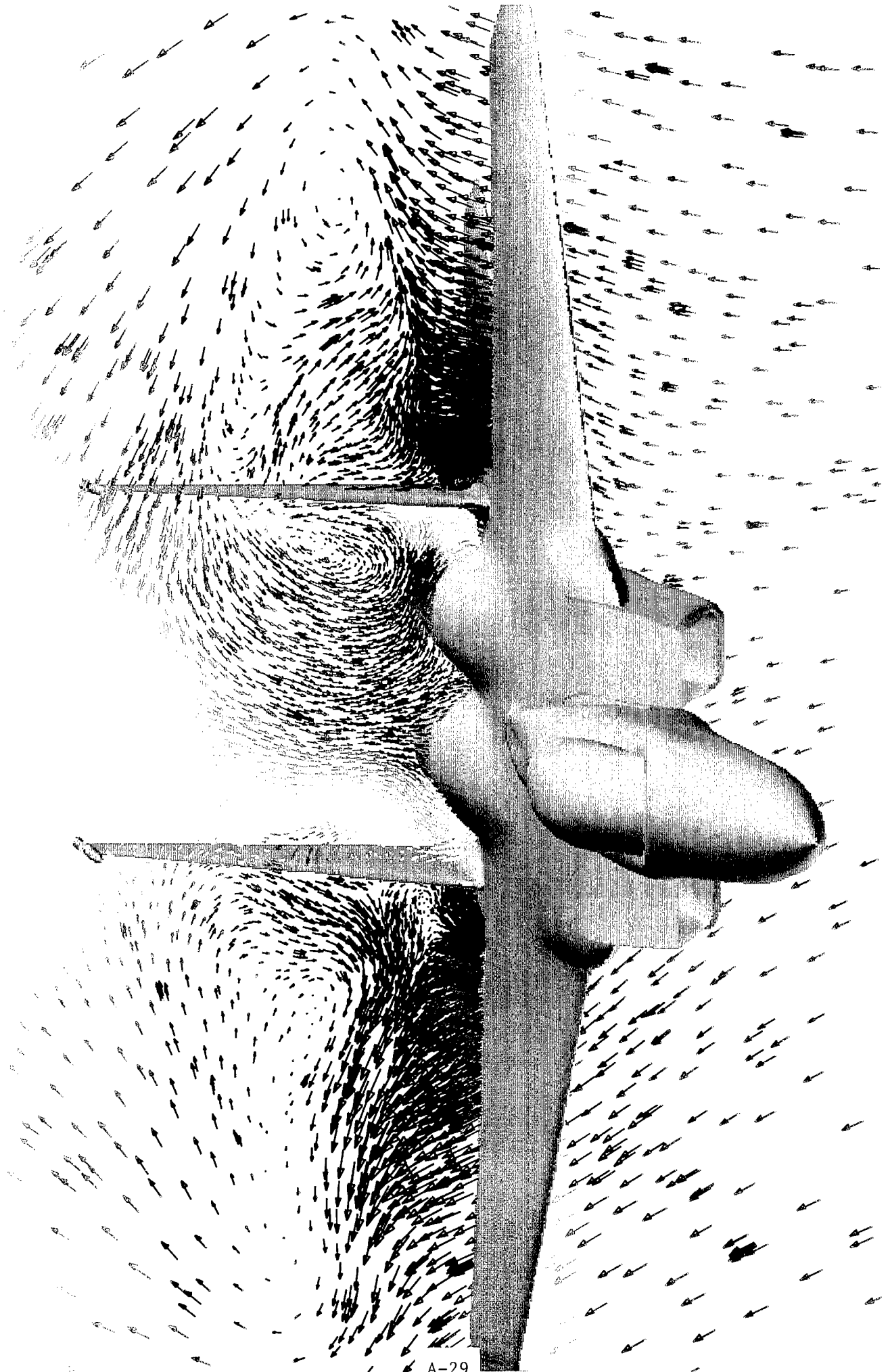


Fig 29. Vortical Flow Outside the Vertical Tails

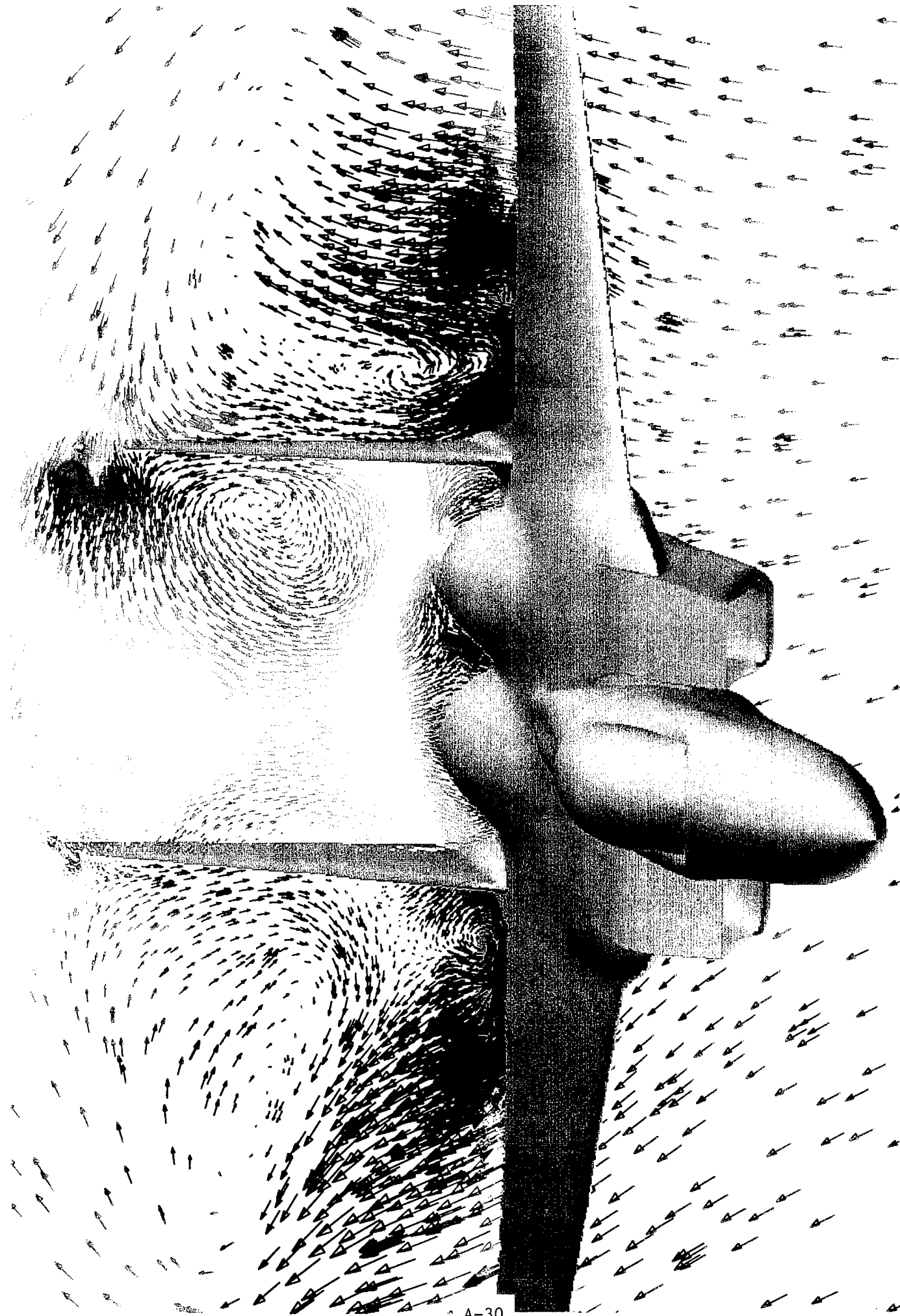


Fig 30. Vortical Flow Impacting the Vertical Tails



Fig 31. Streamline Traces from the Inlet and Wing's Leading Edge

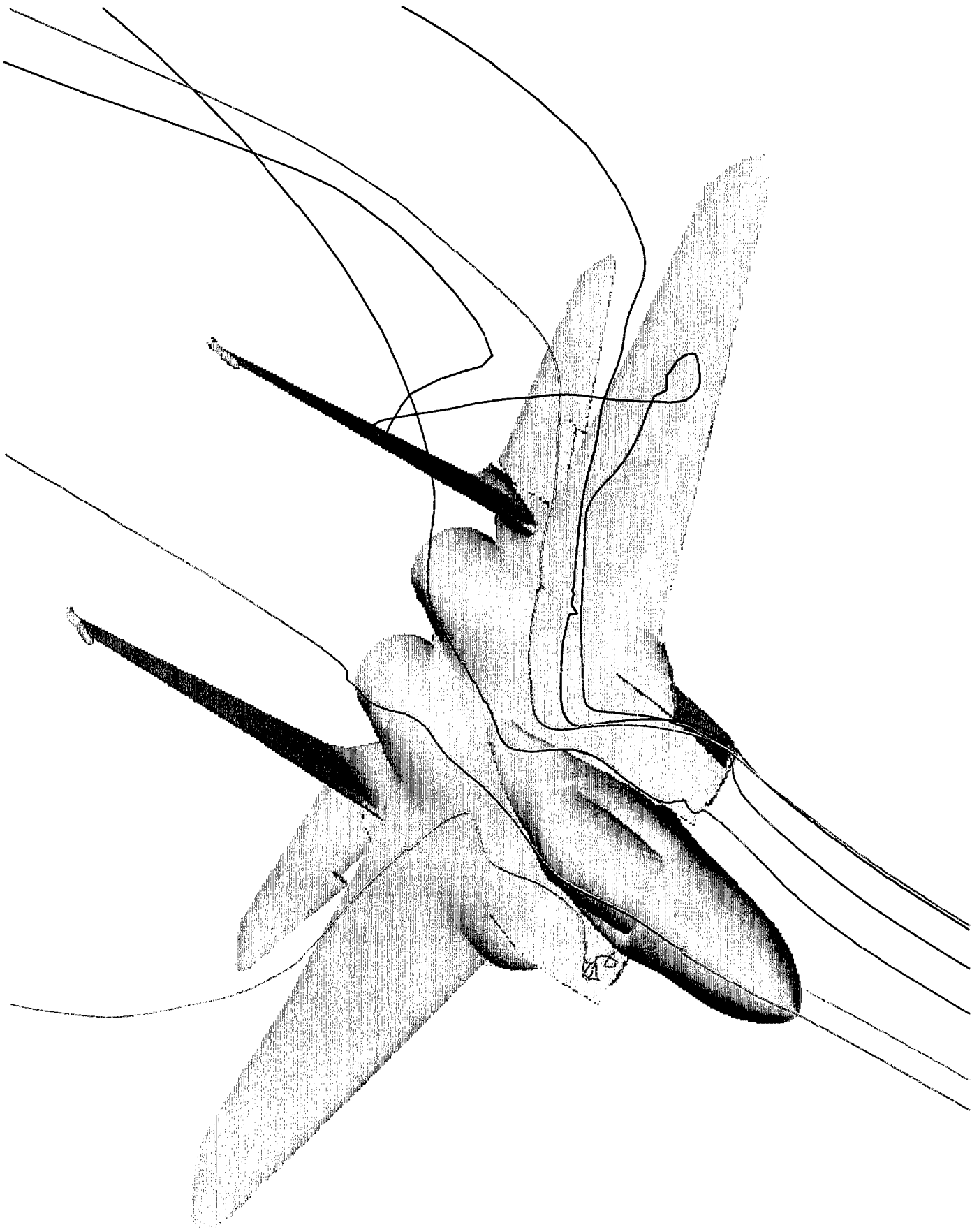
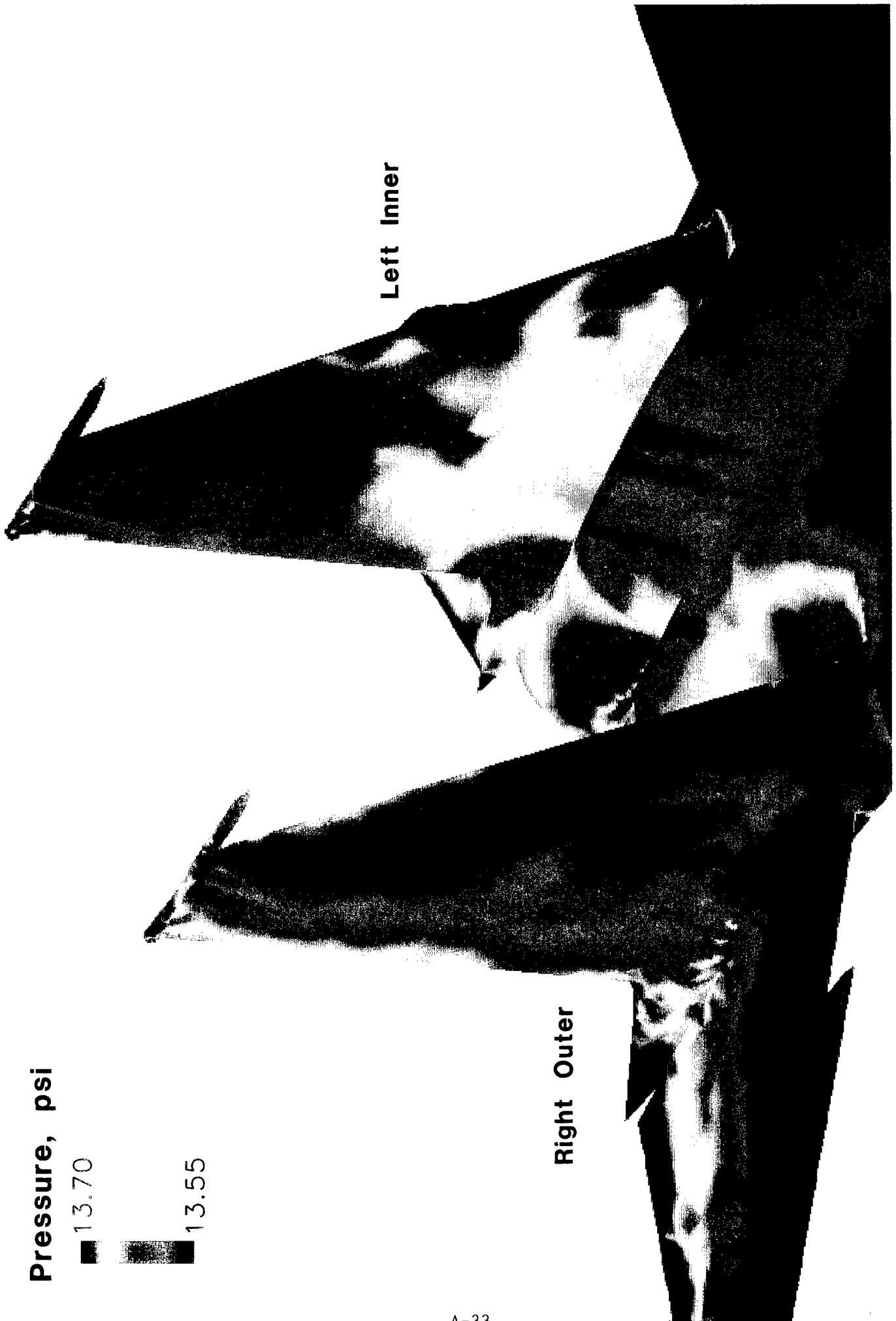


Fig 32. Streamline Traces from the Inlet and Wing Top

**Pressure, psi**

13.70

13.55



**Left Inner**

**Right Outer**

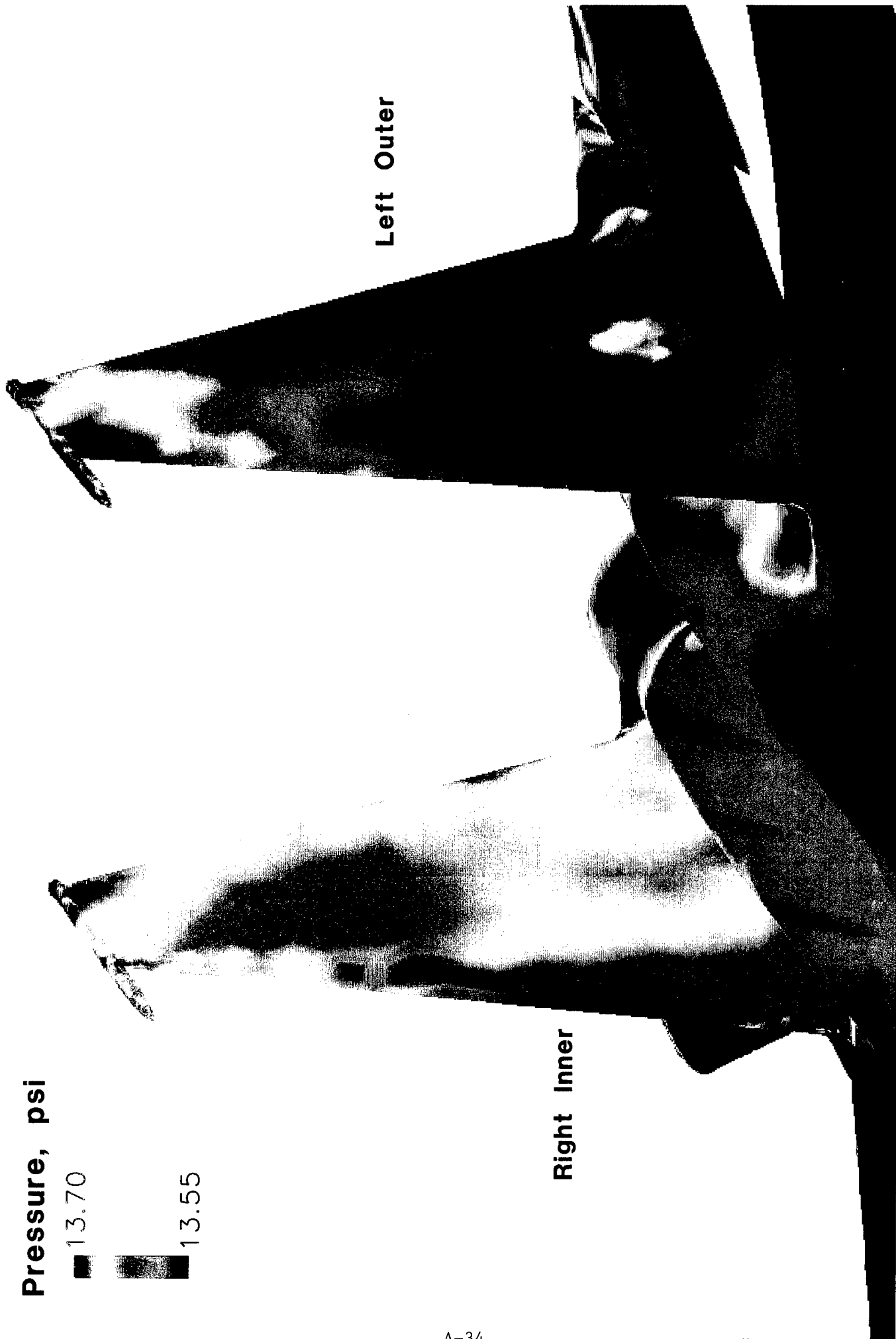
Fig 33. Pressure on Vertical Tails from Aircraft Right



**Pressure, psi**

■ 13.70

■ 13.55



**Left Outer**

**Right Inner**

Fig 34. Pressure on Vertical Tails from Aircraft Left

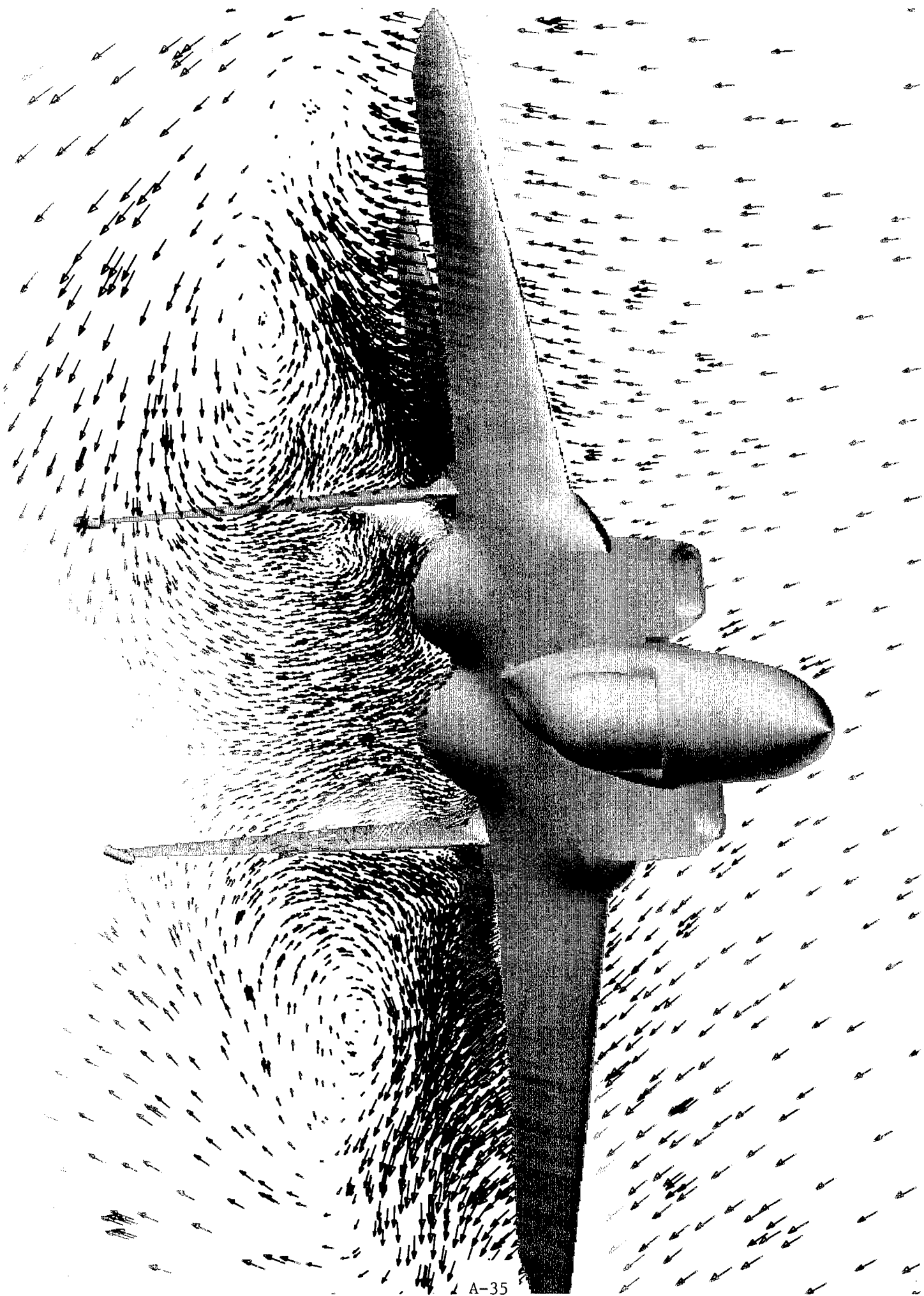
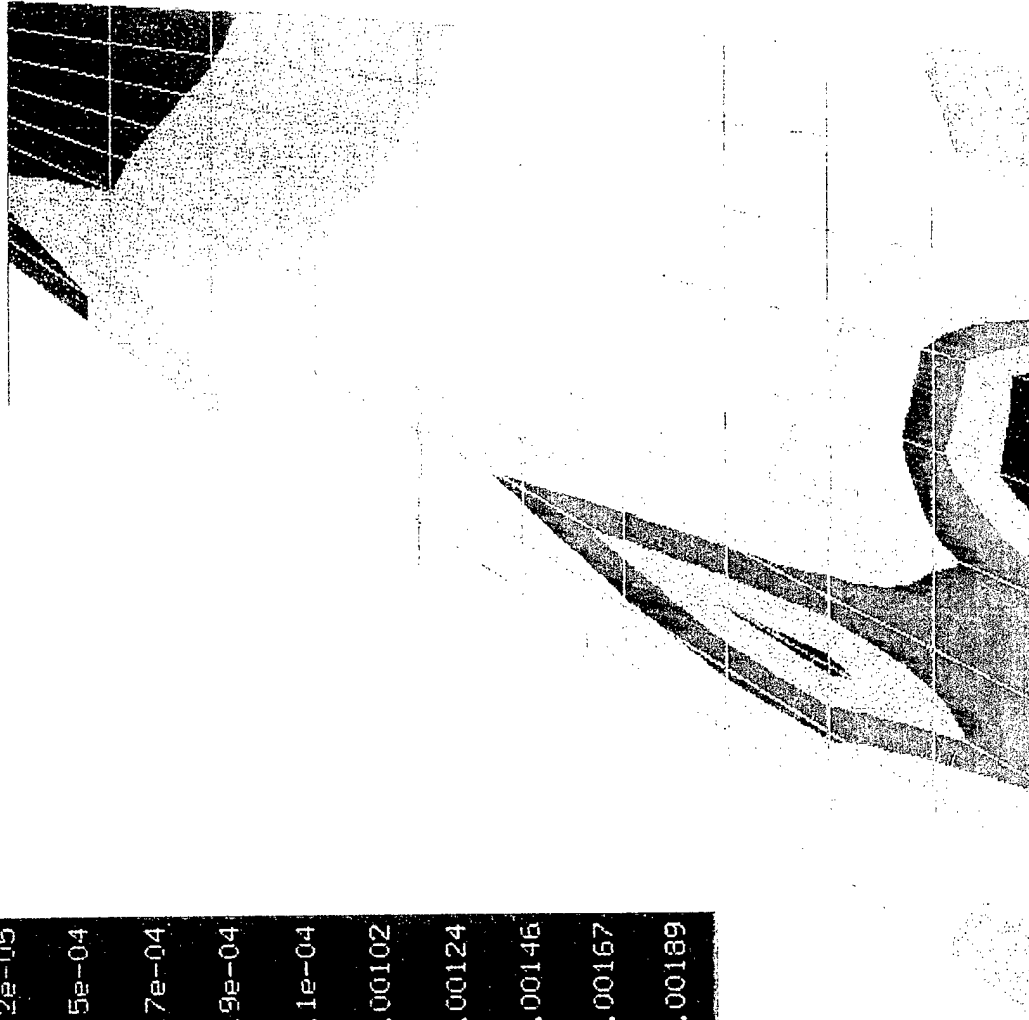
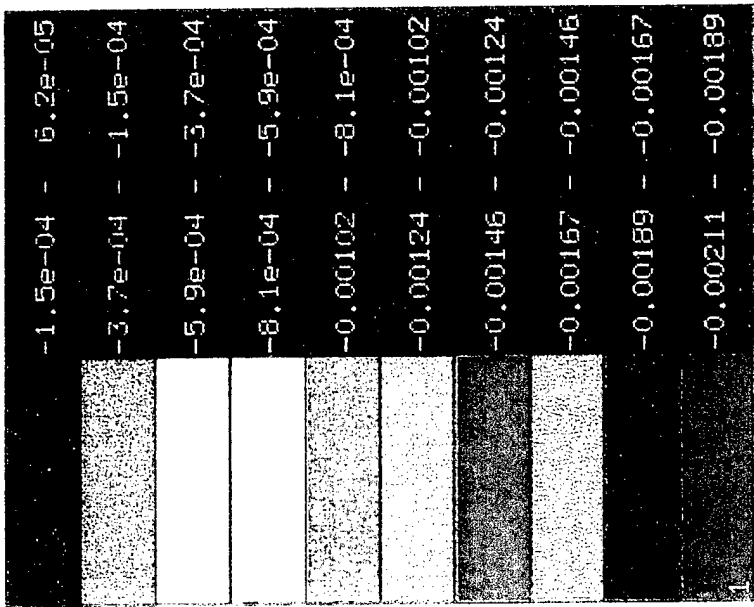


Fig 35. Vortical Flow over the Vertical Tails for the Engine-on Case



1st BENDING

Fig 36. Strain Intensity on the Vertical Tail for the First Bending Mode

0.00463	-	0.00543
0.00383	-	0.00463
0.00302	-	0.00383
0.00222	-	0.00302
0.00142	-	0.00222
6.1e-04	-	0.00142
-1.9e-04	-	6.1e-04
-0.00099	-	-1.9e-04
-0.00180	-	-0.00099
-0.00260	-	-0.00180

Strain Intensity

TORSION

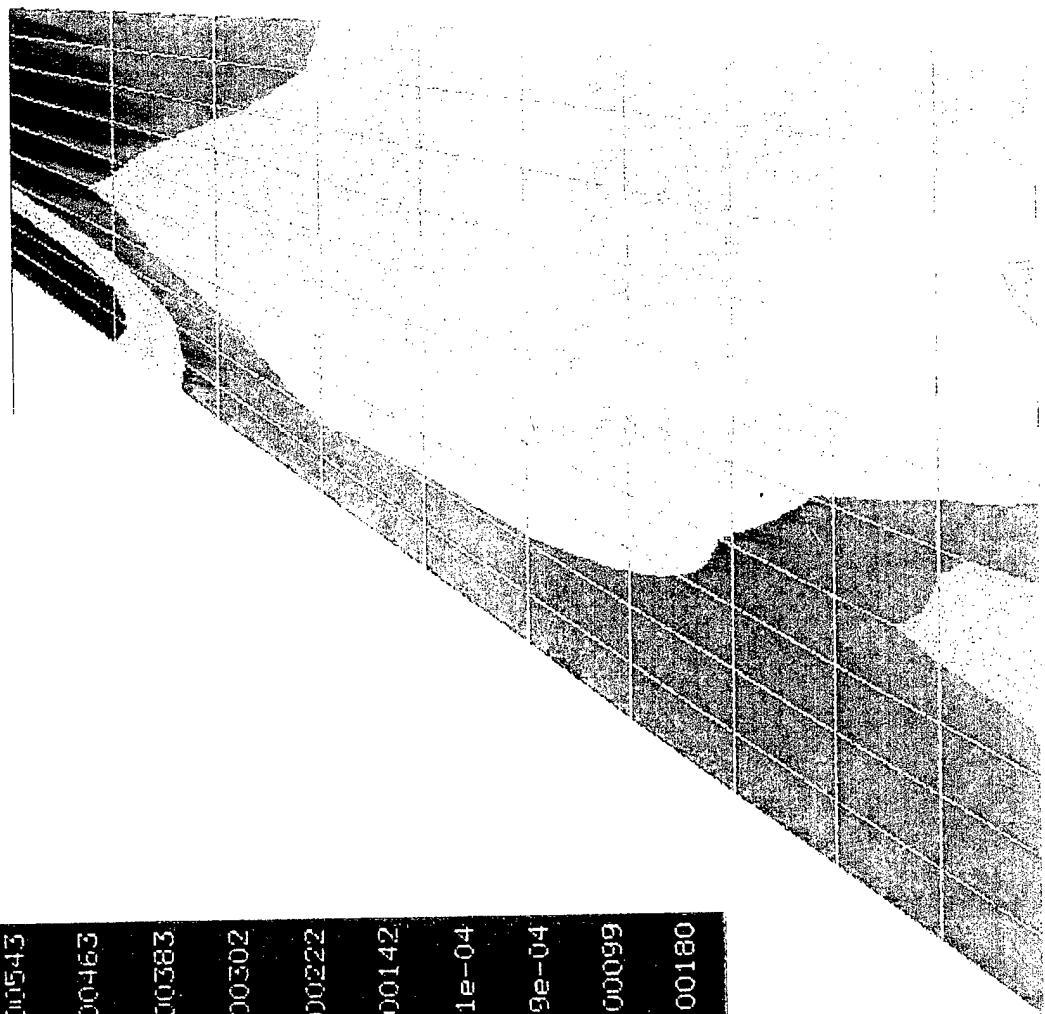


Fig 37. Strain Intensity on the Vertical Tail for the First Torsion Mode

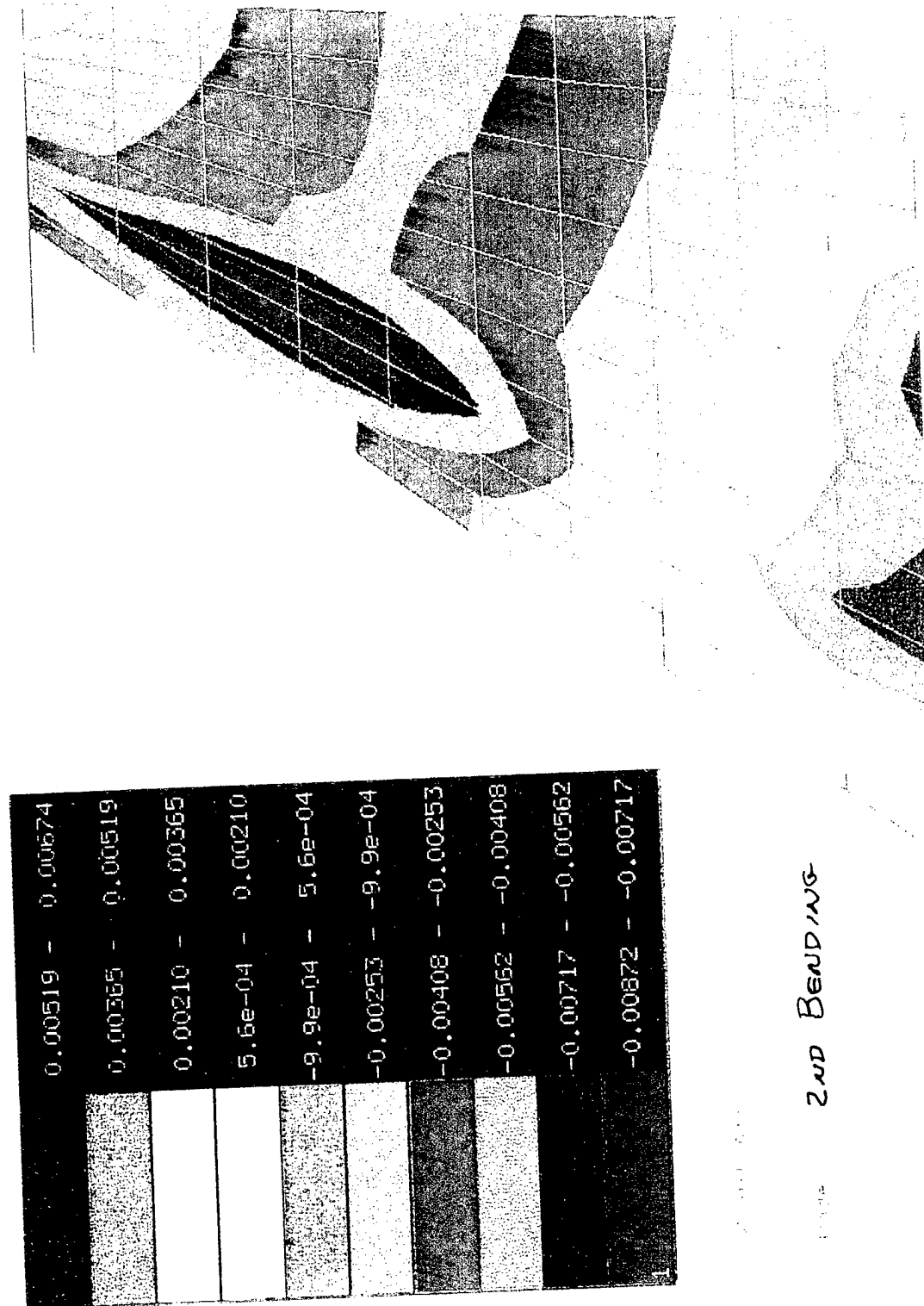


Fig 38. Strain Intensity on the Vertical Tail for the Second Bending Mode











F-15 Vertical Tail Buffet Test: RMS (in-lbs) & Peak PSD (in-lbs\*\*2/Hz)

1st Bending: 35-65 Hz

S1-BENDING: No Blowing Pressure

Beta	Alpha	rms	peak	freq
-4	20	.4719	3.268E-02	49.4
-4	22	.6473	4.857E-02	50.0
-4	24	.8462	1.104E-01	48.2
-4	28	1.1270	2.024E-01	48.2
-4	32	1.5490	3.856E-01	48.8
0	20	.4131	2.155E-02	50.0
0	22	.5085	3.832E-02	50.0
0	24	.6262	4.925E-02	48.8
0	28	1.0190	1.584E-01	48.2
0	32	1.6110	5.005E-01	47.6
4	20	.2885	8.435E-03	50.7
4	22	.4207	2.526E-02	50.7
4	24	.6123	6.338E-02	50.7
4	28	.9290	1.363E-01	50.0
4	32	1.3960	3.659E-01	48.8

Wing Blowing Pressure

B.P.	Beta	Alpha	rms	peak	freq
45	-4	32	1.5620	4.819E-01	51.3
45	0	24	.6672	6.118E-02	51.3
65	0	24	.6224	4.609E-02	47.0
45	0	32	1.5644	4.996E-01	51.3
45	4	32	1.5402	3.871E-01	50.0

1st Torsion: 180-210 Hz

S2-TORSION: No Blowing Pressure

Beta	Alpha	rms	peak	freq
-4	20	.5690	2.721E-02	190.4
-4	22	.6756	3.987E-02	191.0
-4	24	.5643	2.557E-02	191.6
-4	28	.2354	4.128E-03	194.7
-4	32	.2240	4.622E-03	193.5
0	20	.3817	1.632E-02	190.4
0	22	.5708	3.368E-02	189.8
0	24	.7279	5.535E-02	191.0
0	28	.4221	1.556E-02	191.0
0	32	.2695	5.935E-03	193.5
4	20	.2140	4.036E-03	192.3
4	22	.3882	1.423E-02	191.6
4	24	.6070	3.559E-02	193.5
4	28	.7277	4.453E-02	192.9
4	32	.3947	1.381E-02	195.3

Wing Blowing Pressure

B.P.	Beta	Alpha	rms	peak	freq
45	-4	32	.2372	5.284E-03	204.5
45	0	24	.6712	5.378E-02	201.4
65	0	24	.6099	3.122E-02	187.4
45	0	32	.3151	1.124E-02	205.7
45	4	32	.4154	2.289E-02	204.5

2nd Bending: 210-240 Hz

S1-BENDING: No Blowing Pressure

Beta	Alpha	rms	peak	freq
-4	20	.3241	6.926E-03	230.1
-4	22	.3698	9.630E-03	226.4
-4	24	.3158	7.514E-03	227.1
-4	28	.4941	1.790E-03	227.7
-4	32	.3532	9.624E-03	227.1
0	20	.2478	4.503E-03	228.9
0	22	.3145	6.206E-03	228.9
0	24	.3090	5.511E-03	228.9
0	28	.4908	1.687E-02	228.9
0	32	.4465	1.303E-02	231.3
4	20	.1100	8.259E-04	229.5
4	22	.1812	2.647E-03	232.5
4	24	.2640	5.177E-03	231.9
4	28	.3367	9.148E-03	233.2
4	32	.5290	1.955E-02	228.3

Wing Blowing Pressure

B.P.	Beta	Alpha	rms	peak	freq
45	-4	32	.3313	1.299E-02	237.4
45	0	24	.3143	8.208E-03	232.5
65	0	24	.3136	7.744E-03	216.7
45	0	32	.3797	1.529E-02	239.3
45	4	32	.4909	2.343E-02	236.8

Table 5. Additional Data for Different Test Conditions

# COMPARISON OF ANALYSIS AND TEST

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<u>Coefficient</u>	<u>Computation</u>	<u>Test</u>
Lift	1.30	1.29
Side Force	0.039	0.051
Drag	0.582	0.824
Pitching Moment	-0.173	-0.186
Yawing Moment	0.005	0.003
Rolling Moment	-0.008	0.011

Conditions:  $M=0.2$ , 24 deg angle of attack, & -4 deg sideslip

Table 6. Comparison of Analysis and Test

Table 7. Vertical Tail Pressure Comparisons (Flow Through Inlet Computations to Wind Tunnel Test)

Gauge	Test Pressure psi	Computational Pressure psi	Percentage Difference	Test Pressure Coefficient	Computational Pressure Coefficient	Percentage Difference	Within Experimental Uncertainty
<b>Right Inner</b>							
K147 2	13.436	13.620	1.4	-0.725	-0.251	-65.4	*
K148 3	13.576	13.620	0.3	-0.365	-0.251	-31.3	*
K149 4	13.400	13.643	1.8	-0.817	-0.194	-76.3	*
K145 5	13.480	13.668	1.4	-0.612	-0.127	-79.2	*
K150 6	13.555	13.644	0.7	-0.419	-0.189	-54.8	*
<b>Right Outer</b>							
K152 2	13.524	13.525	0.0	-0.499	-0.497	-0.3	*
K153 3	13.533	13.567	0.2	-0.475	-0.389	-18.1	*
K154 4	13.404	13.571	1.2	-0.807	-0.377	-53.3	*
K151 5	13.224	13.591	2.8	-1.269	-0.323	-74.3	*
K155 6	13.454	13.603	1.1	-0.678	-0.296	-56.4	*
<b>Left Inner</b>							
K122 1	13.656	13.624	-0.2	-0.159	-0.242	52.1	*
K121 2	13.604	13.602	0.0	-0.293	-0.298	1.8	*
K115 3	13.601	13.576	-0.2	-0.301	-0.365	21.3	*
K119 4	13.541	13.579	0.3	-0.455	-0.358	-21.3	*
K114 5	13.533	13.581	0.4	-0.475	-0.352	-25.9	*
K113 6	13.622	13.617	0.0	-0.247	-0.260	5.3	*
<b>Left Outer</b>							
K144 1	13.545	13.562	0.1	-0.445	-0.402	-9.6	*
K143 2	13.591	13.586	0.0	-0.326	-0.340	4.3	*
K120 3	13.629	13.627	0.0	-0.229	-0.233	1.9	*
K117 4	13.641	13.677	0.3	-0.198	-0.105	-47.1	*
K142 5	13.596	13.644	0.4	-0.314	-0.191	-39.0	*
K118 6	13.653	13.640	-0.1	-0.167	-0.200	20.0	*

Table 7. Vertical Tail Static Pressure Comparison